

Xiaojin Zhu · Andrew B. Goldberg

Introduction to Semi-Supervised Learning

Introduction To Semi Supervised Learning Andrew Goldberg

Ioannis S. Triantafyllou, Mangey Ram

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Introduction to Semi-supervised Learning Xiaojin Zhu, Andrew B. Goldberg, 2009 Semi supervised learning is a learning paradigm concerned with the study of how computers and natural systems such as humans learn in the presence of both labeled and unlabeled data Traditionally learning has been studied either in the unsupervised paradigm e g clustering outlier detection where all the data are unlabeled or in the supervised paradigm e g classification regression where all the data are labeled The goal of semi supervised learning is to understand how combining labeled and unlabeled data may change the learning behavior and design algorithms that take advantage of such a combination Semi supervised learning is of great interest in machine learning and data mining because it can use readily available unlabeled data to improve supervised learning tasks when the labeled data are scarce or expensive Semi supervised learning also shows potential as a quantitative tool to understand human category learning where most of the input is self evidently unlabeled In this introductory book we present some popular semi supervised learning models including self training mixture models co training and multiview learning graph based methods and semi supervised support vector machines For each model we discuss its basic mathematical formulation The success of semi supervised learning depends critically on some underlying assumptions We emphasize the assumptions made by each model and give counterexamples when appropriate to demonstrate the limitations of the different models In addition we discuss semi supervised learning for cognitive psychology Finally we give a computational learning theoretic perspective on semi supervised learning and we conclude the book with a brief discussion of open questions in the field

Table of Contents Introduction to Statistical Machine Learning Overview of Semi Supervised Learning Mixture Models and EM Co Training Graph Based Semi Supervised Learning Semi Supervised Support Vector Machines Human Semi Supervised Learning Theory and Outlook

Introduction to Semi-Supervised Learning Xiaojin Zhu, Andrew. B Goldberg, 2022-05-31 Semi supervised learning is a learning paradigm concerned with the study of how computers and natural systems such as humans learn in the presence of both labeled and unlabeled data Traditionally learning has been studied either in the unsupervised paradigm e g clustering outlier detection where all the data are unlabeled or in the supervised paradigm e g classification regression where all the data are labeled The goal of semi supervised learning is to understand how combining labeled and unlabeled data may change the learning behavior and design algorithms that take advantage of such a combination Semi supervised learning is of great interest in machine learning and data mining because it can use readily available unlabeled data to improve supervised learning tasks when the labeled data are scarce or expensive Semi supervised learning also shows potential as a quantitative tool to understand human category learning where most of the input is self evidently unlabeled In this introductory book we present some popular semi supervised learning models including self training mixture models co training and multiview learning graph based methods and semi supervised support vector machines For each model we discuss its basic mathematical formulation

The success of semi supervised learning depends critically on some underlying assumptions We emphasize the assumptions made by each model and give counterexamples when appropriate to demonstrate the limitations of the different models In addition we discuss semi supervised learning for cognitive psychology Finally we give a computational learning theoretic perspective on semi supervised learning and we conclude the book with a brief discussion of open questions in the field

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Active Learning Burr Settles, 2022-05-31 The key idea behind active learning is that a machine learning algorithm can perform better with less training if it is allowed to choose the data from which it learns An active learner may pose queries usually in the form of unlabeled data instances to be labeled by an oracle e.g a human annotator that already understands the nature of the problem This sort of approach is well motivated in many modern machine learning and data mining applications where unlabeled data may be abundant or easy to come by but training labels are difficult time consuming or expensive to obtain This book is a general introduction to active learning It outlines several scenarios in which queries might be formulated and details many query selection algorithms which have been organized into four broad categories or query selection frameworks We also touch on some of the theoretical foundations of active learning and conclude with an overview of the strengths and weaknesses of these approaches in practice including a summary of ongoing work to address these open challenges and opportunities

