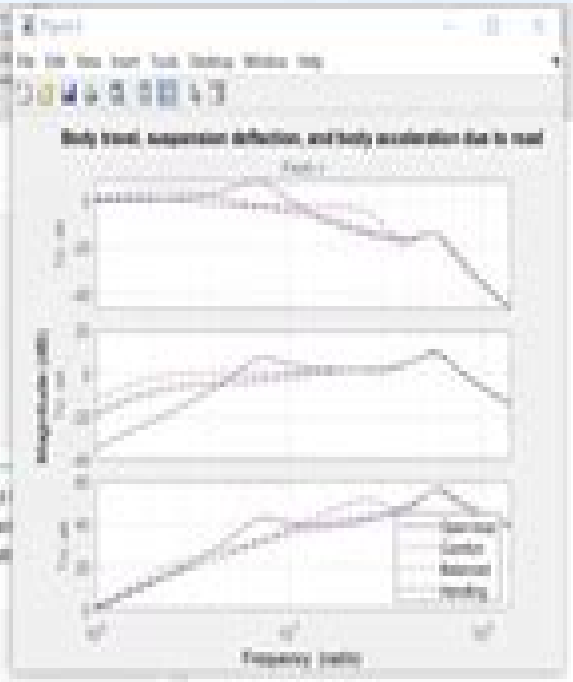
Nominal H-Infinity Design

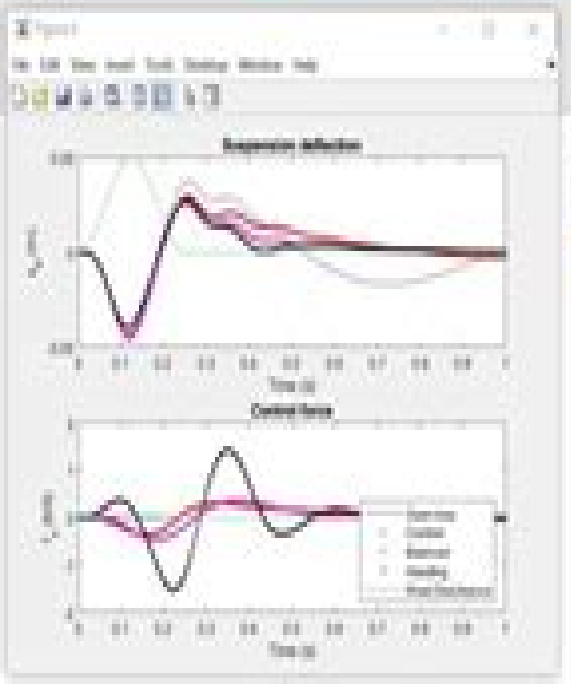
Use hinfsyn to compute an H_∞ controller for each value of the blending factor β.

```
ncont = 1; % one control signal, u
nmeas = 2; % two measurement signals, zd and ab
K = zeros(ncont,nmeas,3);
gamma = zeros(3,1);
for jw=3
    [K(:,:,jw),~,gamma(jw)] = hinfsyn(sparss(:,:,jw),nmeas,ncont);
end

area
```

The three controllers achieve closed-loop H_∞ norms of 0.94, 0.87 and 0.85, respectively. Construct
closed-loop models and compare the gains from road disturbance to z_s, z_u, a_b for the passive and a
Observe that all three controllers reduce suspension deflection and body acceleration below the valli
nodes.

```
% Closed-loop models
io = [1 3; 2 3; 3 3];
CL = connect(sparss(A,B,C,D),K(:,:,jw),io,[1 2],[1 2 3]);

bodemag(sparss(:,:,1),'b',CL(:,:,1),'r',...
    CL(:,:,2),'m',CL(:,:,3),'c',{1e-1,1e3})
legend('Open-loop','Comfort','Balanced','Handling','Location','SouthEast')
title('Body travel, suspension deflection, and body acceleration due to road')
```





Robust Mu Design

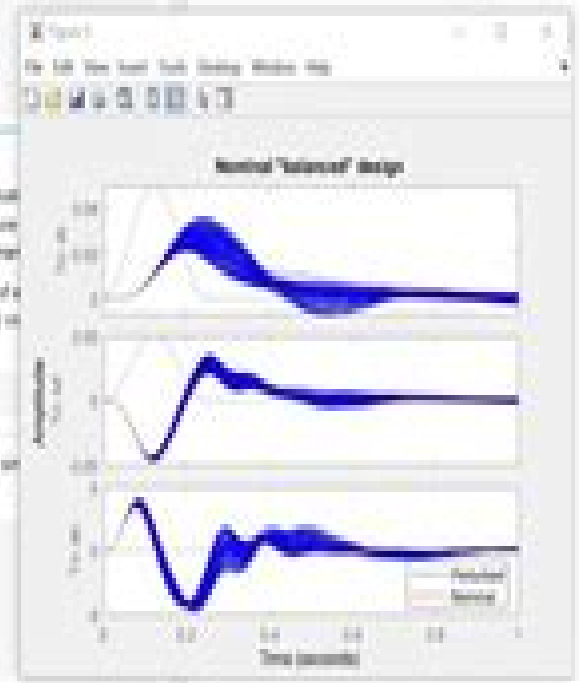
So far you have designed H_∞ controllers that meet the performance objectives for the nominal actuat
discussed earlier, this model is only an approximation of the true actuator and you need to make sure
performance is maintained in the face of model errors and uncertainty. This is called robust performa

