

# Fundamentals of Astrodynamics and Applications

Fourth Edition

**David A. Vallado**

with contributions by  
Wayne D. McClain



# Fundamentals Of Astrodynamics And Applications 4th Edition

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## **Fundamentals Of Astrodynamics And Applications 4th Edition:**

**Fundamentals of Astrodynamics and Applications** D.A. Vallado, 2001-06-30 Fundamentals of Astrodynamics and Applications is rapidly becoming the standard astrodynamics reference for those involved in the business of spaceflight What sets this book apart is that nearly all of the theoretical mathematics is followed by discussions of practical applications implemented in tested software routines For example the book includes a compendium of algorithms that allow students and professionals to determine orbits with high precision using a PC Without a doubt when an astrodynamics problem arises in the future it will become standard practice for engineers to keep this volume close at hand and look it up in Vallado While the first edition was an exceptionally useful and popular book throughout the community there are a number of reasons why the second edition will be even more so There are many reworked examples and derivations Newly introduced topics include ground illumination calculations Moon rise and set and a listing of relevant Internet sites There is an improved and expanded discussion of coordinate systems orbit determination and differential correction Perhaps most important is that all of the software routines described in the book are now available for free in FORTRAN PASCAL and C This makes the second edition an even more valuable text and superb reference *Fundamentals of Astrodynamics and Applications* David Anthony Vallado, Wayne D. McClain, 1997 This book integrates two body dynamics and applications with perturbation methods and real world applications *Fundamentals of Astrodynamics and Applications* David A. Vallado, Wayne D. McClain, 2001-01-01

Interplanetary Astrodynamics David B. Spencer, Davide Conte, 2023-04-28 Focusing on the orbital mechanics tools and techniques necessary to design predict and guide a trajectory of a spacecraft traveling between two or more bodies in a Solar System this book covers the dynamical theory necessary for describing the motion of bodies in space examines the N body problem and shows applications using this theory for designing interplanetary missions While most orbital mechanics books focus primarily on Earth orbiting spacecraft with a brief discussion of interplanetary missions this book reverses the focus and emphasizes the interplanetary aspects of space missions Written for instructors graduate students and advanced undergraduate students in Aerospace and Mechanical Engineering this book provides advanced details of interplanetary trajectory design navigation and targeting An Introduction to GNSS Geodesy and Applications Clement A. Ogaja, 2024-12-26 This volume is the second edition to 2022 s Introduction to GNSS Geodesy Foundations of Precise Positioning Using Global Navigation Satellite Systems It serves as an important reference to GNSS beginners as well as seasoned enthusiasts In this updated edition author Clement Ogaja focuses on fundamentals and contents that will remain unaffected by rapid changes and data exchange formats ensuring that the book will remain up to date for years The book consists of five chapters The first covers basic concepts of parameter estimation in GNSS Geodesy From there Chapter 2 discusses reference systems in GNSS Geodesy Chapter 3 moves on to observation models errors and biases and Chapter 4 which is completely new to this second edition details GNSS data processing workflow and strategies The book concludes

with an applied chapter that details concrete uses of GNSS Geodesy New appendices that will be especially useful to seasoned users are also featured

*Introduction to Orbital Perturbations* James M. Longuski, Felix R. Hoots, George E. Pollock IV, 2022-03-01 This textbook provides details of the derivation of Lagrange's planetary equations and of the closely related Gauss's variational equations thereby covering a sorely needed topic in existing literature Analytical solutions can help verify the results of numerical work giving one confidence that his or her analysis is correct The authors all experienced experts in astrodynamics and space missions take on the massive derivation problem step by step in order to help readers identify and understand possible analytical solutions in their own endeavors The stages are elementary yet rigorous suggested student research project topics are provided After deriving the variational equations the authors apply them to many interesting problems including the Earth Moon system the effect of an oblate planet the perturbation of Mercury's orbit due to General Relativity and the perturbation due to atmospheric drag Along the way they introduce several useful techniques such as averaging Poincaré's method of small parameters and variation of parameters In the end this textbook will help students practicing engineers and professionals across the fields of astrodynamics astronomy dynamics physics planetary science spacecraft missions and others An extensive detailed yet still easy to follow presentation of the field of orbital perturbations Prof Hanspeter Schaub Smead Aerospace Engineering Sciences Department University of Colorado Boulder This book based on decades of teaching experience is an invaluable resource for aerospace engineering students and practitioners alike who need an in depth understanding of the equations they use Dr Jean Albert Kechichian The Aerospace Corporation Retired Today we look at perturbations through the lens of the modern computer But knowing the why and the how is equally important In this well organized and thorough compendium of equations and derivations the authors bring some of the relevant gems from the past back into the contemporary literature Dr David A Vallado Senior Research Astrodynamicist COMSPOC The book presentation is with the thoroughness that one always sees with these authors Their theoretical development is followed with a set of Earth orbiting and Solar System examples demonstrating the application of Lagrange's planetary equations for systems with both conservative and nonconservative forces some of which are not seen in orbital mechanics books Prof Kyle T Alfriend University Distinguished Professor Texas A M University

