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Henry Hexmoor

Essential Principles for Autonomous Robotics

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Essential Principles For Autonomous Robotics Henry Hexmoor

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Essential Principles For Autonomous Robotics Henry Hexmoor:

    Essential Principles for Autonomous Robotics Henry Hexmoor,2013-06-01 From driving flying and swimming to digging for unknown objects in space exploration autonomous robots take on varied shapes and sizes In part autonomous robots are designed to perform tasks that are too dirty dull or dangerous for humans With nontrivial autonomy and volition they may soon claim their own place in human society These robots will be our allies as we strive for understanding our natural and man made environments and build positive synergies around us Although we may never perfect replication of biological capabilities in robots we must harness the inevitable emergence of robots that synchronizes with our own capacities to live learn and grow This book is a snapshot of motivations and methodologies for our collective attempts to transform our lives and enable us to cohabit with robots that work with and for us It reviews and guides the reader to seminal and continual developments that are the foundations for successful paradigms It attempts to demystify the abilities and limitations of robots It is a progress report on the continuing work that will fuel future endeavors Table of Contents Part I Preliminaries Agency Motion and Anatomy Behaviors Architectures Affect Sensors Manipulators Part II Mobility Potential Fields Roadmaps Reactive Navigation Multi Robot Mapping Brick and Mortar Strategy Part III State of the Art Multi Robotics Phenomena Human Robot Interaction Fuzzy Control Decision Theory and Game Theory Part IV On the Horizon Applications Macro and Micro Robots References Author Biography Discussion   Essential Principles for Autonomous Robotics Henry Hexmoor,2022-05-31 From driving flying and swimming to digging for unknown objects in space exploration autonomous robots take on varied shapes and sizes In part autonomous robots are designed to perform tasks that are too dirty dull or dangerous for humans With nontrivial autonomy and volition they may soon claim their own place in human society These robots will be our allies as we strive for understanding our natural and man made environments and build positive synergies around us Although we may never perfect replication of biological capabilities in robots we must harness the inevitable emergence of robots that synchronizes with our own capacities to live learn and grow This book is a snapshot of motivations and methodologies for our collective attempts to transform our lives and enable us to cohabit with robots that work with and for us It reviews and guides the reader to seminal and continual developments that are the foundations for successful paradigms It attempts to demystify the abilities and limitations of robots It is a progress report on the continuing work that will fuel future endeavors Table of Contents Part I Preliminaries Agency Motion and Anatomy Behaviors Architectures Affect Sensors Manipulators Part II Mobility Potential Fields Roadmaps Reactive Navigation Multi Robot Mapping Brick and Mortar Strategy Part III State of the Art Multi Robotics Phenomena Human Robot Interaction Fuzzy Control Decision Theory and Game Theory Part IV On the Horizon Applications Macro and Micro Robots References Author Biography Discussion

    Intelligent Moving Cities: Technological Leap and Social Integration of Autonomous Mobile Robots Minje Choi,Seungjae Lee,2025-08-25 The book Intelligence Moving Cities methodically unveils the multifaceted impacts of

