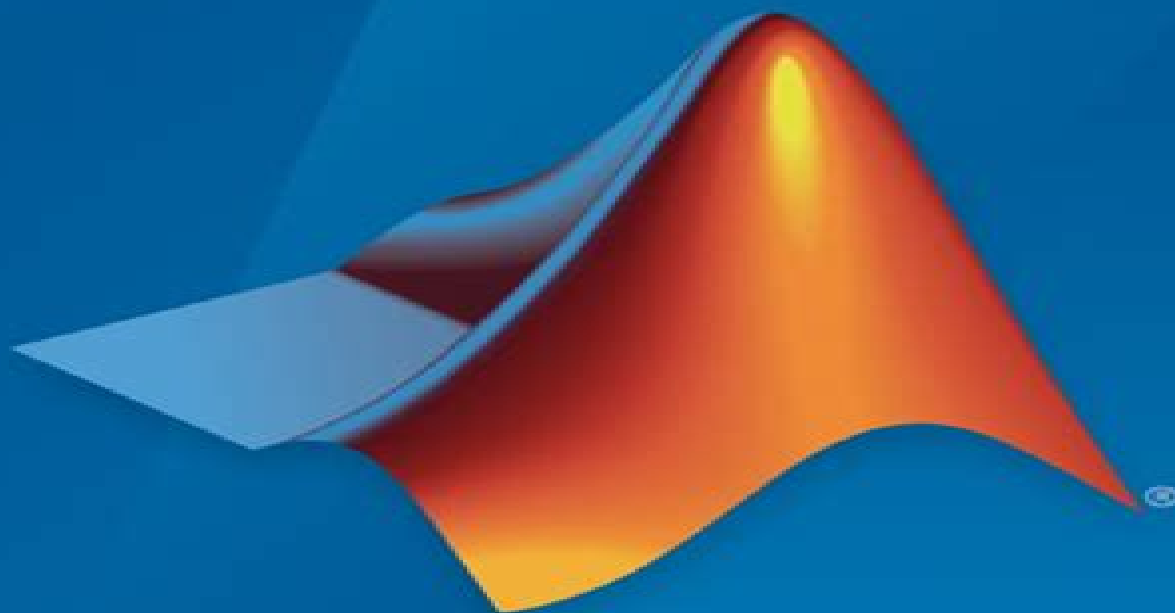


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MATLAB, 2004 **Switched Reluctance Motor Drives** Berker Bilgin, James Weisheng Jiang, Ali Emadi, 2019-04-29

Electric motors are the largest consumer of electric energy and they play a critical role in the growing market for electrification. Due to their simple construction, switched reluctance motors (SRMs) are exceptionally attractive for the industry to respond to the increasing demand for high efficiency, high performance and low cost electric motors with a more secure supply chain. *Switched Reluctance Motor Drives: Fundamentals to Applications* is a comprehensive textbook covering the major aspects of switched reluctance motor drives. It provides an overview of the use of electric motors in the industrial, residential, commercial and transportation sectors. It explains the theory behind the operation of switched reluctance motors and provides models to analyze them. The book extensively concentrates on the fundamentals and applications of SRM design and covers various design details such as materials, mechanical construction and controls. Acoustic noise and vibration is the most well known issue in switched reluctance motors, but this can be reduced significantly through a multidisciplinary approach. These methodologies are explained in two chapters of the book. The first covers the fundamentals of acoustic noise and vibration, so readers have the necessary tools to analyze the problems and explains the surface waves, spring mass models, forcing harmonics and mode shapes that are utilized in modeling and analyzing acoustic noise and vibration. The second applies these fundamentals to switched reluctance motors and provides examples for determining the sources of any acoustic noise in switched reluctance motors. In the final chapter, two SRM designs are presented and proposed as replacements for permanent magnet machines in a residential HVAC application and a hybrid electric propulsion application. It also shows a high power and compact converter design for SRM drives. **Features:** Comprehensive coverage of switched reluctance motor drives from fundamental principles to design, operation and applications. A specific chapter on electric motor usage in industrial, residential, commercial and transportation applications to address the benefits of switched reluctance machines. Two chapters address acoustic noise and vibration in detail. Numerous illustrations and practical examples on the design, modeling and analysis of switched reluctance motor drives. Examples of switched reluctance motor and drive design.