Grid-based Nonlinear Estimation and Its Applications Bin Jia, Ming Xin, 2019-04-25 Grid based Nonlinear Estimation and its Applications presents new Bayesian nonlinear estimation techniques developed in the last two decades Grid based estimation techniques are based on efficient and precise numerical integration rules to improve performance of the traditional Kalman filtering based estimation for nonlinear and uncertainty dynamic systems The unscented Kalman filter Gauss Hermite quadrature filter cubature Kalman filter sparse grid quadrature filter and many other numerical grid based filtering techniques have been introduced and compared in this book Theoretical analysis and numerical simulations are provided to show the relationships and distinct features of different estimation techniques To assist the exposition of the filtering concept

preliminary mathematical review is provided. In addition, rather than merely considering the single sensor estimation, multiple sensor estimation including the centralized and decentralized estimation is included. Different decentralized estimation strategies including consensus diffusion and covariance intersection are investigated. Diverse engineering applications such as uncertainty propagation, target tracking, guidance, navigation, and control are presented to illustrate the performance of different grid-based estimation techniques.

**Introduction to GNSS Geodesy** Clement A. Ogaja, 2022-05-24. Introduction to GNSS Geodesy is a concise reference for beginners and experts in GNSS-based satellite geodesy. It covers all of the important concepts in almost a third of the space of the other GNSS books. The book begins with a case study in Augmented Reality to set the stage for what is to come and then moves on to the key elements of GNSS geodesy that make accurate and precise geopositioning possible. For example, it is important to understand the geodetic reference systems and the associated GNSS data processing strategies that enable both accurate and high-precision geopositioning. Chapter 2 gives an overview of GNSS constellations and signals, highlighting important characteristics. Chapter 3 then introduces reference systems in geodesy, covering such topics as time systems, geodetic datums, coordinate systems, coordinate conversions, and transformations, and the International Terrestrial Reference Frame. This lays the framework for the rest of the book. Chapters 4 and 5 dig deep into the mathematical formulation of GNSS parameter estimation and observation models. All the concepts are presented clearly and concisely, with diagrams to assist reader comprehension. Chapter 6 describes Continuously Operating Reference Station (CORS) networks and their role in geodesy and the definition of reference frames. Various global and regional CORS networks are presented in this section. The chapter also covers GNSS data and common formats such as RINEX and RTCM. Chapter 7 introduces the whole cycle of GNSS data processing, including preprocessing, ambiguity fixing, and solution reprocessing methods as commonly used in both epoch solutions and time series data. The book concludes with appendices on orbit modelling, GNSS linear combinations, application examples, and an example linear model.

**Guidance, Control and Docking for CubeSat-based Active Debris Removal** Mohamed Khalil Ben-Larbi, 2023-08-07. While a paradigm shift in space industry has already started, involving mass production of higher standardized large distributed systems such as constellations, there are no effective solutions existing for the mass removal of satellites. Many indicators point to a further increase in the space traffic in Earth orbit in the near future, which could imply new dynamics in the evolution of the space debris environment. Even in case of diligent compliance with the Inter-Agency Space Debris Coordination Committee (IADC) mitigation guidelines, the growth in space traffic complicates its management and drastically increases the probability of accidents and system failures. NASA scientist Donald J. Kessler proposed a scenario in which the density of objects in low Earth orbit is high enough that collisions between objects could cause a cascade that renders space unusable for many generations. Therefore, a reliable and affordable capability of removing or servicing non-functional objects is essential to guarantee sustainable access to Earth orbit. Recently, the CubeSat design standard introduced a new class of cost-efficient

small spacecraft and thereby offers a potential solution to the active debris removal ADR problem The development of a novel CubeSat compatible ADR technology has significant advantages such as the use of commercial off the shelf parts reduced launch cost and reduced design efforts This thesis presents in the frame of an ADR mission an approach to advanced rendezvous and docking with non cooperative targets via CubeSat It covers the design process of simulation systems used for verification purposes the ideation and implementation of novel guidance control and docking techniques as well as their verification and evaluation The outcome of this research is a series of validated software tools processes technical devices and algorithms for automated approach and docking that have been tested in simulation and with prototype hardware