autonomous mobile robots on urban environments Through seven insightful chapters readers are taken on a journey from the historical developments in robotics to cutting edge applications that promise a more livable safe and efficient cityscape From navigation systems and design tailored specifically for urban settings to their integration into daily activities this book provides a comprehensive look at the technological advancements that are transforming our public spaces Each chapter delves deep into critical aspects of urban autonomous robotics the societal and technological drivers the evolution of robotics core technologies of navigation and mobility design and scalability of urban use robots and their diverse applications ranging from public safety to personal mobility and logistics Furthermore it addresses the broader implications of deploying these technologies in urban settings including urban planning pedestrian safety and the overall enhancement of city life Targeted at technologists urban planners policymakers and academics Intelligence Moving Cities is not merely a technical recount but a profound statement on the intersection of technology urban planning and social integration It offers practical examples case studies and forward looking analyses making it an indispensable resource for anyone committed to the future of urban development Explore the transformative potential of autonomous robotics in creating more accessible efficient and people oriented urban environments with Intelligence Moving Cities Join the movement toward revolutionizing city life ensuring a sustainable inclusive and thriving future for urban landscapes   *Robot Learning from Human Teachers* Sonia Chernova,Andrea L. Thomaz,2022-06-01 Learning from Demonstration LfD explores techniques for learning a task policy from examples provided by a human teacher The field of LfD has grown into an extensive body of literature over the past 30 years with a wide variety of approaches for encoding human demonstrations and modeling skills and tasks Additionally we have recently seen a focus on gathering data from non expert human teachers i e domain experts but not robotics experts In this book we provide an introduction to the field with a focus on the unique technical challenges associated with designing robots that learn from naive human teachers We begin in the introduction with a unification of the various terminology seen in the literature as well as an outline of the design choices one has in designing an LfD system Chapter 2 gives a brief survey of the psychology literature that provides insights from human social learning that are relevant to designing robotic social learners Chapter 3 walks through an LfD interaction surveying the design choices one makes and state of the art approaches in prior work First is the choice of input how the human teacher interacts with the robot to provide demonstrations Next is the choice of modeling technique Currently there is a dichotomy in the field between approaches that model low level motor skills and those that model high level tasks composed of primitive actions We devote a chapter to each of these Chapter 7 is devoted to interactive and active learning approaches that allow the robot to refine an existing task model And finally Chapter 8 provides best practices for evaluation of LfD systems with a focus on how to approach experiments with human subjects in this domain   **Learning and Decision-Making from Rank Data** Lirong Xia,2022-06-01 The ubiquitous challenge of learning and decision making from rank data arises in situations where intelligent systems collect preference

and behavior data from humans learn from the data and then use the data to help humans make efficient effective and timely decisions Often such data are represented by rankings This book surveys some recent progress toward addressing the challenge from the considerations of statistics computation and socio economics We will cover classical statistical models for rank data including random utility models distance based models and mixture models We will discuss and compare classical and state of the art algorithms such as algorithms based on Minorize Majorization MM Expectation Maximization EM Generalized Method of Moments GMM rank breaking and tensor decomposition We will also introduce principled Bayesian preference elicitation frameworks for collecting rank data Finally we will examine socio economic aspects of statistically desirable decision making mechanisms such as Bayesian estimators This book can be useful in three ways 1 for theoreticians in statistics and machine learning to better understand the considerations and caveats of learning from rank data compared to learning from other types of data especially cardinal data 2 for practitioners to apply algorithms covered by the book for sampling learning and aggregation and 3 as a textbook for graduate students or advanced undergraduate students to learn about the field This book requires that the reader has basic knowledge in probability statistics and algorithms Knowledge in social choice would also help but is not required   **Lifelong Machine Learning, Second Edition** Zhiyuan Chen,Bing Liu,2022-06-01 Lifelong Machine Learning Second Edition is an introduction to an advanced machine learning paradigm that continuously learns by accumulating past knowledge that it then uses in future learning and problem solving In contrast the current dominant machine learning paradigm learns in isolation given a training dataset it runs a machine learning algorithm on the dataset to produce a model that is then used in its intended application It makes no attempt to retain the learned knowledge and use it in subsequent learning Unlike this isolated system humans learn effectively with only a few examples precisely because our learning is very knowledge driven the knowledge learned in the past helps us learn new things with little data or effort Lifelong learning aims to emulate this capability because without it an AI system cannot be considered truly intelligent Research in lifelong learning has developed significantly in the relatively short time since the first edition of this book was published The purpose of this second edition is to expand the definition of lifelong learning update the content of several chapters and add a new chapter about continual learning in deep neural networks which has been actively researched over the past two or three years A few chapters have also been reorganized to make each of them more coherent for the reader Moreover the authors want to propose a unified framework for the research area Currently there are several research topics in machine learning that are closely related to lifelong learning most notably multi task learning transfer learning and meta learning because they also employ the idea of knowledge sharing and transfer This book brings all these topics under one roof and discusses their similarities and differences Its goal is to introduce this emerging machine learning paradigm and present a comprehensive survey and review of the important research results and latest ideas in the area This book is thus suitable for students researchers and practitioners who are interested in machine learning data mining natural

language processing or pattern recognition Lecturers can readily use the book for courses in any of these related fields

