

Chapter 2

P.2-1 (a) $\vec{a}_1 = \frac{\vec{A}}{A} = \frac{\vec{a}_x + \vec{a}_y 2 - \vec{a}_z 3}{\sqrt{1^2 + 2^2 + (-3)^2}} = \frac{1}{\sqrt{14}} (\vec{a}_x + \vec{a}_y 2 - \vec{a}_z 3)$

(b) $|\vec{A} - \vec{B}| = |\vec{a}_x + \vec{a}_y 6 - \vec{a}_z 4| = \sqrt{1^2 + 6^2 + 4^2} = \sqrt{53}$

(c) $\vec{A} \cdot \vec{B} = 0 + 2(-4) + (-3) = -11$

(d) $\theta_{AB} = \cos^{-1}(\vec{A} \cdot \vec{B} / AB) = \cos^{-1}(-11 / \sqrt{14} \sqrt{17}) = 135.5^\circ$

(e) $\vec{A} \cdot \vec{a}_c = \vec{A} \cdot \frac{\vec{C}}{C} = \vec{A} \cdot \frac{1}{\sqrt{29}} (\vec{a}_x 5 - \vec{a}_z 2) = \frac{11}{\sqrt{29}}$

(f) $\vec{A} \times \vec{C} = -\vec{a}_x 4 - \vec{a}_y 13 - \vec{a}_z 10$

(g) $\vec{A} \cdot (\vec{B} \times \vec{C}) = (\vec{A} \times \vec{B}) \cdot \vec{C} = -42$

(h) $(\vec{A} \times \vec{B}) \times \vec{C} = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{A}(\vec{C} \cdot \vec{B}) = \vec{a}_x 2 - \vec{a}_y 40 + \vec{a}_z 5$
 $\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B}) = \vec{a}_x 33 + \vec{a}_y 44 - \vec{a}_z 11$

P.2-2 Position vectors of the three corners:

$\vec{OP}_1 = \vec{a}_y - \vec{a}_z 2$, $\vec{OP}_2 = \vec{a}_x 4 - \vec{a}_y - \vec{a}_z 3$, $\vec{OP}_3 = \vec{a}_x 6 + \vec{a}_y 2 + \vec{a}_z 5$

Vectors representing the three sides of the triangle:

$\vec{P}_1 \vec{P}_2 = \vec{OP}_2 - \vec{OP}_1 = \vec{a}_x 4 - \vec{a}_z$, $\vec{P}_2 \vec{P}_3 = \vec{a}_x 2 + \vec{a}_y + \vec{a}_z 8$, $\vec{P}_3 \vec{P}_1 = -\vec{a}_x 6 - \vec{a}_y - \vec{a}_z$

(a) $\vec{P}_1 \vec{P}_2 \cdot \vec{P}_2 \vec{P}_3 = 0$. $\therefore \Delta P_1 P_2 P_3$ is a right triangle.

(b) Area of triangle = $\frac{1}{2} |\vec{P}_1 \vec{P}_2 \times \vec{P}_2 \vec{P}_3| = 17.1$

P.2-3



$\vec{D}_1 = \vec{B} + \vec{A}$, $\vec{D}_2 = \vec{B} - \vec{A}$

$\vec{D}_1 \cdot \vec{D}_2 = (\vec{B} + \vec{A}) \cdot (\vec{B} - \vec{A})$
 $= \vec{B} \cdot \vec{B} - \vec{A} \cdot \vec{A} = 0$

$\therefore \vec{D}_1 \perp \vec{D}_2$

P.2-4 From $\vec{A} \cdot \vec{B} = \vec{A} \cdot \vec{C}$, we have $\vec{A} \cdot (\vec{B} - \vec{C}) = 0$. (1)

From $\vec{A} \times \vec{B} = \vec{A} \times \vec{C}$, we have $\vec{A} \times (\vec{B} - \vec{C}) = 0$. (2)

(1) implies $\vec{A} \perp (\vec{B} - \vec{C})$ and (2) implies $\vec{A} \parallel (\vec{B} - \vec{C})$. Since $\vec{A}$ is not a null vector, (1) and (2) cannot hold at the same time unless $(\vec{B} - \vec{C})$ is a null vector. Thus, $\vec{B} - \vec{C} = 0$ or $\vec{B} = \vec{C}$.

P.2-5 $\vec{a}_1 \cdot \vec{a}_2 = \cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$.