**Remote Sensing by Satellite Gravimetry** Thomas Gruber,Annette Eicker,Frank Flechtner,2021-01-19 Over the last two decades satellite gravimetry has become a new remote sensing technique that provides a detailed global picture of the physical structure of the Earth With the CHAMP GRACE GOCE and GRACE Follow On missions mass distribution and mass transport in the Earth system can be systematically observed and monitored from space A wide range of Earth science disciplines benefit from these data enabling improvements in applied models providing new insights into Earth system processes e g monitoring the global water cycle ice sheet and glacier melting or sea level rise or establishing new operational services Long time series of mass transport data are needed to disentangle anthropogenic and natural sources of climate change impacts on the Earth system In order to secure sustained observations on a long term basis space agencies and the Earth science community are currently planning future satellite gravimetry mission concepts to enable higher accuracy and better spatial and temporal resolution This Special Issue provides examples of recent improvements in gravity observation techniques and data processing and analysis applications in the fields of hydrology glaciology and solid Earth based on satellite gravimetry data as well as concepts of future satellite constellations for monitoring mass transport in the Earth system

*Engineering Satellite-Based Navigation and Timing* John W. Betz,2015-12-01 This book describes the design and performance analysis of satnav systems signals and receivers with a general approach that applies to all satnav systems and signals in use or under development It also provides succinct descriptions and comparisons of each satnav system Clearly structured and comprehensive depiction of engineering satellite based navigation and timing systems signals and receivers GPS as well as all new and modernized systems SBAS GLONASS Galileo BeiDou QZSS IRNSS and signals being developed and fielded Theoretical and applied review questions which can be used for homework or to obtain deeper insights into the material Extensive equations describing techniques and their performance illustrated by MATLAB plots New results novel insights and innovative descriptions for key approaches and results in systems engineering and receiver design If you are an instructor and adopted this book for your course please email [ieeeproposals@wiley.com](mailto:ieeeproposals@wiley.com) to get access to the instructor files for this book

**New Trends and Challenges in Optimization Theory Applied to Space Engineering** Piermarco Cannarsa,Alessandra Celletti,Giorgio Fasano,Leonardo Mazzini,Mauro Pontani,Emmanuel Trélat,2025-08-30 The book

consists of the proceedings of the workshop New Trends and Challenges in Optimization Theory Applied to Space Engineering held in L'Aquila Italy and organized by the Gran Sasso Science Institute GSSI on December 13-15, 2023. The main purpose of the book is to provide an overview of the most important current topics concerning optimal control in space. Optimal control theory is an exciting research area where both new theoretical approaches and application problems come into play. The New Trends and Challenges in Optimization Theory Applied to Space Engineering conference brought together influential academic researchers and experts from industry and government to build bridges between their respective groups. The topics of the conference panels are selected to include the most advanced areas of interest for space applications. In line with the mission of the Gran Sasso Tech Foundation, interdisciplinary dialogue is promoted between the sciences and different experts are encouraged to work together to identify new problems and generate new solutions. Covering a wide range of space-related topics and challenges, this conference aims to lay the foundation for a long-term collaboration between different groups of experts. A broad overview of control theory applications in space is presented, highlighting the most recent aspects both from a theoretical and practical point of view, in particular on the following topics: manifold dynamics, trajectory design and related control aspects, AI techniques in guidance control problems and space missions, optimization techniques for constellations with applications to space operations, multi-stage control problems for launch and landing problems, optimal control problems in the presence of uncertain parameters, improved sufficient and necessary conditions in optimal control problems for space problems. New methods, specific mathematical models, ad hoc algorithms and heuristics, innovative mission scenarios and advances in classical control theory are presented.