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Metric Learning Aurélien Muise, Amaury Yang, 2022-05-31 Similarity between objects plays an important role in both human cognitive processes and artificial systems for recognition and categorization How to appropriately measure such similarities for a given task is crucial to the performance of many machine learning pattern recognition and data mining methods This book is devoted to metric learning a set of techniques to automatically learn similarity and distance functions from data that has attracted a lot of interest in machine learning and related fields in the past ten years In this book we provide a thorough review of the metric learning literature that covers algorithms theory and applications for both numerical and structured data We first introduce relevant definitions and classic metric functions as well as examples of their use in machine learning and data mining We then review a wide range of metric learning algorithms starting with the simple setting of linear distance and similarity learning We show how one may scale up these methods to very large amounts of training data To go beyond the linear case we discuss methods that learn nonlinear metrics or multiple linear metrics throughout the feature space and review methods for more complex settings such as multi task and semi supervised learning Although most of the existing work has focused on numerical data we cover the literature on metric learning for structured data like strings trees graphs and time series In the more technical part of the book we present some

recent statistical frameworks for analyzing the generalization performance in metric learning and derive results for some of the algorithms presented earlier Finally we illustrate the relevance of metric learning in real world problems through a series of successful applications to computer vision bioinformatics and information retrieval Table of Contents Introduction Metrics Properties of Metric Learning Algorithms Linear Metric Learning Nonlinear and Local Metric Learning Metric Learning for Special Settings Metric Learning for Structured Data Generalization Guarantees for Metric Learning Applications Conclusion Bibliography Authors Biographies

Federated Learning Qiang Yang, Yang Liu, Yong Cheng, Yan Kang, Tianjian Chen, Han Yu, 2022-06-01 How is it possible to allow multiple data owners to collaboratively train and use a shared prediction model while keeping all the local training data private Traditional machine learning approaches need to combine all data at one location typically a data center which may very well violate the laws on user privacy and data confidentiality Today many parts of the world demand that technology companies treat user data carefully according to user privacy laws The European Union's General Data Protection Regulation GDPR is a prime example In this book we describe how federated machine learning addresses this problem with novel solutions combining distributed machine learning cryptography and security and incentive mechanism design based on economic principles and game theory We explain different types of privacy preserving machine learning solutions and their technological backgrounds and highlight some representative practical use cases We show how federated learning can become the foundation of next generation machine learning that caters to technological and societal needs for responsible AI development and application

Graph Representation Learning William L. Hamilton, 2022-06-01 Graph structured data is ubiquitous throughout the natural and social sciences from telecommunication networks to quantum chemistry Building relational inductive biases into deep learning architectures is crucial for creating systems that can learn reason and generalize from this kind of data Recent years have seen a surge in research on graph representation learning including techniques for deep graph embeddings generalizations of convolutional neural networks to graph structured data and neural message passing approaches inspired by belief propagation These advances in graph representation learning have led to new state of the art results in numerous domains including chemical synthesis 3D vision recommender systems question answering and social network analysis This book provides a synthesis and overview of graph representation learning It begins with a discussion of the goals of graph representation learning as well as key methodological foundations in graph theory and network analysis Following this the book introduces and reviews methods for learning node embeddings including random walk based methods and applications to knowledge graphs It then provides a technical synthesis and introduction to the highly successful graph neural network GNN formalism which has become a dominant and fast growing paradigm for deep learning with graph data The book concludes with a synthesis of recent advancements in deep generative models for graphs a nascent but quickly growing subset of graph representation learning

Algorithms for Reinforcement Learning Csaba Szepesvári, 2022-05-31 Reinforcement learning is a learning paradigm

concerned with learning to control a system so as to maximize a numerical performance measure that expresses a long term objective What distinguishes reinforcement learning from supervised learning is that only partial feedback is given to the learner about the learner s predictions Further the predictions may have long term effects through influencing the future state of the controlled system Thus time plays a special role The goal in reinforcement learning is to develop efficient learning algorithms as well as to understand the algorithms merits and limitations Reinforcement learning is of great interest because of the large number of practical applications that it can be used to address ranging from problems in artificial intelligence to operations research or control engineering In this book we focus on those algorithms of reinforcement learning that build on the powerful theory of dynamic programming We give a fairly comprehensive catalog of learning problems describe the core ideas note a large number of state of the art algorithms followed by the discussion of their theoretical properties and limitations Table of Contents Markov Decision Processes Value Prediction Problems Control For Further Exploration

Applying Reinforcement Learning on Real-World Data with Practical Examples in Python
Philip Osborne,Kajal Singh,Matthew E. Taylor,2022-05-20