    Strategic Voting Reshef Meir,2022-05-31 Social choice theory deals with aggregating the preferences of multiple individuals regarding several available alternatives a situation colloquially known as voting There are many different voting rules in use and even more in the literature owing to the various considerations such an aggregation method should take into account The analysis of voting scenarios becomes particularly challenging in the presence of strategic voters that is voters that misreport their true preferences in an attempt to obtain a more favorable outcome In a world that is tightly connected by the Internet where multiple groups with complex incentives make frequent joint decisions the interest in strategic voting exceeds the scope of political science and is a focus of research in economics game theory sociology mathematics and computer science The book has two parts The first part asks are there voting rules that are truthful in the sense that all voters have an incentive to report their true preferences The seminal Gibbard Satterthwaite theorem excludes the existence of such voting rules under certain requirements From this starting point we survey both extensions of the theorem and various conditions under which truthful voting is made possible such as restricted preference domains We also explore the connections with other problems of mechanism design such as locating a facility that serves multiple users In the second part we ask what would be the outcome when voters do vote strategically rather than trying to prevent such behavior We overview various game theoretic models and equilibrium concepts from the literature demonstrate how they apply to voting games and discuss their implications on social welfare We conclude with a brief survey of empirical and experimental findings that could play a key role in future development of game theoretic voting models   *Reasoning with Probabilistic and Deterministic Graphical Models* Rina Dechter,2019-02-14 Graphical models e g Bayesian and constraint networks influence diagrams and Markov decision processes have become a central paradigm for knowledge representation and reasoning in both artificial intelligence and computer science in general These models are used to perform many reasoning tasks such as scheduling planning and learning diagnosis and prediction design hardware and software verification and bioinformatics These problems can be stated as the formal tasks of constraint satisfaction and satisfiability combinatorial optimization and probabilistic inference It is well known that the tasks are computationally hard but research during the past three decades has yielded a variety of principles and techniques that significantly advanced the state of the art This book provides comprehensive coverage of the primary exact algorithms for reasoning with such models The main feature exploited by the algorithms is the model s graph We present inference based message passing schemes e g variable elimination and search based conditioning schemes e g cycle cutset conditioning and AND OR search Each class possesses distinguished characteristics and in particular has different time vs space behavior We emphasize the dependence of both schemes on few graph parameters such as the treewidth cycle cutset and the pseudo tree height The new edition includes the notion of influence diagrams which focus on sequential decision making under uncertainty We believe the principles outlined in the

book would serve well in moving forward to approximation and anytime based schemes The target audience of this book is researchers and students in the artificial intelligence and machine learning area and beyond   Game Theory for Data Science Boi Faltings,Goran Radanovic,2022-05-31 Intelligent systems often depend on data provided by information agents for example sensor data or crowdsourced human computation Providing accurate and relevant data requires costly effort that agents may not always be willing to provide Thus it becomes important not only to verify the correctness of data but also to provide incentives so that agents that provide high quality data are rewarded while those that do not are discouraged by low rewards We cover different settings and the assumptions they admit including sensing human computation peer grading reviews and predictions We survey different incentive mechanisms including proper scoring rules prediction markets and peer prediction Bayesian Truth Serum Peer Truth Serum Correlated Agreement and the settings where each of them would be suitable As an alternative we also consider reputation mechanisms We complement the game theoretic analysis with practical examples of applications in prediction platforms community sensing and peer grading   *Explainable Human-AI Interaction* Sarath Sreedharan,Anagha Kulkarni,Subbarao Kambhampati,2022-01-24 From its inception artificial intelligence AI has had a rather ambivalent relationship with humans swinging between their augmentation and replacement Now as AI technologies enter our everyday lives at an ever increasing pace there is a greater need for AI systems to work synergistically with humans One critical requirement for such synergistic human AI interaction is that the AI systems behavior be explainable to the humans in the loop To do this effectively AI agents need to go beyond planning with their own models of the world and take into account the mental model of the human in the loop At a minimum AI agents need approximations of the human s task and goal models as well as the human s model of the AI agent s task and goal models The former will guide the agent to anticipate and manage the needs desires and attention of the humans in the loop and the latter allow it to act in ways that are interpretable to humans by conforming to their mental models of it and be ready to provide customized explanations when needed The authors draw from several years of research in their lab to discuss how an AI agent can use these mental models to either conform to human expectations or change those expectations through explanatory communication While the focus of the book is on cooperative scenarios it also covers how the same mental models can be used for obfuscation and deception The book also describes several real world application systems for collaborative decision making that are based on the framework and techniques developed here Although primarily driven by the authors own research in these areas every chapter will provide ample connections to relevant research from the wider literature The technical topics covered in the book are self contained and are accessible to readers with a basic background in AI   Positive Unlabeled Learning Kristen Jaskie,Andreas Spanias,2022-04-20 Machine learning and artificial intelligence AI are powerful tools that create predictive models extract information and help make complex decisions They do this by examining an enormous quantity of labeled training data to find patterns too complex for human observation However in