Fault Tolerant Attitude Estimation for Small Satellites

Chingiz Hajiyeu, Halil Ersin Soken, 2020-12-22. Small satellites use commercial off-the-shelf sensors and actuators for attitude determination and control (ADC) to reduce the cost. These sensors and actuators are usually not as robust as the available more expensive space-proven equipment. As a result, the ADC system of small satellites is more vulnerable to any fault compared to a system for larger competitors. This book aims to present useful solutions for fault tolerance in ADC systems of small satellites. The contents of the book can be divided into two categories: fault-tolerant attitude filtering algorithms for small satellites and sensor calibration methods to compensate the sensor errors. MATLAB will be used to demonstrate simulations. Presents fault-tolerant attitude estimation algorithms for small satellites with an emphasis on algorithms' practicability and applicability. Incorporates fundamental knowledge about the attitude determination methods at large. Discusses comprehensive information about attitude sensors for small satellites. Reviews calibration algorithms for small satellite magnetometers with simulated examples. Supports theory with MATLAB simulation results which can be easily understood by individuals without a comprehensive background in this field. Covers up-to-date discussions for small satellite attitude systems design. Dr. Chingiz Hajiyeu is a professor at the Faculty of Aeronautics and Astronautics, Istanbul Technical University, Istanbul, Turkey. Dr. Halil Ersin Soken is an assistant professor at the Aerospace Engineering Department, Middle

East Technical University Ankara Turkey      *Space Vehicle Maneuvering, Propulsion, Dynamics and Control* Ranjan Vepa, 2024-09-27 This textbook introduces space vehicle maneuvering propulsion dynamics and control and discusses the space environment and its influence on the spacecraft propulsion system This is followed by an in depth description of Keplerian celestial mechanics co planar and non planar orbital transfers involving both impulsive and continuous manoeuvres and perturbation effects that characterize the real non Keplerian nature of orbital motion Dr Vepa then explains the use of restricted two body and three body dynamics as descriptors of spacecraft motion the limitations of these approach in terms of orbital perturbations and an understanding of the physical source and influence of these perturbations and principles of the optimal synthesis of trajectories Featuring many exercises design case studies and extensive use of MATLAB SIMULINK and MATLAB analytical tools the book is ideal for graduate students post graduate students researchers as well professionals in the industry      Re-entry Systems Erwin Mooij, 2024-12-25 This book explains and describes re entry systems for both the Earth and other planets It provides sufficient information for readers to perform entry mission analysis for different bodies in the Solar System Not only does it discuss re entry flight mechanics but also addresses relevant subsystems and fields enabling readers to put the information into perspective The book begins with a complete description of planetary environments including atmosphere gravity fields and the shape of the primary body After a detailed discussion of planar flight mechanics it then moves on to discuss guidance navigation and control entry descent and landing systems as well as thermal protection systems It uses examples throughout the text enabling the theory to be linked to practical applications Ideal for those wanting an updated thorough discussion of re entry systems this book is suitable for students and researchers

**Orbital Mechanics for Engineering Students** Howard D. Curtis, 2009-10-26 *Orbital Mechanics for Engineering Students* Second Edition provides an introduction to the basic concepts of space mechanics These include vector kinematics in three dimensions Newton s laws of motion and gravitation relative motion the vector based solution of the classical two body problem derivation of Kepler s equations orbits in three dimensions preliminary orbit determination and orbital maneuvers The book also covers relative motion and the two impulse rendezvous problem interplanetary mission design using patched conics rigid body dynamics used to characterize the attitude of a space vehicle satellite attitude dynamics and the characteristics and design of multi stage launch vehicles Each chapter begins with an outline of key concepts and concludes with problems that are based on the material covered This text is written for undergraduates who are studying orbital mechanics for the first time and have completed courses in physics dynamics and mathematics including differential equations and applied linear algebra Graduate students researchers and experienced practitioners will also find useful review materials in the book NEW Reorganized and improved discussions of coordinate systems new discussion on perturbations and quarternions NEW Increased coverage of attitude dynamics including new Matlab algorithms and examples in chapter 10 New examples and homework problems      *Space Flight Dynamics* Craig A. Kluever, 2018-03-02