Reinforcement learning is a powerful tool in artificial intelligence in which virtual or physical agents learn to optimize their decision making to achieve long term goals In some cases this machine learning approach can save programmers time outperform existing controllers reach super human performance and continually adapt to changing conditions It has shown human level performance on a number of tasks REF and the methodology for automation in robotics and self driving cars REF This book argues that these successes show reinforcement learning can be adopted successfully in many different situations including robot control stock trading supply chain optimization and plant control However reinforcement learning has traditionally been limited to applications in virtual environments or simulations in which the setup is already provided Furthermore experimentation may be completed for an almost limitless number of attempts risk free In many real life tasks applying reinforcement learning is not as simple as 1 data is not in the correct form for reinforcement learning 2 data is scarce and 3 automation has limitations in the real world Therefore this book is written to help academics domain specialists and data enthusiast alike to understand the basic principles of applying reinforcement learning to real world problems This is achieved by focusing on the process of taking practical examples and modeling standard data into the correct form required to then apply basic agents To further assist readers gain a deep and grounded understanding of the approaches the book shows hand calculated examples in full and then how this can be achieved in a more automated manner with code For decision makers who are interested in reinforcement learning as a solution but are not proficient the book includes simple non technical examples in the introduction and case studies section These provide context of what reinforcement learning offer but also the challenges and risks associated with applying it in practice Specifically these sections illustrate the differences between reinforcement learning and other machine learning approaches as well as how well known companies have found success using the

approach to their problems Robot Learning from Human Teachers Sonia Chernova, Andrea L. Thomaz, 2022-06-01

Learning from Demonstration LfD explores techniques for learning a task policy from examples provided by a human teacher. The field of LfD has grown into an extensive body of literature over the past 30 years with a wide variety of approaches for encoding human demonstrations and modeling skills and tasks. Additionally, we have recently seen a focus on gathering data from non expert human teachers i.e. domain experts but not robotics experts. In this book we provide an introduction to the field with a focus on the unique technical challenges associated with designing robots that learn from naive human teachers. We begin in the introduction with a unification of the various terminology seen in the literature as well as an outline of the design choices one has in designing an LfD system. Chapter 2 gives a brief survey of the psychology literature that provides insights from human social learning that are relevant to designing robotic social learners. Chapter 3 walks through an LfD interaction surveying the design choices one makes and state of the art approaches in prior work. First is the choice of input how the human teacher interacts with the robot to provide demonstrations. Next is the choice of modeling technique. Currently there is a dichotomy in the field between approaches that model low level motor skills and those that model high level tasks composed of primitive actions. We devote a chapter to each of these. Chapter 7 is devoted to interactive and active learning approaches that allow the robot to refine an existing task model. And finally Chapter 8 provides best practices for evaluation of LfD systems with a focus on how to approach experiments with human subjects in this domain.

Lifelong Machine Learning, Second Edition Zhiyuan Chen, Bing Liu, 2022-06-01

Lifelong Machine Learning Second Edition is an introduction to an advanced machine learning paradigm that continuously learns by accumulating past knowledge that it then uses in future learning and problem solving. In contrast the current dominant machine learning paradigm learns in isolation given a training dataset it runs a machine learning algorithm on the dataset to produce a model that is then used in its intended application. It makes no attempt to retain the learned knowledge and use it in subsequent learning. Unlike this isolated system humans learn effectively with only a few examples precisely because our learning is very knowledge driven the knowledge learned in the past helps us learn new things with little data or effort. Lifelong learning aims to emulate this capability because without it an AI system cannot be considered truly intelligent. Research in lifelong learning has developed significantly in the relatively short time since the first edition of this book was published. The purpose of this second edition is to expand the definition of lifelong learning update the content of several chapters and add a new chapter about continual learning in deep neural networks which has been actively researched over the past two or three years. A few chapters have also been reorganized to make each of them more coherent for the reader. Moreover the authors want to propose a unified framework for the research area. Currently there are several research topics in machine learning that are closely related to lifelong learning most notably multi task learning transfer learning and meta learning because they also employ the idea of knowledge sharing and transfer. This book brings all these topics under one roof and discusses their similarities and

differences Its goal is to introduce this emerging machine learning paradigm and present a comprehensive survey and review of the important research results and latest ideas in the area This book is thus suitable for students researchers and practitioners who are interested in machine learning data mining natural language processing or pattern recognition Lecturers can readily use the book for courses in any of these related fields

