#### Problem 1.13

$$\mathbf{A} = (x - x') \hat{\mathbf{x}} + (y - y') \hat{\mathbf{y}} + (z - z') \hat{\mathbf{z}}; \quad \hat{\mathbf{x}} = \sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}.$$

$$(a) \nabla (\Phi^2) = \mathcal{L}[(x-x')^2 + (y-y')^2 + (z-z')^2] + \mathcal{L}() + \mathcal{$$

(b) 
$$\nabla (\frac{1}{2}) = \frac{\partial}{\partial z} [(x - x')^2 + (y - y')^2 + (z - z')^2]^{-\frac{1}{2}} \hat{\mathbf{x}} + \frac{\partial}{\partial z} ()^{-\frac{1}{2}} \hat{\mathbf{y}} + \frac{\partial}{\partial z} ()^{-\frac{1}{2}} \hat{\mathbf{z}} = -\frac{1}{2} ()^{-\frac{3}{2}} 2(x - x') \hat{\mathbf{x}} - \frac{1}{2} ()^{-\frac{3}{2}} 2(y - y') \hat{\mathbf{y}} - \frac{1}{2} ()^{-\frac{3}{2}} 2(z - z') \hat{\mathbf{z}} = -()^{-\frac{3}{2}} [(x - x') \hat{\mathbf{x}} + (y - y') \hat{\mathbf{y}} + (z - z') \hat{\mathbf{z}}] = -(1/4^{-2}) \hat{\mathbf{x}} = -(1/4^{-2}) \hat{\mathbf{x}}.$$

(c) 
$$\frac{\partial}{\partial x}(\mathbf{4}^{-n}) = n \cdot \mathbf{4}^{-n-1} \cdot \frac{\partial \cdot \mathbf{4}}{\partial x} = n \cdot \mathbf{4}^{-n-1} \cdot (\frac{1}{2} \cdot \frac{1}{4} \cdot 2 \cdot \mathbf{4}^{-x}) = n \cdot \mathbf{4}^{-n-1} \cdot \mathbf{4}^{-x}$$
, so  $\nabla (\mathbf{4}^{-n}) = n \cdot \mathbf{4}^{-n-1} \cdot \mathbf{4}^{-x}$ 

#### Problem 1.14

$$\bar{y} = +y \cos \phi + z \sin \phi$$
; multiply by  $\sin \phi$ ;  $\bar{y} \sin \phi = +y \sin \phi \cos \phi + z \sin^2 \phi$ .

$$\mathbb{T} = -y \sin \phi + z \cos \phi$$
; multiply by  $\cos \phi$ ;  $\mathbb{T} \cos \phi = -y \sin \phi \cos \phi + z \cos^2 \phi$ .

Add: 
$$\overline{y} \sin \phi + T \cos \phi = z(\sin^2 \phi + \cos^2 \phi) = z$$
. Likewise,  $\overline{y} \cos \phi - T \sin \phi = y$ .

So 
$$\frac{\partial h}{\partial t} = \cos \phi$$
;  $\frac{\partial h}{\partial t} = -\sin \phi$ ;  $\frac{\partial h}{\partial t} = \sin \phi$ ;  $\frac{\partial h}{\partial t} = \cos \phi$ . Therefore

$$\frac{\overline{(\boldsymbol{\nabla} f)}_y = \frac{\partial f}{\partial \boldsymbol{Q}} = \frac{\partial f}{\partial \boldsymbol{Q}} \frac{\partial \boldsymbol{Q}}{\partial \boldsymbol{Q}} + \frac{\partial f}{\partial \boldsymbol{Q}} \frac{\partial \boldsymbol{Q}}{\partial \boldsymbol{Q}} = +\cos\phi(\boldsymbol{\nabla} f)_y + \sin\phi(\boldsymbol{\nabla} f)_z}{\overline{(\boldsymbol{\nabla} f)}_z = \frac{\partial f}{\partial \boldsymbol{Q}} = \frac{\partial f}{\partial \boldsymbol{Q}} \frac{\partial \boldsymbol{Q}}{\partial \boldsymbol{Q}} + \frac{\partial f}{\partial \boldsymbol{Q}} \frac{\partial \boldsymbol{Q}}{\partial \boldsymbol{Q}} = -\sin\phi(\boldsymbol{\nabla} f)_y + \cos\phi(\boldsymbol{\nabla} f)_z} \right\} \text{ So } \boldsymbol{\nabla} f \text{ transforms as a vector.} \quad \text{ qed}$$

