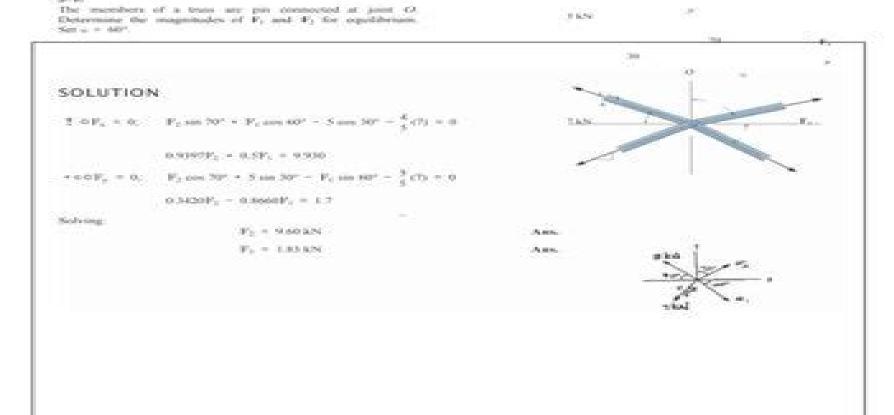
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readers with a mathematics background The book has been designed to accompany senior and graduate students enrolled in a simulation class but it may also serve as a reference and self study guide for modeling and simulation practitioners

Dynamics of Parallel Robots Stefan Staicu, 2018-09-14 This book establishes recursive relations concerning kinematics and dynamics of constrained robotic systems It uses matrix modeling to determine the connectivity conditions on the relative velocities and accelerations in order to compare two efficient energetic ways in dynamics modeling the principle of virtual work and the formalism of Lagrange's equations First a brief fundamental theory is presented on matrix mechanics of the rigid body which is then developed in the following five chapters treating matrix kinematics of the rigid body matrix kinematics of the composed motion kinetics of the rigid body dynamics of the rigid body and analytical mechanics By using a set of successive mobile frames the geometrical properties and the kinematics of the vector system of velocities and accelerations for each element of the robot are analysed The dynamics problem is solved in two energetic ways using an approach based on the principle of virtual work and applying the formalism of Lagrange's equations of the second kind These are shown to be useful for real time control of the robot s evolution. Then the recursive matrix method is applied to the kinematics and dynamics analysis of five distinct case studies planar parallel manipulators spatial parallel robots planetary gear trains mobile wheeled robots and finally two module hybrid parallel robots **Distributed Transfer Function Method** Bingen Yang, Kyoungrae Noh, 2023-10-04 The distributed transfer function method DTFM is an analytical method for modeling analysis and control of a class of distributed parameter systems that are governed by partial differential equations and that can be defined over multiple interconnected subregions In this comprehensive reference the authors show how the DTFM delivers highly accurate analytical solutions in both the frequency domain and the time domain while offering a versatile modeling technique for various problems in mechanical civil aerospace electrical chemical biomechanical and vehicle engineering Theory of Gyroscopic Effects for Rotating Objects Ryspek Usubamatov, 2022-06-30 This book highlights an analytical solution for the dynamics of axially rotating objects It also presents the theory of gyroscopic effects explaining their physics and using mathematical models of Euler's form for the motion of movable spinning objects to demonstrate these effects The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and Coriolis forces as well as the change in the angular momentum The interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the principle of mechanical energy conservation These kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc Lastly the mathematical models for the gyroscopic effects are validated by practical tests. The 2nd edition became necessary due to new development and corrections of mathematical expressions It contains new chapters about the Tippe top inversion and inversion of the spinning object in an

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Essentials of Dynamics and Vibrations John Billingsley,2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler s equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects

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