Adversarial Machine Learning Yevgeniy Vorobeychik, Murat Kantarcioglu, 2022-05-31 The increasing abundance of large high quality datasets combined with significant technical advances over the last several decades have made machine learning into a major tool employed across a broad array of tasks including vision language finance and security However success has been accompanied with important new challenges many applications of machine learning are adversarial in nature Some are adversarial because they are safety critical such as autonomous driving An adversary in these applications can be a malicious party aimed at causing congestion or accidents or may even model unusual situations that expose vulnerabilities in the prediction engine Other applications are adversarial because their task and or the data they use are For example an important class of problems in security involves detection such as malware spam and intrusion detection The use of machine learning for detecting malicious entities creates an incentive among adversaries to evade detection by changing their behavior or the content of malicious objects they develop The field of adversarial machine learning has emerged to study vulnerabilities of machine learning approaches in adversarial settings and to develop techniques to make learning robust to adversarial manipulation This book provides a technical overview of this field After reviewing machine learning concepts and approaches as well as common use cases of these in adversarial settings we present a general categorization of attacks on machine learning We then address two major categories of attacks and associated defenses decision time attacks in which an adversary changes the nature of instances seen by a learned model at the time of prediction in order to cause errors and poisoning or training time attacks in which the actual training dataset is maliciously modified In our final chapter devoted to technical content we discuss recent techniques for attacks on deep learning as well as approaches for improving robustness of deep neural networks We conclude with a discussion of several important issues in the area of adversarial learning that in our view warrant further research Given the increasing interest in the area of adversarial machine learning we hope this book provides readers with the tools necessary to successfully engage in research and practice of machine learning in adversarial settings

Positive Unlabeled Learning Kristen Jaskie, Andreas Spanias, 2022-04-20 Machine learning and artificial intelligence AI are powerful tools that create predictive models extract information and help make complex decisions They do this by examining an enormous quantity of labeled training data to find patterns too complex for human observation However in many real world applications well labeled data can be difficult expensive or even impossible to obtain In some cases such as when identifying rare objects like new archeological sites or secret enemy military facilities in satellite images acquiring labels could require months of trained human observers at incredible expense Other times as when attempting to predict

disease infection during a pandemic such as COVID 19 reliable true labels may be nearly impossible to obtain early on due to lack of testing equipment or other factors In that scenario identifying even a small amount of truly negative data may be impossible due to the high false negative rate of available tests In such problems it is possible to label a small subset of data as belonging to the class of interest though it is impractical to manually label all data not of interest We are left with a small set of positive labeled data and a large set of unknown and unlabeled data Readers will explore this Positive and Unlabeled learning PU learning problem in depth The book rigorously defines the PU learning problem discusses several common assumptions that are frequently made about the problem and their implications and considers how to evaluate solutions for this problem before describing several of the most popular algorithms to solve this problem It explores several uses for PU learning including applications in biological medical business security and signal processing This book also provides high level summaries of several related learning problems such as one class classification anomaly detection and noisy learning and their relation to PU learning

Learning and Decision-Making from Rank Data Lirong Xia,2022-06-01 The ubiquitous challenge of learning and decision making from rank data arises in situations where intelligent systems collect preference and behavior data from humans learn from the data and then use the data to help humans make efficient effective and timely decisions Often such data are represented by rankings This book surveys some recent progress toward addressing the challenge from the considerations of statistics computation and socio economics We will cover classical statistical models for rank data including random utility models distance based models and mixture models We will discuss and compare classical and state of the art algorithms such as algorithms based on Minorize Majorization MM Expectation Maximization EM Generalized Method of Moments GMM rank breaking and tensor decomposition We will also introduce principled Bayesian preference elicitation frameworks for collecting rank data Finally we will examine socio economic aspects of statistically desirable decision making mechanisms such as Bayesian estimators This book can be useful in three ways 1 for theoreticians in statistics and machine learning to better understand the considerations and caveats of learning from rank data compared to learning from other types of data especially cardinal data 2 for practitioners to apply algorithms covered by the book for sampling learning and aggregation and 3 as a textbook for graduate students or advanced undergraduate students to learn about the field This book requires that the reader has basic knowledge in probability statistics and algorithms Knowledge in social choice would also help but is not required