many real world applications well labeled data can be difficult expensive or even impossible to obtain In some cases such as when identifying rare objects like new archeological sites or secret enemy military facilities in satellite images acquiring labels could require months of trained human observers at incredible expense Other times as when attempting to predict disease infection during a pandemic such as COVID 19 reliable true labels may be nearly impossible to obtain early on due to lack of testing equipment or other factors In that scenario identifying even a small amount of truly negative data may be impossible due to the high false negative rate of available tests In such problems it is possible to label a small subset of data as belonging to the class of interest though it is impractical to manually label all data not of interest We are left with a small set of positive labeled data and a large set of unknown and unlabeled data Readers will explore this Positive and Unlabeled learning PU learning problem in depth The book rigorously defines the PU learning problem discusses several common assumptions that are frequently made about the problem and their implications and considers how to evaluate solutions for this problem before describing several of the most popular algorithms to solve this problem It explores several uses for PU learning including applications in biological medical business security and signal processing This book also provides high level summaries of several related learning problems such as one class classification anomaly detection and noisy learning and their relation to PU learning   **Introduction to Symbolic Plan and Goal Recognition** Reuth Mirsky,Sarah Keren,Christopher Geib,2022-05-31 Plan recognition activity recognition and goal recognition all involve making inferences about other actors based on observations of their interactions with the environment and other agents This synergistic area of research combines unites and makes use of techniques and research from a wide range of areas including user modeling machine vision automated planning intelligent user interfaces human computer interaction autonomous and multi agent systems natural language understanding and machine learning It plays a crucial role in a wide variety of applications including assistive technology software assistants computer and network security human robot collaboration natural language processing video games and many more This wide range of applications and disciplines has produced a wealth of ideas models tools and results in the recognition literature However it has also contributed to fragmentation in the field with researchers publishing relevant results in a wide spectrum of journals and conferences This book seeks to address this fragmentation by providing a high level introduction and historical overview of the plan and goal recognition literature It provides a description of the core elements that comprise these recognition problems and practical advice for modeling them In particular we define and distinguish the different recognition tasks We formalize the major approaches to modeling these problems using a single motivating example Finally we describe a number of state of the art systems and their extensions future challenges and some potential applications   Adversarial Machine Learning Yevgeniy Vorobeychik,Murat Kantarcioglu,2022-05-31 The increasing abundance of large high quality datasets combined with significant technical advances over the last several decades have made machine learning into a major tool employed across a broad array of tasks

including vision language finance and security However success has been accompanied with important new challenges many applications of machine learning are adversarial in nature Some are adversarial because they are safety critical such as autonomous driving An adversary in these applications can be a malicious party aimed at causing congestion or accidents or may even model unusual situations that expose vulnerabilities in the prediction engine Other applications are adversarial because their task and or the data they use are For example an important class of problems in security involves detection such as malware spam and intrusion detection The use of machine learning for detecting malicious entities creates an incentive among adversaries to evade detection by changing their behavior or the content of malicius objects they develop The field of adversarial machine learning has emerged to study vulnerabilities of machine learning approaches in adversarial settings and to develop techniques to make learning robust to adversarial manipulation This book provides a technical overview of this field After reviewing machine learning concepts and approaches as well as common use cases of these in adversarial settings we present a general categorization of attacks on machine learning We then address two major categories of attacks and associated defenses decision time attacks in which an adversary changes the nature of instances seen by a learned model at the time of prediction in order to cause errors and poisoning or training time attacks in which the actual training dataset is maliciously modified In our final chapter devoted to technical content we discuss recent techniques for attacks on deep learning as well as approaches for improving robustness of deep neural networks We conclude with a discussion of several important issues in the area of adversarial learning that in our view warrant further research Given the increasing interest in the area of adversarial machine learning we hope this book provides readers with the tools necessary to successfully engage in research and practice of machine learning in adversarial settings **Transfer Learning for Multiagent Reinforcement Learning Systems** Felipe Leno da Silva,Anna Helena Reali Costa,2022-06-01 Learning to solve sequential decision making tasks is difficult Humans take years exploring the environment essentially in a random way until they are able to reason solve difficult tasks and collaborate with other humans towards a common goal Artificial Intelligent agents are like humans in this aspect Reinforcement Learning RL is a well known technique to train autonomous agents through interactions with the environment Unfortunately the learning process has a high sample complexity to infer an effective actuation policy especially when multiple agents are simultaneously actuating in the environment However previous knowledge can be leveraged to accelerate learning and enable solving harder tasks In the same way humans build skills and reuse them by relating different tasks RL agents might reuse knowledge from previously solved tasks and from the exchange of knowledge with other agents in the environment In fact virtually all of the most challenging tasks currently solved by RL rely on embedded knowledge reuse techniques such as Imitation Learning Learning from Demonstration and Curriculum Learning This book surveys the literature on knowledge reuse in multiagent RL The authors define a unifying taxonomy of state of the art solutions for reusing knowledge providing a comprehensive discussion of recent progress in the area In this

