


3/1  $v_2^2 - v_1^2 = 2a(x_2 - x_1)$   
 $0^2 - \left(\frac{100}{3.2}\right)^2 = 2a_x(50)$ ,  $a_x = -7.72 \text{ m/s}^2$   


$\Sigma F_x = ma_x$ :  $-4F = 1500(-7.72)$   
 $F = 2870 \text{ N}$

3/2  $50(9.81) \text{ N}$   $\Sigma F_y = 0$ :  $N - 50(9.81) \cos 15^\circ = 0$   
 $N = 474 \text{ N}$  Throughout

(a)  $P = 0$   
 Equilibrium check:  
 $\Sigma F_x = 0$ :  $F - 50(9.81) \sin 15^\circ = 0$   
 $F = 127.9 \text{ N}$

$F_{\max} = \mu_s N = 0.2(474) = 94.8 \text{ N} < F$ : motion  $\checkmark$   
 $\Sigma F_x = ma_x$ :  $0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$   
 $a_x = -1.118 \text{ m/s}^2$

(b)  $P = 150 \text{ N}$ ; Equilibrium check:  
 $\Sigma F_y = 0$ :  $150 + F - 50(9.81) \sin 15^\circ = 0$


$F = -23.9 \text{ N}$ ,  $|F| < F_{\max}$  so no motion:  $a = 0$


(c)  $P = 300 \text{ N}$ ; Equilibrium check yields  $F = -173.0 \text{ N}$   
 $|F| > F_{\max}$ , so motion  $\checkmark$ ,  $F = F_k \checkmark$ .  
 $\Sigma F_x = ma_x$ :  $300 - 0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$   
 $a_x = 2.04 \text{ m/s}^2$

3/3  $80 \text{ lb}$   $\Sigma F_y = 0$ :  $N - 80 \cos 20^\circ = 0$   
 $N = 75.2 \text{ lb}$   
 $\Sigma F_x = ma_x$ :  
 $-0.25(75.2) - 80 \sin 20^\circ = \frac{80}{32.2} a$   
 $a = -18.58 \text{ ft/sec}^2$

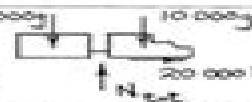
$v = v_0 + at$ :  $0 = 30 - 18.58t$ ,  $t = 1.615 \text{ sec}$   
 $v^2 = v_0^2 + 2a(s - s_0)$ :  $0^2 = 30^2 + 2(-18.58)d$   
 $d = 24.2 \text{ ft}$

$v^2 = v_0^2 + 2a(s - s_0)$ :  $15^2 = 30^2 + 2(-18.58)d'$   
 $d' = 18.17 \text{ ft}$


3/4  $300,000(9.81) \text{ N}$   
  
 $\Sigma F_x = ma_x$ :  
 $3(240,000) - 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$   
 $a_x = 2.31 \text{ m/s}^2$

$v^2 = 2a_x s$ :  $\left(\frac{220}{3.6}\right)^2 = 2(2.31)s$ ,  $s_x = 807 \text{ m}$   
  
 $\Sigma F_x = ma_x$ :  
 $3(240,000) + 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$   
 $a_x = 2.49 \text{ m/s}^2$


$v^2 = 2a_x s$ :  $\left(\frac{220}{3.6}\right)^2 = 2(2.49)s$ ,  $s_x = 751 \text{ m}$

3/5 For entire unit:  $20,000 \text{ kg}$   $10,000 \text{ kg}$   
 $\Sigma F = ma$ :  $20,000 = 30,000a$   
 $a = 0.667 \text{ m/s}^2$   


For trailer alone,  $T = 20,000(0.667) = 13,330 \text{ N}$   
 or  $T = 13.33 \text{ kN}$   


3/6  $\Sigma F_x = ma_x$ :  $mg \sin 40^\circ - \mu_k mg \cos 40^\circ = ma$   
 $a = 9.81(\sin 40^\circ - \mu_k \cos 40^\circ)$   
 $= 6.31 - 7.51 \mu_k$   


For constant accel.  $s = v_0 t + \frac{1}{2}at^2$ :  
 $20 = 0 + \frac{1}{2}(6.31 - 7.51 \mu_k)2.58^2$   
 $\mu_k = 0.0595$

3/7  $\Sigma F = ma$ :  $T - 100 = \frac{100}{32.2} a$   
 (a)  $T \uparrow$   $150 - T = \frac{100}{32.2} a$   
 $50 = \frac{200}{32.2} a$ ,  $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$   


(b)  $150 - 100 = \frac{100}{32.2} a$ ,  $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$   


# Meriam Dynamics Solutions Chapter 3

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*Nonlinear Vibration and Dynamics of Smart Continuous Structures and Materials* Majid Ghadiri,2025-05-08 Nonlinear Vibration and Dynamics of Smart Continuous Structures and Materials delves into intricate subjects concerning the analysis of nonlinear vibration issues in continuous structures It covers general concepts and a history of nonlinear systems before evolving into kinetics and solution methods of continuous structures Exploring the implementation of new types of materials in various sectors of automobile aerospace and structural engineering the book provides applicable information on the behaviors of smart structures The book provides a set of mathematical formulations to solve nonlinear static and dynamic behaviors of smart continuous structures by applying principles of elasticity The book will interest academic researchers and graduate students studying structural engineering mechanics of solids and smart materials      *Solving Dynamics Problems in Maple by Brian Harper T/a Engineering Mechanics Dynamics 6th Edition by Meriam and Kraige* Brian D. Harper,J. L. Meriam,L. G. Kraige,2006-12-15      **Statics** Meriam,J.L. (James L.),L. Glenn Kraige,2008 Over the past 50 years Meriam Kraige s Engineering Mechanics Statics has established a highly respected tradition of excellence a tradition that emphasizes accuracy rigor clarity and applications Now in a Sixth Edition this classic text builds on these strengths adding a comprehensive course management system Wiley Plus to the text including an e text homework management animations of concepts and additional teaching and learning resources New sample problems new homework problems and updates to content make the book more accessible The Sixth Edition continues to provide a wide variety of high quality problems that are known for their accuracy realism applications and variety motivating students to learn and develop their problem solving skills To build necessary visualization and problem solving skills the Sixth Edition continues to offer comprehensive coverage of drawing free body diagrams the most important skill needed to solve mechanics problems      *Dynamics* James L. Meriam,1959      **Engineering Mechanics: Statics, Australian New Zealand Edition** James L. Meriam,L. Glenn Kraige,Jeff N. Bolton,2019-07-09 A foundation in mechanics principles with integrated engineering design problems Recognized for its accuracy and reliability Engineering Mechanics Statics has provided a solid foundation of mechanics principles for decades The ninth edition helps students develop problem solving skills This text for Australia and New Zealand includes helpful sample and practice problems It guides students in developing visualization and problem solving skills by focusing on the drawing of free body diagrams a key skill for solving mechanics problems      **Solving Dynamics Problems in MathCad A Supplement to Accompany Engineering Mechanics: Dynamics, 5th Edition by Meriam & Kraige** Brian Harper,2001-11-26 If MathCad is the computer algebra system you need to use for your engineering calculations and graphical output Harper s Solving Dynamics Problems in MathCad is the reference that will be a valuable tutorial for your studies Written as a guidebook for students taking the Engineering Mechanics course it will help you with

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