Transfer Learning for Multiagent Reinforcement Learning Systems Felipe Leno da Silva,Anna Helena Reali Costa,2022-06-01 Learning to solve sequential decision making tasks is difficult Humans take years exploring the environment essentially in a random way until they are able to reason solve difficult tasks and collaborate with other humans towards a common goal Artificial Intelligent agents are like humans in this aspect Reinforcement Learning RL is a well known technique to train autonomous agents through interactions with the environment Unfortunately the learning process has a high sample complexity to infer an effective

actuation policy especially when multiple agents are simultaneously actuating in the environment However previous knowledge can be leveraged to accelerate learning and enable solving harder tasks In the same way humans build skills and reuse them by relating different tasks RL agents might reuse knowledge from previously solved tasks and from the exchange of knowledge with other agents in the environment In fact virtually all of the most challenging tasks currently solved by RL rely on embedded knowledge reuse techniques such as Imitation Learning Learning from Demonstration and Curriculum Learning This book surveys the literature on knowledge reuse in multiagent RL The authors define a unifying taxonomy of state of the art solutions for reusing knowledge providing a comprehensive discussion of recent progress in the area In this book readers will find a comprehensive discussion of the many ways in which knowledge can be reused in multiagent sequential decision making tasks as well as in which scenarios each of the approaches is more efficient The authors also provide their view of the current low hanging fruit developments of the area as well as the still open big questions that could result in breakthrough developments Finally the book provides resources to researchers who intend to join this area or leverage those techniques including a list of conferences journals and implementation tools This book will be useful for a wide audience and will hopefully promote new dialogues across communities and novel developments in the area

Learning with Support Vector Machines Colin Campbell, Yiming Ying, 2022-05-31 Support Vectors Machines have become a well established tool within machine learning They work well in practice and have now been used across a wide range of applications from recognizing hand written digits to face identification text categorisation bioinformatics and database marketing In this book we give an introductory overview of this subject We start with a simple Support Vector Machine for performing binary classification before considering multi class classification and learning in the presence of noise We show that this framework can be extended to many other scenarios such as prediction with real valued outputs novelty detection and the handling of complex output structures such as parse trees Finally we give an overview of the main types of kernels which are used in practice and how to learn and make predictions from multiple types of input data Table of Contents Support Vector Machines for Classification Kernel based Models Learning with Kernels *Statistical Modeling of Reliability Structures and Industrial Processes* Ioannis S. Triantafyllou, Mangey Ram, 2022-09-27 This reference text introduces advanced topics in the field of reliability engineering introduces statistical modeling techniques and probabilistic methods for diverse applications It comprehensively covers important topics including consecutive type reliability systems coherent structures multi scale statistical modeling the performance of reliability structures big data analytics prognostics and health management It covers real life applications including optimization of telecommunication networks complex infrared detecting systems oil pipeline systems and vacuum systems in accelerators or spacecraft relay stations The text will serve as an ideal reference book for graduate students and academic researchers in the fields of industrial engineering manufacturing science mathematics and statistics [Representing and Reasoning with Qualitative Preferences](#) Ganesh Ram

Santhanam, Samik Basu, Vasant Honavar, 2022-05-31 This book provides a tutorial introduction to modern techniques for representing and reasoning about qualitative preferences with respect to a set of alternatives. The syntax and semantics of several languages for representing preference languages including CP nets, TCP nets, CI nets, and CP theories are reviewed. Some key problems in reasoning about preferences are introduced, including determining whether one alternative is preferred to another or whether they are equivalent with respect to a given set of preferences. These tasks can be reduced to model checking in temporal logic. Specifically, an induced preference graph that represents a given set of preferences can be efficiently encoded using a Kripke Structure for Computational Tree Logic (CTL). One can translate preference queries with respect to a set of preferences into an equivalent set of formulae in CTL such that the CTL formula is satisfied whenever the preference query holds. This allows us to use a model checker to reason about preferences, i.e., answer preference queries and to obtain a justification as to why a preference query is satisfied or not with respect to a set of preferences. This book defines the notions of the equivalence of two sets of preferences, including what it means for one set of preferences to subsume another, and shows how to answer preferential equivalence and subsumption queries using model checking. Furthermore, this book demonstrates how to generate alternatives ordered by preference along with providing ways to deal with inconsistent preference specifications. A description of CRISNER, an open source software implementation of the model checking approach to qualitative preference reasoning in CP nets, TCP nets, and CP theories, is included, as well as examples illustrating its use.

