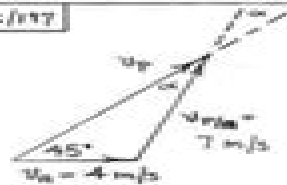


2/197

With  $\vec{r}$  being the path:

$$\vec{V}_p = \vec{V}_A + \vec{V}_{rel}$$

Law of sines:

$$\frac{\sin 45^\circ}{7} = \frac{\sin \alpha}{4}$$

$$\alpha = 23.8^\circ$$

2/198

w = wind  
B = boat

$$\vec{V}_w = \vec{V}_B + \vec{V}_{w/B}$$

$$\vec{V}_w = 6.5 \text{ knots}$$

Law of sines:

$$\frac{V_w}{\sin 35^\circ} = \frac{6.5}{\sin 25^\circ}$$

$$V_w = \frac{6.5(0.5736)}{0.4226} = 16.40 \text{ knots}$$



2/198

w = wind  
B = boat

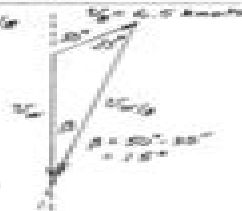
$$\vec{V}_w = \vec{V}_B + \vec{V}_{w/B}$$

$$\vec{V}_w = 6.5 \text{ knots}$$

Law of sines:

$$\frac{V_w}{\sin 35^\circ} = \frac{6.5}{\sin 25^\circ}$$

$$V_w = \frac{6.5(0.5736)}{0.4226} = 16.40 \text{ knots}$$



2/199

$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$

$$\vec{V}_{B/A} = \frac{15}{\sin 135^\circ}$$

$$\sin 135^\circ = \frac{15}{\sin \beta}$$

$$\text{where } \beta = 180 - 20 - 135 = 25^\circ$$

$$\vec{V}_{B/A} = \frac{0.7071/15}{0.4226} = 25.1 \text{ knots}$$

$$t = \frac{\text{Dist}}{\text{Vel}} = \frac{10}{25} = 0.399 \text{ hr}$$

$$\text{or } 23.9 \text{ min}$$

So collision would occur at 2:29 PM



2/200

$$\text{Drop: } V_b = \sqrt{2gh} = \sqrt{2(10)(6)} = 10.95 \text{ m/s}$$

$$\text{Car: } V_c = 100/3.6 = 27.8 \text{ m/s}$$

$$\vec{V}_{b/c} = \vec{V}_b - \vec{V}_c = -10.95\hat{j} - 27.8\hat{i} \text{ m/s}$$

$$\alpha = \tan^{-1} \frac{10.95}{27.8} = 21.3^\circ$$



$$40^\circ + \theta + \alpha = 90^\circ \Rightarrow \theta = 28.7^\circ \text{ below normal}$$

2/201

$$\vec{V}_A = \vec{V}_B + \vec{V}_{A/B}$$



$$\text{Law of sines: } \frac{16.67}{\sin 40^\circ} = \frac{V_A}{\sin 120^\circ}$$

$$V_A = 22.5 \text{ m/s or } V_A = 80.8 \text{ km/h}$$

$$V_{AB} = 16.67 \frac{\sin 20^\circ}{\sin 40^\circ} = 10.6, \quad \dot{\theta} = 0.887 \frac{\text{rad}}{\text{s}}$$



2/202

Let S = satellite, A = observer

$$\vec{V}_S = \vec{V}_A + \vec{V}_{S/A}, \quad \vec{V}_A = 400 \text{ km/h}$$

$$= 378 (\text{convert}) / (3600)$$

$$= 104.8 \text{ km/h (convert)}$$

$$\vec{V}_S = 27840 \text{ km/h (convert)}$$

$$\theta = \tan^{-1} \frac{104.8}{27840} = 0.43^\circ$$

Satellite appears to travel  $0.43^\circ$  west of north

2/203

$$\vec{V}_A = 60 \text{ km/h}, \quad \vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$



$$V_B = 20 \frac{\text{km}}{\text{h}}$$

$$V_{B/A}^2 = 40^2 + 20^2 - 2(40)(20)\cos 135^\circ$$

$$V_{B/A} = 129.6 \text{ km/h or } 36.0 \text{ m/s}$$

$$\frac{36.0}{\sin 135^\circ} = \frac{80/3.6}{\sin \beta}, \quad \beta = 25.9^\circ$$

