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Properties of Quadratic Functions in Standard Form

HH
FUSE Algebra 2

Lesson and Examples

Guided Practice

Practice and Problem Solving

Properties of Quadratic Functions in Standard Form

Learn this?

Quadratic functions can be used to find the maximum speed of a speedboat. (See Example 1.)

Lesson Objective(s):

Define, identify, and graph quadratic functions.
Identify and use maximums and minimums of quadratic functions to solve problems.

You transformed quadratic functions previously, you saw that shifting the parent function across the y-axis

$$f(x) = x^2$$
$$g(x) = (-x)^2 = x^2$$



67



Professor Edward Burger

point (negative 4, negative 13). The axis of symmetry is a square negative 4. There you go. It couldn't be any easier.

- Define, identify, and graph quadratic functions.

Key Objectives

Lesson Tutorials

Identifying the Axis of Symmetry

Identify the axis of symmetry for the graph of $f(x) = 3x^2 + 4x^2 - 1$.

$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 7x^2 - 1$$

$$f(x) = 7x^2 - 1$$

$$f(x) = 7x^2 - 1$$

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$$f(x) = 7x^2 - 1$$

$$f(x) = 7x^2 - 1$$

Rewrite the function to find the value of h .

$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 3x^2 + 4x^2 - 1$$

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$$f(x) = 3x^2 + 4x^2 - 1$$

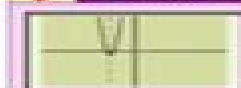
$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 3x^2 + 4x^2 - 1$$

$$f(x) = 3x^2 + 4x^2 - 1$$



Check Your Work



The **axis of symmetry** is the line through the vertex of a parabola that divides the parabola into two congruent halves.

shows that parabolas are symmetric curves. The **axis of symmetry** is the line through the vertex of a parabola that divides the parabola into two congruent halves.

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Kohei Arai



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web coordinates of v the standard coordinates are v_3 are the b_1 b are assumed if no other basis is specified this means $v = 3e_1 + 4e_2 + 4e_5 + 2e_6$ if $b = \{v_1, v_2, v_3\}$ is a basis of $\mathbb{R}^n$ then the matrix S which contains the vectors v_k as column vectors is called the coordinate change matrix

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web and now that we know what $\mathbf{D}$ is we can now solve for $\mathbf{A}$ we can now solve for the transformation matrix with respect to the standard basis so to do that we have to figure out $\mathbf{C}$ and $\mathbf{C}^{-1}$ so $\mathbf{C}$ remember $\mathbf{C}$ is just the change of basis matrix and all that is is the basis vectors it's just a matrix with the basis vectors in the column

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web a translation by a nonzero vector is not a linear map because linear maps must send the zero vector to the zero vector however translations are very useful in performing coordinate transformations i'll introduce the following terminology for the composite of a linear transformation and a translation definition let $\mathbf{A}$ be a real matrix

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web any vector $\mathbf{v}$ represented in $\mathbf{B}$ can be transformed to a representation in $\mathbf{C}$ as follows under the transformation of basis notice that the superscript on the transformation matrix $\mathbf{M}$ and the subscript on the coordinate vector $\mathbf{v}$ are the same and seemingly cancel leaving the remaining subscript

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