# RF Controlled Robot Using Advanced Sensors

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Abstract— The wireless communication technology are rapidly spreading in too many new areas, including the automation and the importance of the use of wireless technologies in the data acquisition building control and automation of manufacturing processes will grow. Robots are also useful to do job in area and in situation that are hazardoos for human. This paper gives an idea about designing wireless communication between a remote control and a rubot. The main aim is to build a wireless robot using Arabino which can be detect obstacles. flames and chemical and the rubot can be controlled by a remote control through RF module the information pass through the RF module to the operator and the LED light will alove.

Key Words: Arduino, robot, RF Module, wireless

#### 1. INTRODUCTION

The fundamental concept of wireless communication on a small scale. The remote control application of RF has been extended to operate a bot. The main aim of the project is to implement a wireless robot which can be controlled through remote control using RF module and navigates around the areas and tries to detect obstacles, flames, of fire and chemical. This innovative concept consist of 434MHz Transmitter and receiver pair to allow the ambiino on both the ends to communicate wirelessly with each other. [1] Here the Robot can detect the obstacles through the use of ultrasonic sensors. Apart from this the Robot can detect flames of fire through the use of flames sensor. Also it will be able to detect chemicals likeH2, LPG, CH4, CO< or propage through the use of a sensors. The robot will be able to implement one of these three functions at a time.

#### 2.METHODOLOGY

Here we show prototype model or 3 phase fault detection, so we make the fault line by using switches. We know that impedance of line is increases with increase in length. So we use resistance combination in senses, for each phase different set of resistance is used for each phase one relay is use to isolate the load at the time of fault which give exact length of fault occur on line. The mastermind of our project is Aurdino Uno. The DC supply is requiring for controlling board. Which is provides with the help of rectifier and

transformer combination. Output switches is given analog pin or Aurdino (Uno) and display is also connected to digital output pin of Aurdino. So when we move fault it indicate of display with exact distance, and at a same time Aurdino give output to relay and it, disconnect load from supply. This all thing happen as soon as fault is occur in line. Due to proper program insert in Aurdino on a based, it is possible become voltages of ADE pin is changes according to flowing from line and it depends upon distance of line.

#### 3.08 JECTIVE

- To reduce the human efforts.
- No need of microcontroller.
- Implement without any programming language.

#### 4.METHODOLOGY

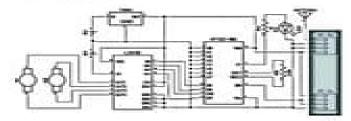


Figure 1 Circuit Diagram of Transmitter

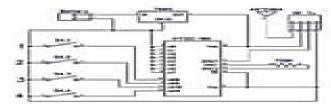


Figure 2 Circuit Diagram of Receiver

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Habib, Maki K.

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Robotics Nicholas Roy,Paul Newman,Siddhartha Srinivasa,2013-07-05 Robotics Science and Systems VIII spans a wide spectrum of robotics bringing together contributions from researchers working on the mathematical foundations of robotics robotics applications and analysis of robotics systems