System Simulation Techniques with MATLAB and Simulink Dingyi Xue, Yang Chen, 2013-09-16. *System Simulation Techniques with MATLAB and Simulink* comprehensively explains how to use MATLAB and Simulink to perform dynamic systems simulation tasks for engineering and non engineering applications. This book begins with covering the fundamentals of MATLAB programming and applications and the solutions to different mathematical problems in simulation. The fundamentals of Simulink modelling and simulation are then presented followed by coverage of intermediate level modelling skills and more advanced techniques in Simulink modelling and applications. Finally, the modelling and simulation of engineering and non engineering systems are presented. The areas covered include electrical/electronic systems, mechanical systems, pharmacokinetic systems, video and image processing systems and discrete event systems. Hardware in

the loop simulation and real time application are also discussed Key features Progressive building of simulation skills using Simulink from basics through to advanced levels with illustrations and examples Wide coverage of simulation topics of applications from engineering to non engineering systems Dedicated chapter on hardware in the loop simulation and real time control End of chapter exercises A companion website hosting a solution manual and powerpoint slides System Simulation Techniques with MATLAB and Simulink is a suitable textbook for senior undergraduate postgraduate courses covering modelling and simulation and is also an ideal reference for researchers and practitioners in industry

MATLAB for Medical Physics Jidi Sun, 2023-01-23 This book gives the practical introduction for medical physics students and clinical physicists to learn MATLAB programming The first part of the book explains the MATLAB software layout and ways to get help followed by the demonstration of the fundamentals of MATLAB programming through over 100 examples The second part of the book features eighteen real life clinical scenarios and projects and twenty three scenario expansions The scenarios cover many of the common clinical medical physics areas including DICOM file manipulation film dosimetry brachytherapy application linear accelerator and CT quality assurance and their automations medical image processing and analysis All scenarios include the step by step solution as a guidance for readers to learn MATLAB by practicing The data files e g DICOM used for all clinical scenarios are provided

Spectrum Sharing Constantinos B. Papadias, Tharmalingam Ratnarajah, Dirk T. M. Slock, 2020-04-06 Combines the latest trends in spectrum sharing both from a research and a standards regulation experimental standpoint Written by noted professionals from academia industry and research labs this unique book provides a comprehensive treatment of the principles and architectures for spectrum sharing in order to help with the existing and future spectrum crunch issues It presents readers with the most current standardization trends including CEPT CEE eLSA CBRS MulteFire LTE Unlicensed LTE U LTE WLAN integration with Internet Protocol security tunnel LWIP and LTE Wi Fi aggregation LWA and offers substantial trials and experimental results as well as system level performance evaluation results The book also includes a chapter focusing on spectrum policy reinforcement and another on the economics of spectrum sharing Beginning with the historic form of cognitive radio Spectrum Sharing The Next Frontier in Wireless Networks continues with current standardized forms of spectrum sharing and reviews all of the technical ingredients that may arise in spectrum sharing approaches It also looks at policy and implementation aspects and ponders the future of the field White spaces and data base assisted spectrum sharing are discussed as well as the licensed shared access approach and cooperative communication techniques The book also covers reciprocity based beam forming techniques for spectrum sharing in MIMO networks resource allocation for shared spectrum networks large scale wireless spectrum monitoring and much more Contains all the latest standardization trends such as CEPT ECC eLSA CBRS MulteFire LTE Unlicensed LTE U LTE WLAN integration with Internet Protocol security tunnel LWIP and LTE Wi Fi aggregation LWA Presents a number of emerging technologies for future spectrum sharing collaborative sensing cooperative communication

reciprocity based beamforming etc as well as novel spectrum sharing paradigms e g in full duplex and radar systems Includes substantial trials and experimental results as well as system level performance evaluation results Contains a dedicated chapter on spectrum policy reinforcement and one on the economics of spectrum sharing Edited by experts in the field and featuring contributions by respected professionals in the field world wide Spectrum Sharing The Next Frontier in Wireless Networks is highly recommended for graduate students and researchers working in the areas of wireless communications and signal processing engineering It would also benefit radio communications engineers and practitioners

Motion planning and feedback control techniques with applications to long tractor-trailer vehicles Oskar

