Solutions to Problems in Goldstein, Classical Mechanics, Second Edition

Homer Reid

December 1, 2001

Chapter 3

Problem 3.1

A particle of mass m is constrained to move under gravity without friction on the inside of a paraboloid of revolution whose axis is vertical. Find the one-dimensional problem equivalent to its motion. What is the condition on the particle's initial velocity to produce circular motion? Find the period of small oscillations about this circular motion.

We'll take the paraboloid to be defined by the equation $z = \alpha r^2$. The kinetic and potential energies of the particle are

$$T = \frac{m}{2}(\hat{r}^2 + r^2\hat{\theta}^2 + \hat{z}^2)$$

= $\frac{m}{2}(\hat{r}^2 + r^2\hat{\theta}^2 + 4\alpha^2r^2\hat{r}^2)$
$$V = mgz = mg\alpha r^2.$$

Hence the Lagrangian is

$$L = \frac{m}{2}[(1 + 4\alpha^2r^2)\dot{r}^2 + r^2\dot{\theta}^2] - mg\alpha r^2.$$

This is cyclic in θ , so the angular momentum is conserved:

$$I = mr^2 \theta = constant.$$

Goldstein Classical Mechanics Solutions Chapter 3

Lauren Gardner

Goldstein Classical Mechanics Solutions Chapter 3:

Classical Relativistic Many-Body Dynamics M.A. Trump, W.C. Schieve, 2013-03-09 in this work we must therefore assume several abstract concepts that hardly need defending at this point in the history of mechanics Most notably these include the concept of the point particle and the concept of the inertial observer. The study of the relativistic particle system is undertaken here by means of a particular classical theory which also exists on the quantum level and which is especially suited to the many body system in flat spacetime In its fundamental postulates the theory may be considered to be primarily the work of E C G Stiickelberg in the 1940 s and of L P Horwitz and C Piron in the 1970 s who may be said to have provided the generalization of Stiickelberg's theory to the many body system. The references for these works may be found in Chapter 1 The theory itself may be legitimately called off shell Hamiltonian dynamics parameterized relativistic mechanics or even classical event dynamics. The most important feature of the theory is probably the use of an invariant world time parameter. usually denoted T which provides an evolution time for the system in such as way as to allow manifest co variance within a Hamiltonian formalism In general this parameter is neither a Lorentz frame time nor the proper time of the particles in the Integrability and Nonintegrability of Dynamical Systems Alain Goriely, 2001 This invaluable book examines qualitative and quantitative methods for nonlinear differential equations as well as integrability and nonintegrability theory Starting from the idea of a constant of motion for simple systems of differential equations it investigates the essence of integrability its geometrical relevance and dynamical consequences Integrability theory is approached from different perspectives first in terms of differential algebra then in terms of complex time singularities and finally from the viewpoint of phase geometry for both Hamiltonian and non Hamiltonian systems As generic systems of differential equations cannot be exactly solved the book reviews the different notions of nonintegrability and shows how to prove the nonexistence of exact solutions and or a constant of motion Finally nonintegrability theory is linked to dynamical systems theory by showing how the property of complete integrability partial integrability or nonintegrability can be related to regular and irregular dynamics in phase space Supersymmetry In Quantum and Classical Mechanics Bijan Kumar Bagchi, 2000-09-21 Following Witten's remarkable discovery of the quantum mechanical scheme in which all the salient features of supersymmetry are embedded SCQM supersymmetric classical and quantum mechanics has become a separate area of research In recent years progress in this field has been dramatic and the literature continues to grow Until now no book has offered an overview of the subject with enough detail to allow readers to become rapidly familiar with its key ideas and methods Supersymmetry in Classical and Quantum Mechanics offers that overview and summarizes the major developments of the last 15 years It provides both an up to date review of the literature and a detailed exposition of the underlying SCQM principles For those just beginning in the field the author presents step by step details of most of the computations For more experienced readers the treatment includes systematic analyses of more advanced topics such as guasi and conditional

solvability and the role of supersymmetry in nonlinear systems Mathematical Analysis of Physical Problems Philip Russell Wallace, 1984-01-01 This mathematical reference for theoretical physics employs common techniques and concepts to link classical and modern physics It provides the necessary mathematics to solve most of the problems Topics include the vibrating string linear vector spaces the potential equation problems of diffusion and attenuation probability and stochastic processes and much more 1972 edition Classical Mechanics Govind S. Krishnaswami, 2025-08-31 This well rounded and self contained treatment of classical mechanics strikes a balance between examples concepts phenomena and formalism While addressed to graduate students and their teachers the minimal prerequisites and ground covered should make it useful also to undergraduates and researchers Starting with conceptual context physical principles guide the development Chapters are modular and the presentation is precise yet accessible with numerous remarks footnotes and problems enriching the learning experience Essentials such as Galilean and Newtonian mechanics the Kepler problem Lagrangian and Hamiltonian mechanics oscillations rigid bodies and motion in noninertial frames lead up to discussions of canonical transformations angle action variables Hamilton Jacobi and linear stability theory Bifurcations nonlinear and chaotic dynamics as well as the wave heat and fluid equations receive substantial coverage Techniques from linear algebra differential equations manifolds vector and tensor calculus groups Lie and Poisson algebras and symplectic and Riemannian geometry are gently introduced A dynamical systems viewpoint pervades the presentation A salient feature is that classical mechanics is viewed as part of the wider fabric of physics with connections to quantum thermal electromagnetic optical and relativistic physics highlighted Thus this book will also be useful in allied areas and serve as a stepping stone for embarking on research DOFL Technical Flexible Robot Dynamics and Controls Rush D. Robinett III, John Feddema, G. Richard Eisler, Clark Review ,1957 Dohrmann, Gordon G. Parker, David G. Wilson, Dennis Stokes, 2012-12-06 This book is the result of over ten 10 years of research and development in flexible robots and structures at Sandia National Laboratories The authors de cided to collect this wealth of knowledge into a set of viewgraphs in order to teach a graduate class in Flexible Robot Dynamics and Controls within the Mechanical En gineering Department at the University of New Mexico UNM These viewgraphs encouragement from several students and many late nights have produced a book that should provide an upper level undergraduate and graduate textbook and a reference for experienced professionals. The content of this book spans several disciplines including structural dynam ics system identification optimization and linear digital and nonlinear control theory which are developed from several points of view including electrical me chanical and aerospace engineering as well as engineering mechanics As a result the authors believe that this book demonstrates the value of solid applied theory when developing hardware solutions to real world problems The reader will find many real world applications in this book and will be shown the applicability of these techniques beyond flexible structures which in turn shows the value of mul tidisciplinary education and teaming International Young Physicists' Tournament: Problems And Solutions 2015 Sihui Wang, Wenli Gao, 2018-01-05

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