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much more readily than a human instructor Mechatronics continues to be an exciting and developing field It is now an essential part of our world and living experience This and the previous books in this series illustrate the journey in developing the use of mechatronics so far We anticipate that you will find the chapters here an equal source of inspiration for new devices to solve the challenges of new applications and of course as a resource for teaching and inspiring the new generation of mechatronics engineers Sharing a Vision Dezhen Song, 2009-01-23 By the dawn of the new millennium robotics has undergone a major transf mation in scope and dimensions This expansion has been brought about by the maturity of the eld and the advances in its related technologies From a largely dominant industrial focus robotics has been rapidly expanding into the challenges of the human world The new generation of robots is expected to safely and dependably co habitat with humans in homes workplaces and c munities providing support in services entertainment education healthcare manufacturing and assistance Beyond its impact on physical robots the body of knowledge robotics has produced is revealing a much wider range of applications reaching across diverse research areas and scientic disciplines such as biomechanics haptics n rosciences virtual simulation animation surgery and sensor networks among others In return the challenges of the new emerging areas are proving an ab dant source of stimulation and insights for the eld of robotics It is indeed at the intersection of disciplines that the most striking advances happen The goal of the series of Springer Tracts in Advanced Robotics STAR is to bring in a timely fashion the latest advances and developments in robotics on thebasisoftheirsigni canceandquality Itisourhopethatthewiderdissemi tion of research developments will stimulate more exchanges and collaborations among the research community and contribute to further advancement of this rapidly growing eld Intelligent Robotics and Applications Chun-Yi Su, Subhash Rakheja, Liu Honghai, 2012-09-28 The three volume set LNAI 7506 LNAI 7507 and LNAI 7508 constitutes the refereed proceedings of the 5th International Conference on Intelligent Robotics and Applications ICIRA 2012 held in Montreal Canada in October 2012 The 197 revised full papers presented were thoroughly reviewed and selected from 271 submissions They present the state of the art developments in robotics automation and mechatronics This volume covers the topics of robotics for rehabilitation and assistance mechatronics and integration technology in electronics and information devices fabrication man machine interactions manufacturing micro and nano systems mobile robots and intelligent autonomous systems motion control multi agent systems and distributed control Research Anthology on Rehabilitation Practices and Therapy Management and multi sensor data fusion algorithms Association, Information Resources, 2020-08-21 The availability of practical applications techniques and case studies by international therapists is limited despite expansions to the fields of clinical psychology rehabilitation and counseling As dialogues surrounding mental health grow it is important to maintain therapeutic modalities that ensure the highest level of patient centered rehabilitation and care are met across global networks Research Anthology on Rehabilitation Practices and Therapy is a vital reference source that examines the latest scholarly material on trends and techniques in counseling and

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homes and communities providing support in services entertainment education health manufacturing and care As widely discussed above interaction plays a crucial role for the development of modern robotic systems Grasping manipulation and cooperative manipulators are covered in the first part of the third book of the Robotics Goes MOOC project respectively in Chapter 1 by Prattichizzo et al Chapter 2 by Kao et al and Chapter 3 by Caccavale Specific interaction issues along with the development of digital and physical interfaces are dealt with in Chapter 4 by Marchal et al and in Chapter 5 by Croft et al respectively Interaction between robot and human also means that a robot can be worn by a human as presented in Chapter 6 by Vitiello et al A different type of interaction at a cognitive and planning level is the focus of Chapter 7 by Lima devoted to multi robot systems and Chapter 8 by Song et al on networked cloud and fog robotics respectively Rehabilitation Research & Development ,1999 RoboCup-99: Robot Soccer World Cup III Manuela Veloso, Enrico Pagello, Hiroaki Kitano, 2003-07-31 This book is the third official archival publication devoted to RoboCup and documents the achievements presented at the Third Robot World Cup Soccer Games and Conferences Robo Cup 99 held in Stockholm Sweden in July August 1999 The book presents the following parts Introductory overview and survey Research papers of the champion teams and scientific award winners Technical papers presented at the RoboCup 99 Workshop Team description of a large number of participating teams This book is mandatory reading for the rapidly growing RoboCup community as well as a valuable source or reference and inspiration for R D professionals interested in multi agent systems distributed artificial intelligence and intelligent robotics **Journal of Rehabilitation Research and Development**, 2008 Applications of Evolutionary Computation Pedro A. Castillo, Juan Luis Jiménez Laredo, Francisco Fernández de Vega, 2020-04-09 This book constitutes the refereed proceedings of the 23rd European Conference on Applications of Evolutionary Computation EvoApplications 2020 held as part of Evo 2020 in Seville Spain in April 2020 co located with the Evo 2020 events EuroGP EvoMUSART and EvoCOP The 44 full papers presented in this book were carefully reviewed and selected from 62 submissions The papers cover a wide spectrum of topics ranging from applications of bio inspired techniques on social networks evolutionary computation in digital healthcare and personalized medicine soft computing applied to games applications of deep bioinspired algorithms parallel and distributed systems and evolutionary machine learning

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