Ljungqvist, 2020-04-20 During the last decades improved sensor and hardware technologies as well as new methods and algorithms have made self driving vehicles a realistic possibility in the near future At the same time there has been a growing demand within the transportation sector to increase efficiency and to reduce the environmental impact related to transportation of people and goods Therefore many leading automotive and technology companies have turned their attention towards developing advanced driver assistance systems and self driving vehicles Autonomous vehicles are expected to have their first big impact in closed environments such as mines harbors loading and offloading sites In such areas the legal requirements are less restrictive and the surrounding environment is more controlled and predictable compared to urban areas Expected positive outcomes include increased productivity and safety reduced emissions and the possibility to relieve the human from performing complex or dangerous tasks Within these sites tractor trailer vehicles are frequently used for transportation These vehicles are composed of several interconnected vehicle segments and are therefore large complex and unstable while reversing This thesis addresses the problem of designing efficient motion planning and feedback control techniques for such systems The contributions of this thesis are within the area of motion planning and feedback control for long tractor trailer combinations operating at low speeds in closed and unstructured environments It includes development of motion planning and feedback control frameworks structured design tools for guaranteeing closed loop stability and experimental validation of the proposed solutions through simulations lab and field experiments Even though the primary application in this work is tractor trailer vehicles many of the proposed approaches can with some adjustments also be used for other systems such as drones and ships The developed sampling based motion planning algorithms are based upon the probabilistic closed loop rapidly exploring random tree CL RRT algorithm and the deterministic lattice based motion planning algorithm It is also proposed to use numerical optimal control offline for precomputing libraries of optimized maneuvers as well as during online planning in the form of a warm started optimization step To follow the motion plan several predictive path following control approaches are proposed with different computational complexity and performance Common for these approaches are that they use a path following error model of the vehicle for future predictions and are tailored to operate in series with a motion planner that computes feasible paths The design strategies for the path following approaches include

linear quadratic LQ control and several advanced model predictive control MPC techniques to account for physical and sensing limitations To strengthen the practical value of the developed techniques several of the proposed approaches have been implemented and successfully demonstrated in field experiments on a full scale test platform To estimate the vehicle states needed for control a novel nonlinear observer is evaluated on the full scale test vehicle It is designed to only utilize information from sensors that are mounted on the tractor making the system independent of any sensor mounted on the trailer Under de senaste årtiondena har utvecklingen av sensor och hrdvaruteknik gått i en snabb takt samtidigt som nya metoder och algoritmer har introducerats Samtidigt ställs det stora krav på transportsektorn att öka effektiviteten och minska miljöpåverkan vid transporter av både människor och varor Som en följd av detta har många ledande fordonstillverkare och tekniska företag börjat satsa på att utveckla avancerade färdstyre-system och självkörande fordon Vår forskning inom autonoma fordon har under de senaste årtiondena kraftigt ökat då en rad tekniska problem förstärktes att lösas För att lösa dessa problem har stora genombrott i slutna miljöer såsom gruvor hamnar lastnings och lossningsplatser I sådana områden har lagstiftningen mindre betydelse jämfört med stadsområden och omgivningen är mer kontrollerad och förutsägbar Några av de förväntade positiva effekterna är ökad produktivitet och säkerhet minskade utsläpp och möjligheten att avlasta människor från att utföra svåra eller farliga uppgifter Inom dessa platser används ofta lastbilar med olika släpvagnskombinationer för att transportera material En sådan fordonskombination är uppbyggd av flera ihopkopplade moduler och är således utmanande att backa då systemet är instabilt Detta gör det svårt att utforma ramverk för att styra sådana system vid exempelvis autonom backning Självkörande fordon är mycket komplexa system som består av en rad olika komponenter vilka är designade för att lösa separata delproblem Två viktiga komponenter i ett självkörande fordon är dels trafikplaneringen som har i uppgift att planera hur fordonet ska röra sig för att på ett säkert sätt nå ett förordnat mål och dels den banföljande regulatorn vars uppgift är att se till att den planerade manövern faktiskt utförs i praktiken trots störningar och modellfel I denna avhandling presenteras flera olika algoritmer för att planera och utföra komplexa manövrer för lastbilar med olika typer av släpvagnskombinationer De presenterade algoritmerna är avsedda att användas som avancerade färdstyre-system eller som komponenter i ett helt autonomt system Vår omvärldsprimerade applikationen i denna avhandling är lastbilar med släpkan många av de föreslagna algoritmerna kan användas för en rad andra system såsom drönare och bilar Experimentell validering är viktigt för att motivera att en föreslagen algoritm är användbar i praktiken I denna avhandling har flera av de föreslagna planerings och reglerstrategierna implementerats på en småskalig testplattform och utvärderats i en kontrollerad labbmiljö Utöver detta har även flera av de föreslagna ramverken implementerats och utvärderats i ett experiment på en fullskalig testplattform som har utvecklats i samarbete med Scania CV Huvudsakligen utvärderas en ny metod för att skatta släpvagnens beteende genom att endast utnyttja information från sensorer monterade på lastbilen vilket gör det föreslagna ramverket oberoende av sensorer monterade på släpvagnen