book readers will find a comprehensive discussion of the many ways in which knowledge can be reused in multiagent sequential decision making tasks as well as in which scenarios each of the approaches is more efficient The authors also provide their view of the current low hanging fruit developments of the area as well as the still open big questions that could result in breakthrough developments Finally the book provides resources to researchers who intend to join this area or leverage those techniques including a list of conferences journals and implementation tools This book will be useful for a wide audience and will hopefully promote new dialogues across communities and novel developments in the area

Network Embedding Cheng Yang,Zhiyuan Liu,Cunchao Tu,Chuan Shi,Maosong Sun,2022-05-31 heterogeneous graphs Further the book introduces different applications of NE such as recommendation and information diffusion prediction Finally the book concludes the methods and applications and looks forward to the future directions   Predicting Human Decision-Making Ariel Rosenfeld,Sarit Kraus,2022-05-31 Human decision making often transcends our formal models of rationality Designing intelligent agents that interact proficiently with people necessitates the modeling of human behavior and the prediction of their decisions In this book we explore the task of automatically predicting human decision making and its use in designing intelligent human aware automated computer systems of varying natures from purely conflicting interaction settings e g security and games to fully cooperative interaction settings e g autonomous driving and personal robotic assistants We explore the techniques algorithms and empirical methodologies for meeting the challenges that arise from the above tasks and illustrate major benefits from the use of these computational solutions in real world application domains such as security negotiations argumentative interactions voting systems autonomous driving and games The book presents both the traditional and classical methods as well as the most recent and cutting edge advances providing the reader with a panorama of the challenges and solutions in predicting human decision making   **Multi-Objective Decision Making** Diederik M. Roijers,Shimon Whiteson,2022-05-31 Many real world decision problems have multiple objectives For example when choosing a medical treatment plan we want to maximize the efficacy of the treatment but also minimize the side effects These objectives typically conflict e g we can often increase the efficacy of the treatment but at the cost of more severe side effects In this book we outline how to deal with multiple objectives in decision theoretic planning and reinforcement learning algorithms To illustrate this we employ the popular problem classes of multi objective Markov decision processes MOMDPs and multi objective coordination graphs MO CoGs First we discuss different use cases for multi objective decision making and why they often necessitate explicitly multi objective algorithms We advocate a utility based approach to multi objective decision making i e that what constitutes an optimal solution to a multi objective decision problem should be derived from the available information about user utility We show how different assumptions about user utility and what types of policies are allowed lead to different solution concepts which we outline in a taxonomy of multi objective decision problems Second we show how to create new methods for multi objective decision making using existing

