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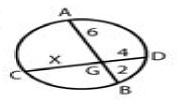
MATH

Score : _____ Date : _____

Segment Relationships in Circles

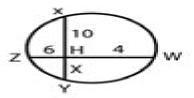
Using the theorems of segment relationships in circles , find the value of "x"

1



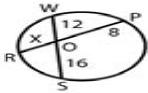
X =____

2



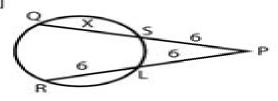
X = ____



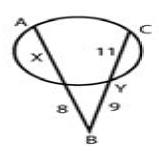


X = _____

4



5



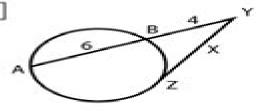
X = ____





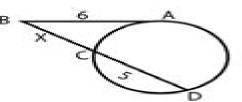
7

X =



X =

8



X = _____

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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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web pick and place robot module block diagram 14 3 3 1 robotic arm design the robotic arm with gripper termination has five degrees of freedom with a rotating base that rests on the upper region of the vehicle as depicted in figure 6