

1/1

$$(a) \quad m = \frac{W}{g} = \frac{3600}{32.2} = \underline{111.8 \text{ slugs}}$$

$$(b) \quad W = 3600 \text{ lb} \left[\frac{4.4482 \text{ N}}{\text{lb}} \right] = \underline{16,010 \text{ N}}$$

$$(c) \quad m = \frac{W}{g} = \frac{16,010}{9.81} = \underline{1632 \text{ kg}}$$

$$\left(\text{or } m = 111.8 \text{ slugs} \left[\frac{14.594 \text{ kg}}{\text{slug}} \right] = 1632 \text{ kg} \right)$$

1/2 For a 180-lb person:

$$W = mg : 180 \text{ lb} = m (32.2 \text{ ft/sec}^2)$$

$$180 \text{ lb} \left(\frac{4.4482 \text{ N}}{\text{lb}} \right) = \underline{801 \text{ N}}$$

$$W = mg : 801 \text{ N} = m (9.81 \text{ m/s}^2)$$

$$m = \underline{81.6 \text{ kg}}$$

$$1/3 \quad \underline{V_1 = 15 \left(\frac{5}{16} \hat{i} + \frac{3}{8} \hat{j} \right) = 12 \hat{i} + 9 \hat{j}}$$

$$\underline{V_2 = 12 (-\cos 60^\circ \hat{i} + \sin 60^\circ \hat{j}) = -6 \hat{i} + 10.39 \hat{j}}$$

$$\underline{V_1 + V_2 = 15 + 12 = 27}$$

$$\underline{V_1 + V_2 = (12-6) \hat{i} + (9+10.39) \hat{j} = 6 \hat{i} + 19.39 \hat{j}}$$

$$\underline{V_1 - V_2 = (12-(-6)) \hat{i} + (9-10.39) \hat{j} = 18 \hat{i} - 1.39 \hat{j}}$$

$$\underline{V_1 \times V_2 = (12 \hat{i} + 9 \hat{j}) \times (-6 \hat{i} + 10.39 \hat{j})}$$

$$= (24.7 + 54) \hat{k} = \underline{178.7 \hat{k}}$$

$$\underline{V_2 \times V_1 = - (V_1 \times V_2) = -178.7 \hat{k}}$$

$$\underline{V_1 \cdot V_2 = (12 \hat{i} + 9 \hat{j}) \cdot (-6 \hat{i} + 10.39 \hat{j})}$$

$$= 12(-6) + 9(10.39) = \underline{21.5}$$

1/4 The weight of an average apple is

$$\underline{W = \frac{5 \text{ lb}}{12 \text{ apples}} = 0.417 \text{ lb}}$$

$$\text{Mass in slugs is } m = \frac{W}{g} = \frac{0.417}{32.2} = \underline{0.01294 \text{ slugs}}$$

$$\text{Mass in kg is } m = 0.01294 \text{ slugs} \left(\frac{14.594 \text{ kg}}{1 \text{ slug}} \right)$$

$$= \underline{0.1888 \text{ kg}}$$

$$\text{Weight in N is } W = mg = 0.1888 (9.8) = \underline{1.853 \text{ N}}$$

These apples weigh closer to 2 N each than to the rule of 1 N each!

1/5

$$\text{Mass of iron sphere } m = \rho V$$

$$= (7210 \frac{\text{kg}}{\text{m}^3}) \left(\frac{4}{3} \pi (0.050^3) \right) = \underline{3.78 \text{ kg}}$$

$$\text{Force of mutual attraction: } \frac{Gm^2}{d^2}$$

$$\text{Weight of each sphere: } \frac{Gm_E m}{r^2}$$

$$\frac{Gm^2}{d^2} = \frac{Gm_E m}{r^2}, \quad r = d \sqrt{\frac{m_E}{m}}$$

$$= 0.1 \sqrt{\frac{5.97 \times 10^{24} \text{ kg}}{3.78}} \quad \frac{1}{10^3}$$

$$= \underline{1.255 (10^3) \text{ km}}$$

1/6



$r = 0.050 \text{ m}$ for all spheres

$$F_B = \frac{Gm_B m_A}{d_{AB}^2} = \frac{G \left(\rho \frac{4}{3} \pi r^3 \right) \left(\rho \frac{4}{3} \pi r^3 \right)}{d_{AB}^2}$$

$$= \frac{6.673 (10^{-11}) \left[\frac{4}{3} \pi (0.050)^3 \right]^2 (8710) (2670)}{1^2}$$

