



Falcon Iii Application Programming Manual

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web coordinates of v the standard coordinates are v_3 are the b_1 b are assumed if no other basis is speci ed this means $v_3 e_1$

Let $\{b_1, b_2, \dots, b_n\}$ be a basis of $\mathbb{R}^n$ then the matrix S which contains the vectors b_k as column vectors is called the coordinate change matrix

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web and now that we know what D is we can now solve for A we can now solve for the transformation matrix with respect to the standard basis so to do that we have to figure out C and C^{-1} so C remember C is just the change of basis matrix and all that is is the basis vectors it's just a matrix with the basis vectors in the column

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web any vector v represented in B can be transformed to a representation in C as follows under the transformation of basis

notice that the superscript on the transformation matrix m and the subscript on the coordinate vector v are the same and seemingly cancel leaving the remaining subscript

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