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| Object Name | Object Type | Product | Schema Owner | Description | |
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| POA_EDW_PO_DIST_F | TABLE | POA - Purchasing Intelligence (Obsolete) | | PO Distributions fact table | |
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| OKC_K_PARTY_ROLES_V | VIEW | OKC - Contracts Core | APPS | View for table OKC_CONTRACT_PARTY_ROLES_F | |

Electronic Technical Reference Manual

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Electronic Technical Reference Manual:

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Technical Reference Model United States. Patent and Trademark Office,1997

Oracle Applications DBA Field Guide Paul Jackson,Elke Phelps,2006-11-22 Oracle Applications DBA Field Guide provides scripts notes guidelines and references to guide you safely through the crucial day to day administration tasks that fall within your jurisdiction This includes configuring monitoring performance tuning troubleshooting and patching This book contains tips techniques and guidance for administering the highly complex Oracle E Business Suite running Oracle9i or Oracle10g on UNIX or Linux servers all in an easy to read and quick to navigate format Even for the experienced database administrator Oracle applications are complicated to administer and most other documentation out there is difficult to find and understand Whether you re an experienced Oracle database administrator or a relative newcomer to Oracle 11i Applications perhaps migrating from PeopleSoft JD Edwards or Siebel this book will enable you to make a real impact on the ease and efficiency of your day to day administrative tasks and is relevant for Oracle releases 12 and Fusion

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[Web Information Systems Engineering - WISE 2010 Workshops](#) Dickson K.W. Chiu,Ladjel Bellatreche,Hideyasu Sasaki,Ho-fung Leung,Shing-Chi Cheung,Haiyang Hu,Jie Shao,2011-09-18 This book contains the carefully selected and reviewed papers presented at three satellite events that were held in conjunction with the 11th International Conference on Web Information Systems Engineering WISE 2010 in Hong Kong China in December 2010 The collection comprises a total of 40 contributions that originate from the First International Symposium on Web Intelligent Systems and Services WISS 2010 from the First International Workshop on Cloud Information Systems Engineering CISE 2010 and from the Second International Workshop on Mobile Business Collaboration MBC 2010 The papers address a wide range of hot topics and are

organized in topical sections on decision and e markets rules and XML web service intelligence semantics and services analyzing web resources engineering web systems intelligent web applications web communities and personalization cloud information system engineering mobile business collaboration

The Functional Verification of Electronic Systems
 Brian Bailey, 2005-01-30 Addressing the need for full and accurate functional information during the design process this guide offers a comprehensive overview of functional verification from the points of view of leading experts at work in the electronic design industry

Control System Technology C. J. Chesmond, 2014-05-12 Control System Technology focuses on the processes methodologies and techniques employed in control system technology including digital computers transducers actuators and amplifiers The book first takes a look at classification terminology and definitions displacement reference and velocity of transducers and strain force torque acceleration load and tension of transducers Discussions focus on strain gauges and measuring bridges other transducers for measuring force torque acceleration and tension displacement and velocity transducers natural control systems classification of control systems and generalized single loop continuous feedback control system The monograph examines electric amplifiers and final control elements hydraulic and pneumatic amplifiers and final control elements flow control valves actuators and positioners and signal and data conversion The publication also ponders on interfacing control systems to digital computers control system performance and commissioning and experimental testing of plant system elements and systems The manuscript is a valuable reference for engineers and researchers interested in control system technology

Scientific and Technical Aerospace Reports, 1995

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Visual Perception for Humanoid Robots
 David Israel González Aguirre, 2018-09-01 This book provides an overview of model based environmental visual perception for humanoid robots The visual perception of a humanoid robot creates a bidirectional bridge connecting sensor signals with internal representations of environmental objects The objective of such perception systems is to answer two fundamental questions What where is it To answer these questions using a sensor to representation bridge coordinated processes are conducted to extract and exploit cues matching robot s mental representations to physical entities These include sensor actuator modeling calibration filtering and feature extraction for state estimation This book discusses the following topics in depth Active Sensing Robust probabilistic methods for optimal high dynamic range image acquisition are suitable for use with inexpensive cameras This enables ideal sensing in arbitrary environmental conditions encountered in human centric spaces The book quantitatively shows the importance of equipping robots with dependable visual sensing Feature Extraction Recognition Parameter free edge extraction methods based on structural graphs enable the representation of geometric primitives effectively and efficiently This is done by eccentricity segmentation providing excellent recognition even on noisy low resolution images Stereoscopic vision Euclidean metric and graph shape descriptors are shown to be powerful

mechanisms for difficult recognition tasks Global Self Localization Depth Uncertainty Learning Simultaneous feature matching for global localization and 6D self pose estimation are addressed by a novel geometric and probabilistic concept using intersection of Gaussian spheres The path from intuition to the closed form optimal solution determining the robot location is described including a supervised learning method for uncertainty depth modeling based on extensive ground truth training data from a motion capture system The methods and experiments are presented in self contained chapters with comparisons and the state of the art The algorithms were implemented and empirically evaluated on two humanoid robots ARMAR III A B The excellent robustness performance and derived results received an award at the IEEE conference on humanoid robots and the contributions have been utilized for numerous visual manipulation tasks with demonstration at distinguished venues such as ICRA CeBIT IAS and Automatica

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