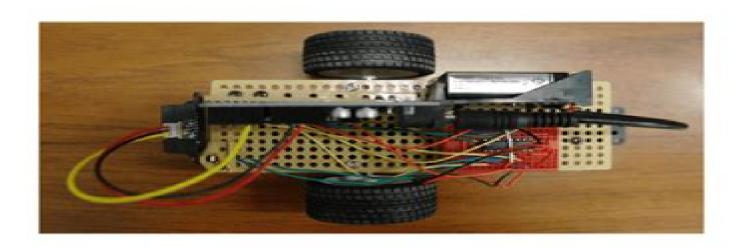
Introduction to Mechatronics Laboratory Manual

Mendenhall Innovation Program

Howard R. Hughes College of Engineering
University of Nevada Las Vegas



Latest Revision: April 22, 2012

Mechatronics Lab Manual For All Experiments

Don Wilcher

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Control Basics for Mechatronics John Billingsley, 2023-09-28 Mechatronics is a mongrel a crossbreed of classic mechanical engineering the relatively young pup of computer science the energetic electrical engineering the pedigree mathematics and the bloodhound of Control Theory All too many courses in control theory consist of a diet of Everything you could ever need to know about the Laplace Transform rather than answering What happens when your servomotor saturates Topics in this book have been selected to answer the questions that the mechatronics student is most likely to raise That does not mean that the mathematical aspects have been left out far from it The diet here includes matrices transforms eigenvectors differential equations and even the dreaded z transform But every effort has been made to relate them to practical experience to make them digestible They are there for what they can do not to support pages of mathematical rigour that defines their origins The theme running throughout the book is simulation with simple JavaScript applications that let you experience the dynamics for yourself There are examples that involve balancing such as a bicycle following a line and a balancing trolley that is similar to a Segway This can be constructed for real with components purchased from the hobby market Embedded Computing and Mechatronics with the PIC32 Microcontroller Kevin Lynch, Nicholas Marchuk, Matthew Elwin, 2015-12-08 For the first time in a single reference this book provides the beginner with a coherent and logical introduction to the hardware and software of the PIC32 bringing together key material from the PIC32 Reference Manual Data Sheets XC32 C Compiler User's Guide Assembler and Linker Guide MIPS32 CPU manuals and Harmony documentation This book also trains you to use the Microchip documentation allowing better life long learning of the PIC32 The philosophy is to get you started quickly but to emphasize fundamentals and to eliminate magic steps that prevent a deep understanding of how the software you write connects to the hardware Applications focus on mechatronics microcontroller controlled electromechanical systems incorporating sensors and actuators To support a learn by doing approach you can follow the examples throughout the book using the sample code and your PIC32 development board The exercises at the end of each chapter help you put your new skills to practice Coverage includes A practical introduction to the C programming language Getting up and running quickly with the PIC32 An exploration of the hardware architecture of the PIC32 and differences among PIC32 families Fundamentals of embedded computing with the PIC32 including the build process time and memory efficient programming and interrupts A peripheral reference with extensive sample code covering digital input and output counter timers PWM analog input input capture watchdog timer and communication by the parallel master port SPI I2C CAN USB and UART An introduction to the Microchip Harmony programming framework Essential topics in mechatronics including interfacing sensors to the PIC32 digital signal processing theory of operation and control of brushed DC motors motor sizing and gearing and other actuators such as stepper motors RC servos and brushless DC motors For more information on the book and to download free sample code please visit http www nu32 org Extensive freely

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Conference of Mechatronics and Machine Vision in Practice M2VIP 2003 which provides a forum for international experts and researchers to present and review advances in Mechatronics and Machine Vision The conference was held in Perth Australia 9 11 December 2003 IEEE/ASME International Conference on Advanced Intelligent Mechatronics Proceedings ,2005

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