Kinematics

Rectilinear motion
$$v = \frac{ds}{dt}$$
 $a = \frac{dv}{dt}$ $a ds = v dv$

velocity
$$\int_{v_0}^{v} dv = \int_{t_0}^{t} a dt$$
 or $\int_{v_0}^{v} v dv = \int_{s_0}^{s} a ds$

position
$$\int_{s_0}^{s} ds = \int_{t_0}^{t} v dt$$

curvilinear motion
$$v = \frac{dr}{dt}$$
 $\alpha = \frac{dr}{dt}$

normal – tangential
$$\mathbf{v} = \mathbf{v} \ \mathbf{u}_{\mathbf{t}}$$
 $\mathbf{a} = \mathbf{a}_{\mathbf{t}} \ \mathbf{u}_{\mathbf{t}} + \mathbf{a}_{\mathbf{n}} \ \mathbf{u}_{\mathbf{n}} = \ \mathbf{v}' \ \mathbf{u}_{\mathbf{t}} + \frac{\mathbf{v}^2}{\rho} \ \mathbf{u}_{\mathbf{n}}$

radius of curvature
$$\rho = \frac{\left[1 + \left(\frac{d_2}{d_3}\right)^2\right]^{\frac{3}{2}}}{\left[\frac{d_2}{d_3}\right]^{\frac{3}{2}}}$$

cylindrical/polar
$$\mathbf{v} = \mathbf{v}_r \, \mathbf{u}_r + \mathbf{v}_\theta \mathbf{u}_\theta + \mathbf{v}_z \mathbf{u}_z = \hat{\mathbf{r}} \, \mathbf{u}_r + \mathbf{r} \, \hat{\mathbf{\theta}} \, \mathbf{u}_\theta + \hat{\mathbf{z}} \mathbf{u}_z$$

$$\mathbf{a} = \mathbf{a}_r \mathbf{u}_r + \mathbf{a}_\theta \mathbf{u}_\theta + \mathbf{a}_z \mathbf{u}_z = (\hat{\mathbf{r}} - \mathbf{r} \, \hat{\mathbf{\theta}}^2) \mathbf{u}_r + (\hat{\mathbf{r}} \, \hat{\mathbf{\theta}} + 2 \, \hat{\mathbf{r}} \, \hat{\mathbf{\theta}}) \mathbf{u}_\theta + \hat{\mathbf{z}} \mathbf{u}_z$$

relative motion
$$r_B = r_A + r_{B/A}$$
 $v_B = v_A + v_{B/A}$ $a_B = a_A + a_{B/A}$

Kinetics

Force due to a spring
$$F_s = k(s-s_0)$$
 s=deformed length, s_0 =undeformed length

Friction force static friction
$$F \le \mu_s N$$

dynamic friction (sliding)
$$F = \mu_k N$$

Newton's second law
$$\Sigma F = m a = m(a_n I + a_n J) = m(a_n u + a_n u) = m(a_n u + a_n u)$$

Work
$$U_{1-2} = \int_{r_2}^{r_2} \mathbf{F} \cdot d\mathbf{r}$$
 Kinetic energy $T = \frac{1}{2} mv^2$

Principle of Work and energy
$$T_1 + \sum U_{1\cdot 2} = T_2$$

Conservation of Energy
$$T_1 + V_1 = T_2 + V_2$$

Potentials (conservative forces) gravity
$$V_0 = mgy$$

linear spring
$$V_e = V_2 k(s-s_0)^2$$

s=deformed length, so=undeformed length

Power P = F · V

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systematic derivations and complete research of ZTD formulas from special 3S ZTD formulas to general NS ZTD formulas. These finally lead to their proposed discrete time Zhang neural network DTZNN algorithms which are more efficient accurate and elegant. This book will open the door to scientific and engineering applications of ZTD formulas and neural networks and will be a major inspiration for studies in neural network modeling numerical algorithm design prediction and robot manipulator control. The book will benefit engineers senior undergraduates graduate students and researchers in the fields of neural networks computer mathematics computer science artificial intelligence numerical algorithms optimization robotics and simulation modeling. Mechanical Vibration Haym Benaroya, Mark Nagurka, Seon Mi Han, 2022-07-15 Mechanical Vibration Analysis Uncertainty and Control presents comprehensive coverage of the fundamental principles of mechanical vibration including the theory of vibration as well as discussions and examples of the applications of these principles to practical engineering problems. In dealing with the subject of vibration the engineer must also consider the effects of uncertainties in the analysis and methods for the control of vibration As such this book includes treatment of both subjects modeling of uncertainties and vibration control Many example problems with solutions are included and are been carefully chosen and are presented at strategic points enabling the reader to have a thorough understanding of the subject and to help cement core ideas the book includes compelling case studies and stories of real world applications of mechanical vibration

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Differential Equations, Mathematical Modeling and Computational Algorithms Vladimir Vasilyev, 2023-06-06 This book contains reports made at the International Conference on Differential Equations Mathematical Modeling and Computational Algorithms held in Belgorod Russia in October 2021 and is devoted to various aspects of the theory of differential equations and their applications in various branches of science Theoretical papers devoted to the

qualitative analysis of emerging mathematical objects theorems of the existence and uniqueness of solutions to the boundary value problems under study are presented and numerical algorithms for their solution are described Some issues of mathematical modeling are also covered in particular in problems of economics computational aspects of the theory of differential equations and boundary value problems are studied The articles are written by well known experts and are interesting and useful to a wide audience mathematicians representatives of applied sciences and students and postgraduates of universities engaged in applied mathematics **Numerical Methods in Mechanics of Materials** Ken Chong, Arthur Boresi, Sunil Saigal, James Lee, 2017-11-27 In the dynamic digital age the widespread use of computers has transformed engineering and science A realistic and successful solution of an engineering problem usually begins with an accurate physical model of the problem and a proper understanding of the assumptions employed With computers and appropriate software we can model and analyze complex physical systems and problems However efficient and accurate use of numerical results obtained from computer programs requires considerable background and advanced working knowledge to avoid blunders and the blind acceptance of computer results This book provides the background and knowledge necessary to avoid these pitfalls especially the most commonly used numerical methods employed in the solution of physical problems It offers an in depth presentation of the numerical methods for scales from nano to macro in nine self contained chapters with extensive problems and up to date references covering Trends and new developments in simulation and computation Weighted residuals methods Finite difference methods Finite element methods Finite strip layer prism methods Boundary element methods Meshless methods Molecular dynamics Multiphysics problems Multiscale methods **Engineering** Science and Mechanics American Astronautical Society, 1983 Advances in Electrical Engineering and Automation Anne Xie, Xiong Huang, 2012-02-02 EEA2011 is an integrated conference concentration its focus on Electrical Engineering and Automation In the proceeding you can learn much more knowledge about Electrical Engineering and Automation of researchers from all around the world The main role of the proceeding is to be used as an exchange pillar for researchers who are working in the mentioned fields In order to meet the high quality of Springer AISC series the organization committee has made their efforts to do the following things Firstly poor quality paper has been refused after reviewing course by anonymous referee experts Secondly periodically review meetings have been held around the reviewers about five times for exchanging reviewing suggestions Finally the conference organizers had several preliminary sessions before the conference Through efforts of different people and departments the conference will be successful and fruitful Comprehensive **Semiconductor Science and Technology**, 2011-01-28 Semiconductors are at the heart of modern living Almost everything we do be it work travel communication or entertainment all depend on some feature of semiconductor technology Comprehensive Semiconductor Science and Technology Six Volume Set captures the breadth of this important field and presents it in a single source to the large audience who study make and exploit semiconductors Previous attempts at this

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