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# Fanuc Robot M-10iA/10S

Short arm version – Payload up to 10 kg, reach 1098 mm



The M-10iA/10S is FANUC Robotics' latest-generation, six-axis, high performance industrial robot. This small but mighty robot only weighs 130 kg but provides 10 kg payload with the highest wrist moments and inertia in its class. Dress-out and routing of cables and airlines have been greatly simplified with a 50-mm hollow wrist and upper arm, helping to reduce system cost and improving reliability. The M-10iA/10S can be floor or wall mounted at any angle, or ceiling mounted. J3 can also flip over allowing the robot to work behind itself creating a very large work envelope. Along with FANUC's integrated vision package in the controller called iRVision™, the M-10iA/10S comes vision ready with a 2D vision cable integrated through the robot arm as a standard option.

The robot M-10iA/10S has the highest axis speeds and the best repeatability in its class, making for an extremely fast and highly repeatable robot. The M-10iA/10S is setting

the industry standard for small robots and is the perfect solution for your application.

## M-10iA Series, the solution for:

- Painting and dispensing
- Material handling
- Material removal
- Assembly
- Picking and packing

## Features and benefits:

- 6 degrees of freedom
- ± 0.05 mm repeatability
- 10 kg payload at wrist
- Large wrist moments and inertia for real-world IC/GTs and workpieces
- Supplementary payload mount on J3 casting
- 2D vision cables from J1 to J3 as a standard option
- Compact size, slim wrist, and small footprint permit operation in tight work spaces
- Robot can be floor, angle, wall or ceiling mounted
- High joint speeds maximize throughput
- Absolute encoder positioning eliminates homing at power-up
- Intelligent colourgraphic teach pendant is network ready
- Built-in solution arm, 50mm hollow wrist and upper arm

## Reliability

- RV reducer, gear and harmonic drivetrains provide rigidity and performance in a compact package
- Sealed bearings and brushless, maintenance-free AC motors provide protection and improve reliability

## Robot and Controller Options

- iRVision for guidance and inspection
- Up to 40 axes (robot + auxiliary) on same controller
- Extended communications capabilities: FTP, ProNet, FANUC Model A I/O rack, etc.
- Linear or circular conveyor tracking
- Many unique robot and application-driven software options available

# Fanuc Robot M10ia Maintenance Manual

**Ying-Ying Zheng**



## **Fanuc Robot M10ia Maintenance Manual:**

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add this url to your eclipse installation to reach this solution s update site emf compare brings model comparison to the emf framework this tool provides generic support for any kind of metamodel in order to compare and merge models the objectives of this component are to provide a stable and efficient generic implementation of model

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emf the core emf framework includes a meta model.ecore for describing models and runtime support for the models including change notification persistence support with default xmi serialization and a very efficient reflective api for manipulating emf objects generically

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the cdo connected data objects model repository is a distributed shared model framework for emf models and meta models cdo is also a model runtime environment with a focus on orthogonal aspects like model scalability transactionality persistence distribution queries and more cdo has a 3 tier architecture supporting emf based client

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the eclipse modeling framework project is a modeling framework and code generation facility for building tools and other applications based on a structured data model from a model specification described in xmi emf provides tools and runtime support to produce a set of java classes for the model along with a set of adapter classes that

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