Thorough coverage of space flight topics with self contained chapters serving a variety of courses in orbital mechanics spacecraft dynamics and astronautics This concise yet comprehensive book on space flight dynamics addresses all phases of a space mission getting to space launch trajectories satellite motion in space orbital motion orbit transfers attitude dynamics and returning from space entry flight mechanics It focuses on orbital mechanics with emphasis on two body motion orbit determination and orbital maneuvers with applications in Earth centered missions and interplanetary missions Space Flight Dynamics presents wide ranging information on a host of topics not always covered in competing books It discusses relative motion entry flight mechanics low thrust transfers rocket propulsion fundamentals attitude dynamics and attitude control The book is filled with illustrated concepts and real world examples drawn from the space industry Additionally the book includes a computational toolbox composed of MATLAB M files for performing space mission analysis Key features Provides practical real world examples illustrating key concepts throughout the book Accompanied by a website containing MATLAB M files for conducting space mission analysis Presents numerous space flight topics absent in competing titles Space Flight Dynamics is a welcome addition to the field ideally suited for upper level undergraduate and graduate students studying aerospace engineering

**Spacecraft Dynamics and Control** Enrico Canuto, Carlo Novara, Donato Carlucci, Carlos Perez-Montenegro, Luca Massotti, 2018-03-08 Spacecraft Dynamics and Control The Embedded Model Control Approach provides a uniform and systematic way of approaching space engineering control problems from the standpoint of model based control using state space equations as the key paradigm for simulation design and implementation The book introduces the Embedded Model Control methodology for the design and implementation of attitude and orbit control systems The logic architecture is organized around the embedded model of the spacecraft and its surrounding environment The model is compelled to include disturbance dynamics as a repository of the uncertainty that the control law must reject to meet attitude and orbit requirements within the uncertainty class The source of the real time uncertainty estimation prediction is the model error signal as it encodes the residual discrepancies between spacecraft measurements and model output The embedded model and the uncertainty estimation feedback noise estimator in the book constitute the state predictor feeding the control law Asymptotic pole placement exploiting the asymptotes of closed loop transfer functions is the way to design and tune feedback loops around the embedded model state predictor control law reference generator The design versus the uncertainty class is driven by analytic stability and performance inequalities The method is applied to several attitude and orbit control problems The book begins with an extensive introduction to attitude geometry and algebra and ends with the core themes state space dynamics and Embedded Model Control Fundamentals of orbit attitude and environment dynamics are treated giving emphasis to state space formulation disturbance dynamics state feedback and prediction closed loop stability Sensors and actuators are treated giving emphasis to their dynamics and modelling of measurement errors Numerical tables are included and their data employed for numerical simulations Orbit and attitude

control problems of the European GOCE mission are the inspiration of numerical exercises and simulations The suite of the attitude control modes of a GOCE like mission is designed and simulated around the so called mission state predictor Solved and unsolved exercises are included within the text and not separated at the end of chapters for better understanding training and application Simulated results and their graphical plots are developed through MATLAB Simulink code

**Satellite Communications Network Design and Analysis** Kenneth Y. Jo, 2011 This authoritative book provides a thorough understanding of the fundamental concepts of satellite communications SATCOM network design and performance assessments You find discussions on a wide class of SATCOM networks using satellites as core components as well as coverage key applications in the field This in depth resource presents a broad range of critical topics from geosynchronous Earth orbiting GEO satellites and direct broadcast satellite systems to low Earth orbiting LEO satellites radio standards and protocols This invaluable reference explains the many specific uses of satellite networks including small terminal wireless and mobile communications systems Moreover this book presents advanced topics such as satellite RF link analyses optimum transponder loading on board processing antenna characteristics protected systems information assurance and spread spectrums You are introduced to current and future SATCOM systems and find details on their performance supportabilities This cutting edge book also presents trends in multimedia satellite applications and IP services over satellites