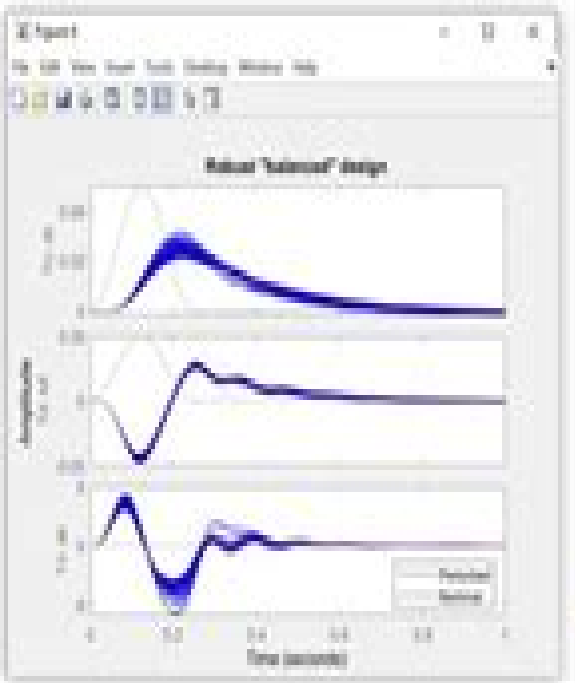
Next use μ synthesis to design a controller that achieves robust performance for the entire family of
robust controller is synthesized with the musyn function using the uncertain model sparss(:,:,2) ob
"balanced" performance ($\beta = 0.5$).

```
[K1mu,CLmu] = musyn(sparss(:,:,2),nmeas,ncont);
```

Simulate the nominal response to a road bump with the robust controller K1mu. The responses are sh
obtained with the "balanced" H_∞ controller.

```
% Closed-loop model (nominal)
Kmu.u = {'sd','ab'};
Kmu.y = 'u';
CLmu = connect(sparss,Kmu,{'rd','sd','ab','fs'},'fs');

% Simulate
```





Matlab Robust Control Toolbox Manual

AW Rasmussen

Matlab Robust Control Toolbox Manual:

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Garcia-Sanz,Constantine H. Houpis,2012-02-02 Presenting the latest developments in the field Wind Energy Systems Control Engineering Design offers a novel take on advanced control engineering design techniques for wind turbine applications The book introduces concurrent quantitative engineering techniques for the design of highly efficient and reliable controllers which can be used to solve the most critical problems of multi megawatt wind energy systems This book is based on the authors experience during the last two decades designing commercial multi megawatt wind turbines and control systems for industry leaders including NASA and the European Space Agency This work is their response to the urgent need for a truly reliable concurrent engineering methodology for the design of advanced control systems Outlining a roadmap for such a coordinated architecture the authors consider the links between all aspects of a multi megawatt wind energy project in which the wind turbine and the control system must be cooperatively designed to achieve an optimized reliable and successful system Look inside for links to a free download of QFTCT a new interactive CAD tool for QFT controller design with MATLAB that the authors developed with the European Space Agency The textbook s big picture insights can help students and practicing engineers control and optimize a wind energy system in which large flexible aerodynamic structures are connected to a demanding variable electrical grid and work automatically under very turbulent and unpredictable environmental conditions The book covers topics including robust QFT control aerodynamics mechanical and electrical dynamic modeling economics reliability and efficiency It also addresses standards certification implementation grid integration and power quality as well as environmental and maintenance issues To reinforce understanding the authors present real examples of experimentation with commercial multi megawatt direct drive wind turbines as well as on shore offshore floating and airborne wind turbine applications They also offer a unique in depth exploration of the quantitative feedback theory QFT a proven successful robust control technique for real world applications as well as advanced switching control techniques that help engineers exceed classical linear limitations Robust Control Toolbox Richard Y. Chiang,Michael G. Safonov,1996 *European Control Conference 1993* ,1993-06-28 Proceedings of the European Control Conference 1993 Groningen Netherlands June 28 July 1 1993 *Mechatronics and Control of Electromechanical Systems* Sergey Edward Lyshevski,2017-07-14 Due to the enormous impact of mechatronics systems we encounter mechatronics and micromechatronic systems in our daily activities Recent trends and novel technologies in engineering have increased the emphasis on integrated analysis design and control This book examines motion devices actuators motors transducers and sensors power electronics controllers and electronic solutions with the main emphasis placed on high performance mechatronic systems Analysis design optimization control and implementation issues as well as a variety of enabling mechatronic systems and devices are also covered The results extend from the scope of mechatronic systems to the modern hardware software developments utilizing enabling solutions and placing the integrated system perspectives in favor of consistent engineering solutions Mechatronics and Control of Electromechanical Systems facilitates comprehensive studies

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