



# G9u 730 Manual

**Intel Corporation Staff**



**G9u 730 Manual:**

**80C186EB/80C188EB User's Manual** Intel Corporation Staff,1991-01-01

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web block diagram showing receiver of a pick n place robot the system consists of two motors for providing motion to the

whole robot and two other motors to provide the arm motion the end effector or the gripper needs to be controlled to apply proper pressure on the object to handle it effectively to give it a soft grip

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web here programmable logic and controller is used for controlling and operating robotic arm all the various problems of this process have been analyzed properly and have been taken into consideration while programming and designing the pick and place robotic arm keywords automation plc pick and place robotic arm

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