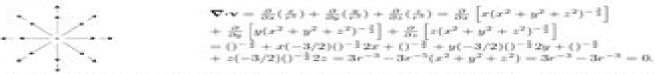
#### Problem 1.15

$$(a)\nabla \cdot \mathbf{v}_{\alpha} = \frac{\partial}{\partial x}(x^2) + \frac{\partial}{\partial y}(3xz^2) + \frac{\partial}{\partial z}(-2xz) = 2x + 0 - 2x = 0.$$

$$(b)\nabla \cdot \mathbf{v}_b = \frac{\partial}{\partial x}(xy) + \frac{\partial}{\partial y}(2yz) + \frac{\partial}{\partial z}(3xz) = y + 2z + 3x.$$

$$(c)\nabla \cdot \mathbf{v}_{\tau} = \frac{\partial}{\partial x}(y^2) + \frac{\partial}{\partial x}(2xy + z^2) + \frac{\partial}{\partial x}(2yz) = 0 + (2x) + (2y) = 2(x + y)$$

#### Problem 1.16



This conclusion is surprising, because, from the diagram, this vector field is obviously diverging away from the origin. How, then, can  $\nabla \cdot \mathbf{v} = 0$ ? The answer is that  $\nabla \cdot \mathbf{v} = 0$  everywhere except at the origin, but at the origin our calculation is no good, since r = 0, and the expression for  $\mathbf{v}$  blows up. In fact,  $\nabla \cdot \mathbf{v}$  is infinite at that one point, and zero elsewhere, as we shall see in Sect. 1.5.

#### Problem 1.17

$$v_y = \cos\phi v_y + \sin\phi v_z$$
;  $v_z = -\sin\phi v_y + \cos\phi v_z$ .  
 $\frac{\partial v_z}{\partial y} = \frac{\partial v_z}{\partial y} \cos\phi + \frac{\partial v_z}{\partial y} \sin\phi = \left(\frac{\partial v_z}{\partial y} \frac{\partial y}{\partial z} + \frac{\partial v_z}{\partial z} \frac{\partial z}{\partial y}\right) \cos\phi + \left(\frac{\partial v_z}{\partial y} \frac{\partial y}{\partial z} + \frac{\partial v_z}{\partial z} \frac{\partial z}{\partial y}\right) \sin\phi$ . Use result in Prob. 1.14:  
 $= \left(\frac{\partial v_z}{\partial y} \cos\phi + \frac{\partial v_z}{\partial z} \sin\phi\right) \cos\phi + \left(\frac{\partial v_z}{\partial y} \cos\phi + \frac{\partial v_z}{\partial z} \sin\phi\right) \sin\phi$ .  
 $\frac{\partial v_z}{\partial z} = -\frac{\partial v_z}{\partial z} \sin\phi + \frac{\partial v_z}{\partial z} \cos\phi = -\left(\frac{\partial v_z}{\partial y} \frac{\partial z}{\partial z} + \frac{\partial v_z}{\partial z} \frac{\partial z}{\partial z}\right) \sin\phi + \left(\frac{\partial v_z}{\partial y} \frac{\partial z}{\partial z} + \frac{\partial v_z}{\partial z} \frac{\partial z}{\partial z}\right) \cos\phi$   
 $= -\left(-\frac{\partial v_z}{\partial z} \sin\phi + \frac{\partial v_z}{\partial z} \cos\phi\right) \sin\phi + \left(-\frac{\partial v_z}{\partial z} \sin\phi + \frac{\partial v_z}{\partial z} \cos\phi\right) \cos\phi$ . So

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