**Contributions to on-board navigation on 1U CubeSats** Weiß, Sascha, 2022-04-07 This thesis investigates the use of GNSS receivers on 1U CubeSats using the example of BEESAT 4 and BEESAT 9 The integration of such a device on satellites enables highly precise time synchronization position acquisition and orbit determination and prediction The application fields that depend on an accurate attitude control and orbit determination system and can also be processed by CubeSats are highlighted Therefore the state of the art of GNSS receivers is described which are suitable for the use on satellites and could be integrated into 1U CubeSats Further on it is investigated which subsystems of a small satellite are particularly affected and what the special challenges are to realize a precise positioning with a GNSS receiver In addition some developments are presented that have significantly increased the performance of 1U CubeSats in recent years The system concept of BEESAT satellites is introduced and the evolution of the payload board including the use of the latest sensor technologies for attitude control is described It is shown how the verification of the satellite s subsystems was performed on the ground with the focus on testing and simulating the attitude control and the GNSS receiver The necessary integration steps the calibration and environmental test campaign are discussed Both satellites were successfully operated and the results of the on orbit experiments are presented It is shown how a three axis stabilized attitude control was first verified on BEESAT 4 and then a GNSS receiver was successfully operated on BEESAT 9 for more than one year In addition the inter satellite link between BEESAT 4 and BIROS will be analyzed since it is essential for the relative navigation of satellites The acquired navigation data was sent to the ground and the identification of BEESAT 9 was carried out using this data A

qualitative analysis of the orbital elements TLE of BEESAT 9 was performed systematically due to a daily operation of the GNSS receiver Furthermore it was investigated how a small GNSS antenna affects the received signal strength from GNSS satellites and whether this antenna or its amplifier degrades over time Additionally an orbit determination and propagation based on the navigation data could be performed and the results are evaluated The analyzed questions allow a statement about the continuous use of GNSS receivers on 1U CubeSats and if it is necessary to achieve the mission objectives Diese Arbeit untersucht den Einsatz von GNSS Empfängern auf 1U CubeSats am Beispiel von BEESAT 4 und BEESAT 9 Das Integrieren einer solchen Komponente auf Satelliten ermöglicht eine hochgenaue Zeitsynchronisation Positions und Orbitbestimmung sowie deren Vorhersage Es werden die Anwendungsfelder beleuchtet die auf ein akkurates Lageregelungs- und Orbitbestimmungssystem angewiesen sind und außerdem auch von CubeSats bearbeitet werden können Dazu wird der Stand der Technik von GNSS Empfängern beschrieben die für den Einsatz auf Satelliten geeignet sind und von ihren Eigenschaften auch auf 1U CubeSats integriert werden können Weitergehend wird untersucht welche Subsysteme eines Kleinstsatelliten besonders betroffen sind und was die speziellen Herausforderungen sind um eine präzise Positionsbestimmung mithilfe eines GNSS Empfängers zu realisieren Dazu werden auch einige Entwicklungen vorgestellt die in den letzten Jahren die Leistungsfähigkeit von 1U CubeSats signifikant erhöht haben Das Systemkonzept der BEESAT Satelliten wird eingeführt und die Evolution der Nutzlastplattform inklusive der Verwendung der jeweils neuesten Sensortechnologien für die Lageregelung beschrieben Es wird gezeigt wie die Verifikation der Subsysteme des Satelliten am Boden erfolgte wobei der Fokus auf dem Testen und Simulieren der Lageregelung und dem GNSS Empfänger liegt Dazu werden die notwendigen Integrationsschritte die Kalibrations und die Umwelttestkampagne diskutiert Beide Satelliten wurden erfolgreich betrieben und die Ergebnisse der on orbit Experimente werden vorgestellt Es wird gezeigt wie zunächst eine dreiaachsenstabilisierte Lageregelung auf BEESAT 4 verifiziert und anschließend auf BEESAT 9 über mehr als ein Jahr ein GNSS Empfänger erfolgreich betrieben wurde Zusätzlich wird der Intersatelliten Link zwischen BEESAT 4 und BIROS analysiert da dieser für die Relativnavigation von Satelliten essentiell ist Die akquirierten Navigationsdaten wurden zum Boden gesendet und die Identifizierung von BEESAT 9 erfolgte mithilfe dieser Daten Eine qualitative Analyse der Orbitalelemente TLE von BEESAT 9 konnte systematisch durchgeführt werden durch einen täglichen Einsatz des GNSS Empfängers Weiterhin wurde erforscht wie sich eine kleine GNSS Antenne auf die empfangenen Signale der GNSS Satelliten auswirkt und ob diese Antenne oder ihr Verstärker mit der Zeit degradieren Zusätzlich konnte eine Orbitbestimmung und propagation auf Basis der Navigationsdaten durchgeführt und die Ergebnisse ausgewertet werden Die analysierten Fragestellungen erlauben eine Aussage über den durchgängigen Einsatz von GNSS Empfängern auf 1U CubeSats und ob dieser notwendig ist um die Missionsziele zu erreichen

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