single objective methods as a basis Focusing on planning we describe two ways to creating multi objective algorithms in the inner loop approach the inner workings of a single objective method are adapted to work with multi objective solution concepts in the outer loop approach a wrapper is created around a single objective method that solves the multi objective problem as a series of single objective problems After discussing the creation of such methods for the planning setting we discuss how these approaches apply to the learning setting Next we discuss three promising application domains for multi objective decision making algorithms energy health and infrastructure and transportation Finally we conclude by outlining important open problems and promising future directions   Applying Reinforcement Learning on Real-World Data with Practical Examples in Python Philip Osborne,Kajal Singh,Matthew E. Taylor,2022-05-20 Reinforcement learning is a powerful tool in artificial intelligence in which virtual or physical agents learn to optimize their decision making to achieve long term goals In some cases this machine learning approach can save programmers time outperform existing controllers reach super human performance and continually adapt to changing conditions It has shown human level performance on a number of tasks REF and the methodology for automation in robotics and self driving cars REF This book argues that these successes show reinforcement learning can be adopted successfully in many different situations including robot control stock trading supply chain optimization and plant control However reinforcement learning has traditionally been limited to applications in virtual environments or simulations in which the setup is already provided Furthermore experimentation may be completed for an almost limitless number of attempts risk free In many real life tasks applying reinforcement learning is not as simple as 1 data is not in the correct form for reinforcement learning 2 data is scarce and 3 automation has limitations in the real world Therefore this book is written to help academics domain specialists and data enthusiast alike to understand the basic principles of applying reinforcement learning to real world problems This is achieved by focusing on the process of taking practical examples and modeling standard data into the correct form required to then apply basic agents To further assist readers gain a deep and grounded understanding of the approaches the book shows hand calculated examples in full and then how this can be achieved in a more automated manner with code For decision makers who are interested in reinforcement learning as a solution but are not proficient the book includes simple non technical examples in the introduction and case studies section These provide context of what reinforcement learning offer but also the challenges and risks associated with applying it in practice Specifically these sections illustrate the differences between reinforcement learning and other machine learning approaches as well as how well known companies have found success using the approach to their problems   **General Game Playing** Michael Genesereth,Michael Thielscher,2022-06-01 General game players are computer systems able to play strategy games based solely on formal game descriptions supplied at runtime n other words they don t know the rules until the game starts Unlike specialized game players such as Deep Blue general game players cannot rely on algorithms designed in advance for specific games they must discover such algorithms themselves

General game playing expertise depends on intelligence on the part of the game player and not just intelligence of the programmer of the game player GGP is an interesting application in its own right It is intellectually engaging and more than a little fun But it is much more than that It provides a theoretical framework for modeling discrete dynamic systems and defining rationality in a way that takes into account problem representation and complexities like incompleteness of information and resource bounds It has practical applications in areas where these features are important e g in business and law More fundamentally it raises questions about the nature of intelligence and serves as a laboratory in which to evaluate competing approaches to artificial intelligence This book is an elementary introduction to General Game Playing GGP 1 It presents the theory of General Game Playing and leading GGP technologies 2 It shows how to create GGP programs capable of competing against other programs and humans 3 It offers a glimpse of some of the real world applications of General Game Playing **Metric Learning** Aurélien Muise,Amaury Yang,2022-05-31 Similarity between objects plays an important role in both human cognitive processes and artificial systems for recognition and categorization How to appropriately measure such similarities for a given task is crucial to the performance of many machine learning pattern recognition and data mining methods This book is devoted to metric learning a set of techniques to automatically learn similarity and distance functions from data that has attracted a lot of interest in machine learning and related fields in the past ten years In this book we provide a thorough review of the metric learning literature that covers algorithms theory and applications for both numerical and structured data We first introduce relevant definitions and classic metric functions as well as examples of their use in machine learning and data mining We then review a wide range of metric learning algorithms starting with the simple setting of linear distance and similarity learning We show how one may scale up these methods to very large amounts of training data To go beyond the linear case we discuss methods that learn nonlinear metrics or multiple linear metrics throughout the feature space and review methods for more complex settings such as multi task and semi supervised learning Although most of the existing work has focused on numerical data we cover the literature on metric learning for structured data like strings trees graphs and time series In the more technical part of the book we present some recent statistical frameworks for analyzing the generalization performance in metric learning and derive results for some of the algorithms presented earlier Finally we illustrate the relevance of metric learning in real world problems through a series of successful applications to computer vision bioinformatics and information retrieval Table of Contents Introduction Metrics Properties of Metric Learning Algorithms Linear Metric Learning Nonlinear and Local Metric Learning Metric Learning for Special Settings Metric Learning for Structured Data Generalization Guarantees for Metric Learning Applications Conclusion Bibliography Authors Biographies

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