$$= \underline{4.38 (10^{-10}) \text{ N}}$$

$$F_C = \frac{Gm_C m_C}{d_{AC}^2} = \frac{G \left[\frac{4}{3} \pi r^3 \right]^2 \rho^2 r^3}{d_{AC}^2}$$

$$= \frac{6.673 (10^{-11}) \left[\frac{4}{3} \pi (0.050)^3 \right]^2 (8710) (7210)}{1^2}$$

$$= \underline{1.175 (10^{-9}) \text{ N}}$$

$$\underline{R = F_B + F_C = 4.38 (10^{-10}) [-\sin 30^\circ \hat{i} + \cos 30^\circ \hat{j}]}$$

$$+ 1.175 (10^{-9}) [\sin 30^\circ \hat{i} + \cos 30^\circ \hat{j}]$$

$$\underline{R = (3.68 \hat{i} + 13.98 \hat{j}) 10^{-10} \text{ N}}$$

1/7

$$g_h = \frac{Gm_E}{(R+h)^2}$$

$$= \frac{(3.438 \times 10^{24}) (4.075 \times 10^{-14})}{[(3757)(5280) + (150)(5280)]^2} = \underline{2.97 \text{ ft/sec}^2}$$

$$\text{Mass of man: } m = \frac{W}{g} = \frac{200}{32.174} = \underline{6.22 \text{ slugs}}$$

Absolute weight at $h = 150$ miles:

$$\underline{W_h = mg_h = (6.22)(2.97) = 186.0 \text{ lb}}$$

The terms "zero-g" and "weightless" are definitely misnomers in this instance.

1/8

$$mg = 0.1 mg_0$$

$$\frac{R^2}{(R+h)^2} g_0 = 0.1 g_0$$

$$\text{Solve for } h \text{ to obtain } \underline{h = 2.16 R}$$

Meriam Kraige Dynamics Solution Chapter 6

Millard F. Beatty



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Engineering Mechanics James L. Meriam, L. G. Kraige, 2012-03-19 The 7th edition continues to provide the same high quality material seen in previous editions. It provides extensively rewritten updated prose for content clarity, superb new problems in new application areas, outstanding instruction on drawing free body diagrams, and new electronic supplements to assist learning and instruction. *Principles of Engineering Mechanics* Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach, but the author uses it to advantage in this two volume set. Students gain a mastery of kinematics first, a solid foundation for the later study of the free body formulation of the dynamics problem. A key objective of these volumes, which present a vector treatment of the principles of mechanics, is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results. In the first volume, the elements of vector calculus and the matrix algebra are reviewed in appendices. Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text. A logical and systematic building of well known kinematic concepts, theorems, and formulas, illustrated by examples and problems, is presented, offering insights into both fundamentals and applications. Problems amplify the material and pave the way for advanced study of topics in mechanical design, analysis, advanced kinematics of mechanisms, and analytical dynamics, mechanical vibrations and controls, and continuum mechanics of solids and fluids. Volume I of *Principles of Engineering Mechanics* provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics, engineering science, engineering physics, applied mathematics, materials science, and mechanical, aerospace, and civil engineering. Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics. Engineering Dynamics Oliver M. O'Reilly, 2013-03-09 Scope, Aims, and Audiences This primer is intended to provide the theoretical background for the standard undergraduate course in dynamics. This course is usually based on one of the following texts: Bedford and Fowler 6, Beer and Johnston 7, Hibbeler 33, Meriam and Kraige 39, Riley and Sturges 50, and Shames 56, among others. Although most teachers will have certain reservations about these texts, there appears to be a general consensus that the selection of problems each of them presents is an invaluable and essential aid for studying and understanding dynamics. I myself use Meriam and Kraige 39 when teaching such a course, which is referred to as ME104 at the University of California at Berkeley. However, I have found that the gap between the theory presented in the aforementioned texts and the problems I wished my students to solve was too large. As a result, I prepared my own set of notes on the relevant theory, and I used Meriam and Kraige 39 as a problem and homework resource. This primer grew out of these notes. Its content was also heavily influenced by three other courses that I teach: one on rigid body dynamics, one on Lagrangian mechanics, and another on Hamiltonian mechanics. Because I use the primer as a

supplement I have only included a set of brief exercises at the end of each chapter

700 Solved Problems In Vector Mechanics for Engineers: Dynamics Joseph F. Shelley, 1991-04 Suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course It offers the comprehensive solved problem reference in the subject It also provides the student with the problem solving drill

