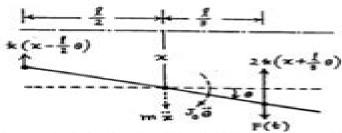
OF

$$\begin{bmatrix} m & 0 \\ 0 & J_0 \end{bmatrix} \begin{bmatrix} \ddot{x} \\ \ddot{\theta} \end{bmatrix} + \begin{bmatrix} 3 & k & k \ell/6 \\ k \ell/6 & 17 & k \ell^2/36 \end{bmatrix} \begin{bmatrix} x \\ \theta \end{bmatrix} - \begin{bmatrix} F(t) \\ \ell & F(t)/3 \end{bmatrix}$$

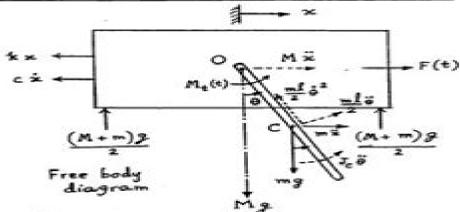
where $J_0 = \frac{m \ell^2}{12}$ and $F(t) = F_0 \sin \omega t$.

(6)

Elastic or static coupling.



(5.42)



Equations of motion with coordinates x(t) and $\theta(t)$:

For motion along x:

$$M\ddot{x} = -kx - c\dot{x} - (m\ell/2)\ddot{\theta}\cos\theta - m\ddot{x} + (m\ell/2)\dot{\theta}^{2}\sin\theta + F(t)$$
(1)

For rotation about O:

$$J_{c}\ddot{\theta} + (m\ell/2)\ddot{\theta}(\ell/2) + m\ddot{x}(\ell\cos\theta/2) = -mg(\ell/2)\sin\theta + M_{t}(t)$$
 (2)

Using $J_c = \frac{1}{12}$ m ℓ^2 , $\cos \theta \approx 1$ and $\sin \theta \approx \theta$ and neglecting the nonlinear term involving $\dot{\theta}^2$ in Eq. (1), Eqs. (1) and (2) can be rewritten in matrix form as:

$$\begin{bmatrix} (M+m) & m \, \ell/2 \\ m \, \ell/2 & (J_c+m \, \ell^2/4) \end{bmatrix} \begin{bmatrix} \ddot{x} \\ \ddot{\theta} \end{bmatrix} + \begin{bmatrix} c & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \dot{x} \\ \dot{\theta} \end{bmatrix} + \begin{bmatrix} k & 0 \\ 0 & m \, g \, \ell/2 \end{bmatrix} \begin{bmatrix} x \\ \theta \end{bmatrix} = \begin{bmatrix} F(t) \\ M_t(t) \end{bmatrix}$$

Mechanical Vibrations Rao 4th Solution Manual

RJ Alexander

Mechanical Vibrations Rao 4th Solution Manual:

Engineering Vibration Analysis with Application to Control Systems C. Beards,1995-06-17 Most machines and structures are required to operate with low levels of vibration as smooth running leads to reduced stresses and fatigue and little noise. This book provides a thorough explanation of the principles and methods used to analyse the vibrations of engineering systems combined with a description of how these techniques and results can be applied to the study of control system dynamics. Numerous worked examples are included as well as problems with worked solutions and particular attention is paid to the mathematical modelling of dynamic systems and the derivation of the equations of motion All engineers practising and student should have a good understanding of the methods of analysis available for predicting the vibration response of a system and how it can be modified to produce acceptable results. This text provides an invaluable insight into both

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volumes serves as a complete reference especially for those involved with earthquake or dynamic analysis or the design of machine foundations in the oil gas a **Scientific and Technical Books and Serials in Print**, 1989 **Forthcoming Books** Rose Arny, 2003 Solutions Manual to Accompany Applied Mechanical Vibrations David V. Hutton, 1981 An Introduction to Mechanical Vibrations Steidel, 1989-03-01 International Books in Print, 1986 **Whitaker's Book List**, 1991 **The Publishers' Trade List Annual**, 1985

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