

Simulink-GUI Synchronization Example
by Will Campbell
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- 1) GUI automatically opened by code in:
File → Model Properties → Callbacks → PostLoadFcn
- 2) GUI automatically closed by code in:
File → Model Properties → Callbacks → CloseFcn
- 3) GUI Start/Stop button synchronized by code in:
File → Model Properties → Callbacks → StartFcn
File → Model Properties → Callbacks → StopFcn
- 4) GUI Switch checkbox synchronized by code in:
Manual Switch → Block Properties → Callbacks → OpenFcn

Open `sl_sync_gui.m` to see how the GUI drives the model.



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Formal Verification of Simulink/Stateflow Diagrams Naijun Zhan, Shuling Wang, Hengjun Zhao, 2016-11-07 This book presents a state of the art technique for formal verification of continuous time Simulink Stateflow diagrams featuring an expressive hybrid system modelling language a powerful specification logic and deduction based verification approach and some impressive realistic case studies Readers will learn the HCSP HHL based deductive method and the use of corresponding tools for formal verification of Simulink Stateflow diagrams They will also gain some basic ideas about fundamental elements of formal methods such as formal syntax and semantics and especially the common techniques applied in formal modelling and verification of hybrid systems By investigating the successful case studies readers will realize how to apply the pure theory and techniques to real applications and hopefully will be inspired to start to use the proposed approach or even develop their own formal methods in their future work

Provably Correct Systems Mike Hinchey, Jonathan P. Bowen, Ernst-Rüdiger Olderog, 2017-03-01 As computers increasingly control the systems and services we depend upon within our daily lives like transport communications and the media ensuring these systems function correctly is of utmost importance This book consists of twelve chapters and one historical account that were presented at a workshop in London in 2015 marking the 25th anniversary of the European ESPRIT Basic Research project ProCoS Provably Correct Systems The ProCoS I and II projects pioneered and accelerated the automation of verification techniques resulting in a wide range of applications within many trades and sectors such as aerospace electronics communications and retail The following topics are covered An historical account of the ProCoS project Hybrid Systems Correctness of Concurrent Algorithms Interfaces and Linking Automatic Verification Run time Assertions Checking Formal and Semi Formal Methods Provably Correct Systems provides researchers designers and engineers with a complete overview of the ProCoS initiative past and present and explores current developments and perspectives within the field

VLSI Design and Test Brajesh Kumar Kaushik, Sudeb Dasgupta, Virendra Singh, 2017-12-21 This book constitutes the refereed proceedings of the 21st International Symposium on VLSI Design and Test VDAT 2017 held in Roorkee India in June July 2017 The 48 full papers presented together with 27 short papers were carefully reviewed and selected from 246 submissions The papers were organized in topical sections named digital design analog mixed signal VLSI testing devices and technology VLSI architectures emerging technologies and memory system design low power design and test RF circuits architecture and CAD and design verification

Scientific Computing with MATLAB Dingyu Xue, YangQuan Chen, 2016-02-17 Scientific Computing with MATLAB Second Edition improves students ability to tackle mathematical problems It helps students understand the mathematical background and find reliable and accurate solutions to mathematical problems with the use of MATLAB avoiding the tedious and complex technical details of mathematics This edition retains the structure of its predecessor while expanding and updating the content of each chapter The book bridges the gap between problems and solutions through well grouped topics and clear

MATLAB example scripts and reproducible MATLAB generated plots Students can effortlessly experiment with the scripts for a deep hands on exploration Each chapter also includes a set of problems to strengthen understanding of the material

Unifying Theories of Programming Jonathan P. Bowen,Huibiao Zhu,2017-01-10 This book constitutes the refereed proceedings of the 6th International Symposium on Unifying Theories of Programming UTP 2016 held in Reykjavik Iceland in June 2016 in conjunction with the 12th International Conference on Integrated Formal Methods iFM 2016 The 8 revised full papers presented were carefully reviewed and selected from 10 submissions They deal with the fundamental problem of combination of formal notations and theories of programming that define in various different ways many common notions such as abstraction refinement choice termination feasibility locality concurrency and communication They also show that despite many differences such theories may be unified in a way that greatly facilitates their study and comparison

Principles of Object-Oriented Modeling and Simulation with Modelica 3.3 Peter Fritzson,2015-01-06 Fritzson covers the Modelica language in impressive depth from the basic concepts such as cyber physical equation base object oriented system model and simulation while also incorporating over a hundred exercises and their solutions for a tutorial easy to read experience The only book with complete Modelica 3.3 coverage Over one hundred exercises and solutions Examines basic concepts such as cyber physical equation based object oriented system model and simulation

Manufacturing Process and Equipment Xiang Hua Liu,Kai Feng Zhang,Ming Zhe Li,2013-05-14 Selected peer reviewed papers from the 2013 International Conference on Manufacturing Science and Engineering 4th ICMSE 2013 March 30 31 2013 Dalian China

MATLAB Kelly Bennett,2014-09-08 MATLAB is an indispensable asset for scientists researchers and engineers The richness of the MATLAB computational environment combined with an integrated development environment IDE and straightforward interface toolkits and simulation and modeling capabilities creates a research and development tool that has no equal From quick code prototyping to full blown deployable applications MATLAB stands as a de facto development language and environment serving the technical needs of a wide range of users As a collection of diverse applications each book chapter presents a novel application and use of MATLAB for a specific result

Handbook Of Renewable Energy Technology & Systems Ramesh C Bansal,Ahmed F Zobaa,2021-08-13 Worldwide the effects of global warming pollution due to power generation from fossil fuels and its depletion have led to the rapid deployment of renewable energy based power generation The leading renewable technologies are wind and photovoltaic PV systems The incorporation of this generation of technologies has led to the development of a broad array of new methods and tools to integrate renewable generation into power system networks The Handbook of Renewable Energy Technology Systems comprises 22 chapters arranged into four sections which present a comprehensive analysis of various renewable energy based distributed generation DG technologies Aspects of renewable energy covered include wind and photovoltaic power systems and technology micro grids power electronic applications power quality and the protection of renewable distributed generation

ROBOT2013: First Iberian Robotics Conference Manuel A. Armada,Alberto Sanfeliu,Manuel Ferre,2013-11-12 This book contains the proceedings of the ROBOT 2013 FIRST IBERIAN ROBOTICS CONFERENCE and it can be said that included both state of the art and more practical presentations dealing with implementation problems support technologies and future applications A growing interest in Assistive Robotics Agricultural Robotics Field Robotics Grasping and Dexterous Manipulation Humanoid Robots Intelligent Systems and Robotics Marine Robotics has been demonstrated by the very relevant number of contributions Moreover ROBOT2013 incorporates a special session on Legal and Ethical Aspects in Robotics that is becoming a topic of key relevance This Conference was held in Madrid 28 29 November 2013 organized by the Sociedad Espa ola para la Investigaci n y Desarrollo en Rob tica SEIDROB and by the Centre for Automation and Robotics CAR Universidad Polit cnica de Madrid UPM and Consejo Superior de Investigaciones Cient ficas CSIC along with the co operation of Grupo Tem tico de Rob tica CEA GTRob Sociedade Portuguesa de Robotica SPR Asociaci n Espa ola de Promoci n de la Investigaci n en Agentes F sicos RedAF and partially supported by Comunidad de Madrid under RoboCity2030 Programme

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