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Solving Dynamics Problems in MathCad A Supplement to Accompany Engineering Mechanics: Dynamics, 5th Edition by Meriam & Kraige Brian Harper, 2001-11-26 If MathCad is the computer algebra system you need to use for your engineering calculations and graphical output Harper's Solving Dynamics Problems in MathCad is the reference that will be a valuable tutorial for your studies Written as a

guidebook for students taking the Engineering Mechanics course it will help you with your engineering assignments throughout the course Over the past 50 years Meriam Kraige's Engineering Mechanics Dynamics has established a highly respected tradition of Excellence A Tradition that emphasizes accuracy rigor clarity and applications Now completely revised redesigned and modernized the new fifth edition of this classic text builds on these strengths adding new problems and a more accessible student friendly presentation *Essentials of Dynamics and Vibrations* John Billingsley, 2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler's equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects *Engineering Mechanics: Statics, Australian New Zealand Edition* James L. Meriam, L. Glenn Kraige, Jeff N. Bolton, 2019-07-09 A foundation in mechanics principles with integrated engineering design problems Recognized for its accuracy and reliability Engineering Mechanics Statics has provided a solid foundation of mechanics principles for decades The ninth edition helps students develop problem solving skills This text for Australia and New Zealand includes helpful sample and practice problems It guides students in developing visualization and problem solving skills by focusing on the drawing of free body diagrams a key skill for solving mechanics problems [Parallel Robots](#) Hamid D. Taghirad, 2025-09-05 In today's rapidly evolving industrial landscape robotics has become essential for meeting the demands of large scale production Parallel robots with their closed loop kinematic structures offer unmatched precision rigidity and load bearing capabilities making them indispensable for tasks requiring high accuracy and efficiency This book explores the unique advantages of parallel robots providing a comprehensive resource for engineers researchers and students interested in mastering their design analysis and control Building on the success of its first edition this second edition has been extensively restructured and updated to reflect over a decade of progress in robotics It features expanded chapters on dynamics new sections on simulation and calibration and a detailed exploration of control techniques ranging from introductory linear methods to advanced force control With nearly 45% updated references the text ensures readers are equipped with cutting edge knowledge This book is both a comprehensive guide and a gateway to innovation providing detailed insights into the design simulation calibration and control of parallel robots Whether you are a newcomer to robotics or an experienced professional this text equips you with the knowledge to harness the full potential of parallel robots helping you stay ahead in the dynamic field of industrial

automation **Statics** Meriam,J.L. (James L.),L. Glenn Kraige,2008 Over the past 50 years Meriam Kraige s Engineering Mechanics Statics has established a highly respected tradition of excellence a tradition that emphasizes accuracy rigor clarity and applications Now in a Sixth Edition this classic text builds on these strengths adding a comprehensive course management system Wiley Plus to the text including an e text homework management animations of concepts and additional teaching and learning resources New sample problems new homework problems and updates to content make the book more accessible The Sixth Edition continues to provide a wide variety of high quality problems that are known for their accuracy realism applications and variety motivating students to learn and develop their problem solving skills To build necessary visualization and problem solving skills the Sixth Edition continues to offer comprehensive coverage of drawing free body diagrams the most important skill needed to solve mechanics problems **Solving Dynamics Problems in Maple by Brian Harper T/a Engineering Mechanics Dynamics 6th Edition by Meriam and Kraige** Brian D. Harper,J. L. Meriam,L. G. Kraige,2006-12-15 **32nd Aerospace Sciences Meeting & Exhibit: 94-0840 - 94-0872** ,1994

Engineering Mathematics for Marine Applications Umesh A. Korde,R. Cengiz Ertekin,2023-05-25 Gaining expertise in marine floating systems typically requires access to multiple resources to obtain the knowledge required but this book fills the long felt need for a single cohesive source that brings together the mathematical methods and dynamic analysis techniques required for a meaningful analysis primarily of large and small bodies in oceans You will be introduced to fundamentals such as vector calculus Fourier analysis and ordinary and partial differential equations Then you ll be taken through dimensional analysis of marine systems viscous and inviscid flow around structures surface waves and floating bodies in waves Real life applications are discussed and end of chapter problems help ensure full understanding Students and practicing engineers will find this an invaluable resource for developing problem solving and design skills in a challenging ocean environment through the use of engineering mathematics Engineering Mechanics , Statics J. L. Meriam,L. G. Kraige,2001-08-28 **Statics** James L. Meriam,L. Glenn Kraige,1986 **Scientific and Technical Books and Serials in Print** ,1989

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