Integrated Uncertainty in Knowledge Modelling and Decision Making Van-Nam Huynh, Masahiro Inuiguchi, Dang Hung Tran, Thierry

Denoeux,2018-03-09 This book constitutes the refereed proceedings of the 6th International Symposium on Integrated Uncertainty in Knowledge Modelling and Decision Making IUKM 2018 held in Hanoi Vietnam in March 2018 The 39 revised full papers presented in this book were carefully reviewed and selected from 76 initial submissions The papers are organized in topical sections on uncertainty management and decision support clustering and classification machine learning applications statistical methods and econometric applications

Smart Energy for Transportation and Health in a Smart City Chun Sing Lai,Loi Lei Lai,Qi Hong Lai,2022-11-21 Smart Energy for Transportation and Health in a Smart City A comprehensive review of the advances of smart cities smart energy transportation infrastructure and health Smart Energy for Transportation and Health in a Smart City offers an essential guide to the functions characteristics and domains of smart cities and the energy technology necessary to sustain them The authors noted experts on the topic include theoretical underpinnings practical information and potential benefits for the development of smart cities The book includes information on various financial models of energy storage the management of networked micro grids coordination of virtual energy storage systems reliability modeling and assessment of cyber space and the development of a vehicle to grid voltage support The authors review smart transportation elements such as advanced metering infrastructure for electric vehicle charging power system dispatching with plug in hybrid electric vehicles and best practices for low power wide area network technologies In addition the book explores smart health that is based on the Internet of Things and smart devices that can help improve patient care processes and decrease costs while maintaining quality This important resource Examines challenges and opportunities that arise with the development of smart cities Presents state of the art financial models of smart energy storage Clearly explores elements of a smart city based on the advancement of information and communication technology Contains a review of advances in smart health for smart cities Includes a variety of real life case studies that illustrate various components of a smart city Written for practicing engineers and engineering students Smart Energy for Transportation and Health in Smart Cities offers a practical guide to the various aspects that create a sustainable smart city

Signal Processing for Joint Radar Communications Kumar Vijay Mishra,M. R. Bhavani Shankar,Bjorn Ottersten,A. Lee Swindlehurst,2024-04-09 A one stop comprehensive source for the latest research in joint radar communications In *Signal Processing for Joint Radar Communications* a trio of eminent electrical engineers delivers a practical and informative contribution to the diffusion of newly developed joint radar communications JRC tools into the radar and communications communities and to illustrate recent successes in applying modern signal processing theories to core problems in JRC The book offers new results on algorithmic methods and applications of JRC in diverse areas including autonomous vehicles waveform design information theory privacy security beamforming estimation theory and sampling The distinguished editors bring together contributions from leading JRC researchers working in radar systems remote sensing electromagnetics optimization and signal processing The included resources provide an in depth mathematical treatment of relevant signal

processing tools and computational methods allowing readers to take full advantage of JRC systems Readers will also find Thorough introductions to joint radar communications theory and applications joint precoding and beamforming and communications based JRC Comprehensive explorations of JRC processing via matrix completion interference mitigation techniques and jamming and clutter in JRC Practical discussions of information theoretic aspects of JRC optimization aspects of JRC and JRC resource allocation In depth examinations of cognition and JRC automotive JRC and dual function radar communications Perfect for researchers and professionals in the fields of radar signal processing communications and electronic warfare Signal Processing for Joint Radar Communications will also earn a place in the libraries of engineers working in the defense aerospace and automotive industries **GeoVadis** Ashish Juneja, Anil Joseph, Dasaka S.

Murty, 2025-09-16 This book contains a prolific compilation of research on geotechnical engineering presented at the First Geotech Asia International Conference GAIC 2025 The papers reflect dynamic engagement of researchers engineers and professionals from all over Asia to offer insights into ongoing developments and applied problem solving This publication brings together contributions across 19 technical themes including cold region geotechnics deep excavations earthquake engineering foundation systems and underground construction It also delves into artificial intelligence and machine learning applications environmental and transportation geotechnics site characterisation slope stability embankments and dams and ground improvement techniques It is intended for academics practising engineers consultants contractors industry professionals government authorities and students involved in geotechnical research education and design and implementation The Open Access version of this book available at <http://www.taylorfrancis.com> has been made available under a Creative Commons Attribution Non Commercial No Derivatives CC BY NC ND 4.0 license

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