$$r\dot{\theta} = V_{B/A} \cos \beta: 30\dot{\theta} = 36.0 \cos 25.9^\circ$$

$$\dot{\theta} = 0.1079 \text{ rad/s}$$

$$\dot{r} = -V_{B/A} \sin \beta: \dot{r} = -36.0 \sin 25.9^\circ$$

$$\dot{r} = -15.71 \text{ m/s}$$



# Meriam 6th Edition Solution

**Millard F. Beatty**



## **Meriam 6th Edition Solution:**

Engineering Applications of Dynamics Dean C. Karnopp, Donald L. Margolis, 2007-12-14 A GROUNDBREAKING TEXT THAT BRIDGES THE GAP BETWEEN THEORETICAL DYNAMICS AND INDUSTRY APPLICATIONS Designed to address the perceived failure of introductory dynamics courses to produce students capable of applying dynamic principles successfully both in subsequent courses and in practice *Engineering Applications of Dynamics* adopts a much needed practical approach designed to make the subject not only more relevant but more interesting as well Written by a highly respected team of authors the book is the first of its kind to tie dynamics theory directly to real world situations By touching on complex concepts only to the extent of illustrating their value in real world applications the authors provide students with a deeper understanding of dynamics in the engineering of mechanical systems Topics of interest include The formulation of equations in forms suitable for computer simulation Simulation examples of real engineering systems Applications to vehicle dynamics Lagrange's equations as an alternative formulation procedure Vibrations of lumped and distributed systems Three dimensional motion of rigid bodies with emphasis on gyroscopic effects Transfer functions for linearized dynamic systems Active control of dynamic systems A Solutions Manual with detailed solutions for all problems in this book is available at the Web site [www.wiley.com/college/karnopp](http://www.wiley.com/college/karnopp) *Principles of Vibration Analysis with Applications in Automotive Engineering* Ronald L. Huston, C. Q. Liu, 2011-01-10 This book written for practicing engineers designers researchers and students summarizes basic vibration theory and established methods for analyzing vibrations *Principles of Vibration Analysis* goes beyond most other texts on this subject as it integrates the advances of modern modal analysis experimental testing and numerical analysis with fundamental theory No other book brings all of these topics together under one cover The authors have compiled these topics compared them and provided experience with practical application This must have book is a comprehensive resource that the practitioner will reference time and again Essentials of Dynamics and Vibrations John Billingsley, 2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler's equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects

VFLOW2D Walter P. Wolfe, James H. Strickland, Gregory F. Homicz, Albert A. Gossler, 2000 A numerical flow model is developed to simulate two dimensional fluid flow past immersed elastically supported tube arrays This work is motivated by

the objective of predicting forces and motion associated with both deep water drilling and production risers in the oil industry This work has other engineering applications including simulation of flow past tubular heat exchangers or submarine towed sensor arrays and the flow about parachute ribbons In the present work a vortex method is used for solving the unsteady flow field This method demonstrates inherent advantages over more conventional grid based computational fluid dynamics The vortex method is non iterative does not require artificial viscosity for stability displays minimal numerical diffusion can easily treat moving boundaries and allows a greatly reduced computational domain since vorticity occupies only a small fraction of the fluid volume A gridless approach is used in the flow sufficiently distant from surfaces A Lagrangian remap scheme is used near surfaces to calculate diffusion and convection of vorticity A fast multipole technique is utilized for efficient calculation of velocity from the vorticity field The ability of the method to correctly predict lift and drag forces on simple stationary geometries over a broad range of Reynolds numbers is presented

### **Principles of Engineering**

**Mechanics** Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text A logical and systematic building of well known kinematic concepts theorems and formulas illustrated by examples and problems is presented offering insights into both fundamentals and applications Problems amplify the material and pave the way for advanced study of topics in mechanical design analysis advanced kinematics of mechanisms and analytical dynamics mechanical vibrations and controls and continuum mechanics of solids and fluids Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics engineering science engineering physics applied mathematics materials science and mechanical aerospace and civil engineering Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics

*Essential Mechanics - Statics and Strength of Materials with MATLAB and Octave* P. Venkataraman, 2020-01-07 Essential Mechanics Statics and Strength of Materials with MATLAB and Octave combines two core engineering science courses Statics and Strength of Materials in mechanical civil and aerospace engineering It weaves together various essential topics from Statics and Strength of Materials to allow discussing structural design from the very beginning The traditional content of these courses are reordered to make it convenient to cover rigid body equilibrium and extend it to deformable body mechanics The

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