Manual Solution Of David Cheng

Julio Sanchez, Maria P. Canton



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Advances in Manufacturing Technology XVI - NCMR 2002 Kai Cheng, David Webb, 2002-11-22 Advances in Manufacturing Technology XVI provides a comprehensive collection of papers exploring the very latest developments in the field of manufacturing engineering and management and incorporates the most up to date techniques TOPICS COVERED INCLUDE Business strategies process reengineering CAD CAM and concurrent engineering E manufacturing and virtual reality Engineering modelling and simulations Total quality management and metrology Intelligent systems robotics and automation Lean and agile manufacturing Machining process and tooling Operations management Process control and condition monitoring Covering all aspects of manufacturing engineering systems and management this volume will be of great interest to those wanting to keep abreast of current research and those involved in the planning stages in this area of engineering

Fundamentals of Engineering Electromagnetics David K. Cheng, 1993-02 Programming Solutions Handbook for IBM Microcomputers Julio Sanchez, Maria P. Canton, 1991 A time saving guide for solving all kinds of programming problems this book picks up where other programming codebooks leave off assuming programmers know the basics and providing help with more complex programming problems Each subject in the book is treated in detail with numerous code samples that can be interfaced with all high level languages

EBOOK: Vector Mechanics for Engineers: Statics (SI units) Ferdinand Beer, E. Johnston, David Mazurek, 2012-10-16 Target Audience This text is designed for the first course in Statics offered in the sophomore year Overview The main objective of a first course in mechanics should be to develop in the engineering student the ability to analyze any problem in a simple and logical manner and to apply to its solution a few well understood basic principles This text is designed to help the instructor achieve this goal Vector analysis is introduced early in the text and is used in the presentation and discussion of the fundamental principles of mechanics Vector methods are also used to solve many problems particularly three dimensional problems where these techniques result in a simpler and more concise solution The emphasis in this text however remains on the correct understanding of the principles of mechanics and on their application to the solution of engineering problems and vector analysis is presented chiefly as a convenient tool In order to achieve the goal of being able to analyze mechanics problems the text employs the following pedagogical strategy Practical applications are introduced early New concepts are introduced simply Fundamental principles are placed in simple contexts Students are given extensive practice through sample problems special sections entitled Solving Problems on Your Own extensive homework problem sets review problems at the end of each chapter and computer problems designed to be solved with computational software Resources Supporting This Textbook Instructor's and Solutions Manual features typeset one per page solutions to the end of chapter problems It also features a number of tables designed to assist instructors in creating a schedule of assignments for their course The various topics covered in the text have been listed in Table I and a suggested number of periods to be spent on each topic has been indicated Table II prepares a brief

description of all groups of problems Sample lesson schedules are shown in Tables III IV and V together with various alternative lists of assigned homework problems For additional resources related to users of this SI edition please visit <http://www.mheducation.com> beerjohnston McGraw Hill Connect Engineering a web based assignment and assessment platform is available at <http://www.mhhe.com/beerjohnston> and includes algorithmic problems from the text Lecture PowerPoints an image bank and animations Hands on Mechanics is a website designed for instructors who are interested in incorporating three dimensional hands on teaching aids into their lectures Developed through a partnership between the McGraw Hill Engineering Team and the Department of Civil and Mechanical Engineering at the United States Military Academy at West Point this website not only provides detailed instructions for how to build 3 D teaching tools using materials found in any lab or local hardware store but also provides a community where educators can share ideas trade best practices and submit their own original demonstrations for posting on the site Visit <http://www.handsonmechanics.com> McGraw Hill Tegrity a service that makes class time available all the time by automatically capturing every lecture in a searchable format for students to review when they study and complete assignments To learn more about Tegrity watch a 2 minute Flash demo at <http://tegritycampus.mhhe.com>

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Process Dynamics and Control Dale E. Seborg,Thomas F. Edgar,Duncan A. Mellichamp,Francis J. Doyle, III,2016-09-13 The new 4th edition of Seborg s Process Dynamics Control provides full topical coverage for process control courses in the chemical engineering curriculum emphasizing how process control and its related fields of process modeling and optimization are essential to the development of high value products A principal objective of this new edition is to describe modern techniques for control processes with an emphasis on complex systems necessary to the development design and operation of modern processing plants Control process instructors can cover the basic material while also having the flexibility to include advanced topics

Books in Print ,1994 *Solutions Manual for Field and Wave Electromagnetics* David K. Cheng,1983

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