Planning with Markov Decision Processes Mausam Natarajan, Andrey Kolobov, 2022-06-01 Markov Decision Processes (MDPs) are widely popular in Artificial Intelligence for modeling sequential decision making scenarios with probabilistic dynamics. They are the framework of choice when designing an intelligent agent that needs to act for long periods of time in an environment where its actions could have uncertain outcomes. MDPs are actively researched in two related subareas of AI: probabilistic planning and reinforcement learning. Probabilistic planning assumes known models for the agent's goals and domain dynamics and focuses on determining how the agent should behave to achieve its objectives. On the other hand, reinforcement learning additionally learns these models based on the feedback the agent gets from the environment. This book provides a concise introduction to the use of MDPs for solving probabilistic planning problems with an emphasis on the algorithmic perspective. It covers the whole spectrum of the field from the basics to state-of-the-art optimal and approximation algorithms. We first describe the theoretical foundations of MDPs and the fundamental solution techniques for them. We then discuss modern optimal algorithms based on heuristic search and the use of structured representations. A major focus of the book is on the numerous approximation schemes for MDPs that have been developed in the AI literature. These include determinization-based approaches, sampling techniques, heuristic functions, dimensionality reduction, and hierarchical representations. Finally, we briefly introduce several extensions of the standard MDP classes that model and solve even more complex planning problems. Table of Contents Introduction MDPs Fundamental Algorithms Heuristic Search

Algorithms Symbolic Algorithms Approximation Algorithms Advanced Notes **Statistical Relational Artificial Intelligence** Luc De Raedt, Kristian Kersting, Sriraam Natarajan, David Poole, 2022-05-31 An intelligent agent interacting with the real world will encounter individual people courses test results drugs prescriptions chairs boxes etc and needs to reason about properties of these individuals and relations among them as well as cope with uncertainty Uncertainty has been studied in probability theory and graphical models and relations have been studied in logic in particular in the predicate calculus and its extensions This book examines the foundations of combining logic and probability into what are called relational probabilistic models It introduces representations inference and learning techniques for probability logic and their combinations The book focuses on two representations in detail Markov logic networks a relational extension of undirected graphical models and weighted first order predicate calculus formula and Problog a probabilistic extension of logic programs that can also be viewed as a Turing complete relational extension of Bayesian networks **Essential Principles for Autonomous Robotics** Henry Hexmoor, 2022-05-31 From driving flying and swimming to digging for unknown objects in space exploration autonomous robots take on varied shapes and sizes In part autonomous robots are designed to perform tasks that are too dirty dull or dangerous for humans With nontrivial autonomy and volition they may soon claim their own place in human society These robots will be our allies as we strive for understanding our natural and man made environments and build positive synergies around us Although we may never perfect replication of biological capabilities in robots we must harness the inevitable emergence of robots that synchronizes with our own capacities to live learn and grow This book is a snapshot of motivations and methodologies for our collective attempts to transform our lives and enable us to cohabit with robots that work with and for us It reviews and guides the reader to seminal and continual developments that are the foundations for successful paradigms It attempts to demystify the abilities and limitations of robots It is a progress report on the continuing work that will fuel future endeavors Table of Contents Part I Preliminaries Agency Motion and Anatomy Behaviors Architectures Affect Sensors Manipulators Part II Mobility Potential Fields Roadmaps Reactive Navigation Multi Robot Mapping Brick and Mortar Strategy Part III State of the Art Multi Robotics Phenomena Human Robot Interaction Fuzzy Control Decision Theory and Game Theory Part IV On the Horizon Applications Macro and Micro Robots References Author Biography Discussion

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