Multivariable Control System Design for Quadruple Tank Process using Quantitative Feedback Theory (QFT)

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Abstract - This paper focus on design of multivariable controller for Quadruple Tank Process, a two input two output system with large plant uncertainty using QFT methodology. In the present work, a new approach using Quantitative Feedback Theory (QFT) is formulated for design of a robust two degree of freedom controller for Quadruple Tank Process. The design is done in frequency domain. This paper presents a design method for a 2 x 2 multiple input multiple output system. The plant uncertainties are transformed into equivalent external disturbance sets, and the design problem becomes one of the external disturbance attenuation. The objective is to find compensator functions which guarantee that the system performance bounds are satisfied over the range of plant uncertainty. The methodology is successfully applied to design a two degree of freedom compensator Quadruple Tank Process.

Kewords — Quadruple Tank Process, Robust Control, QFT, MIMO, EDA.

I. INTRODUCTION

Many practical applications are multi-input multioutput (MIMO) systems. MIMO system is composed of several interacting control loops and numbers of alternative configurations of control loops are very large. Interaction produces several undesirable effects. The design method proposed in this paper consists of design of multivariable controller to have desired response from the plant in the presence of plant uncertainties and external disturbances. The quadruple tank process is a multivariable laboratory process developed by K.H. Johamsson[7]. This process consists of four interconnected water tanks and two pumps as shown in figure 1. Here objective to control the level in the lower two tank with two pump.

The Quantitative Feedback Theory (QFT) is a control method in frequency domain which uses the Nichols chart [1]. It is an engineering science devoted to the design problem with quantitative bounds on the plant parameters and quantitative tolerances on the acceptable closed-loop system response. The objective is to find compensator functions which guarantee that the system performance bounds are satisfied over the range of plant uncertainty.

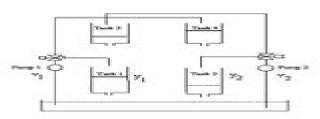


Figure 1: Quadruple tank system.

In this work, we propose a QFT based methodology to design a robust two degree of freedom MIMO compensator for quadruple tank process in the presence of parametric uncertainty. The plant uncertainties are transformed into equivalent external disturbance sets and thus the design problem becomes one of external disturbance attenuation (EDA). The method has been proven rigorous by means of Schauder's fixed point theorem [2]. The design technique is successfully applied to design a two degree of freedom compensator for quadruple tank process.

The present paper is organized as follows: Section II deals with the problem definition for a 2 x 2 MIMO design problem. Basic concepts are discussed in section III. Design equations used in the synthesis of controller for quadruple tank process is given in section IV. Section V deals with the design procedure to design controller and prefilter. In section VI, the methodology is applied to design a compensator for quadruple tank process. Conclusions are drawn in section VII.

II. A 2X2 MIMO DESIGN PROBLEM

The two degree of freedom controller structure used for the design of two input and two output quadruple tank process is shown in figure 2.

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Charles G. Schofield

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