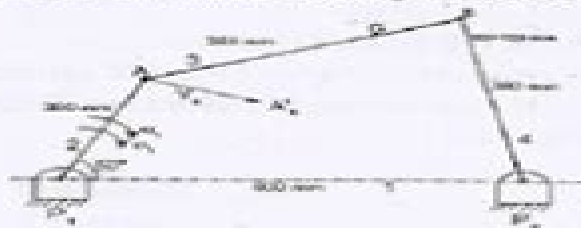




11. a) The dimensions and configuration of the four bar mechanism are shown in figure below $P_1A = 300$ mm, $P_2B = 380$ mm, $AB = 360$ mm, $BG = 120$ mm, $P_1P_2 = 600$ mm. The angle between $\angle AP_1P_2 = 60^\circ$. The crank P_1A has an angular velocity of 10 rad/s and angular acceleration of 30 rad/s², both clockwise. Determine the angular velocities and angular acceleration of P_2B and AB and the velocity and acceleration of the points B and G .



(OR)

- b) Draw the cam profile for a knife-edge follower with the following data :
- Cam lift = 40 mm during 90° of cam rotation with simple harmonic motion.
 - Dwell for the next 30° .
 - During the next 60° of cam rotation, the follower returns to its original position with simple harmonic motion.
 - Dwell during the remaining 180° .

The radius of the base circle of cam is 40 mm. Determine the maximum velocity of the follower during its ascent and descent, if the cam rotates at 240 r.p.m.

12. a) Two equal involute gear wheels of 20° pressure angle have 20 teeth each. Calculate length of arc of contact if the addendum was standard and equal to one module. Pitch of teeth is 6 mm of diameter per tooth. What should be the addendum, if the arc of contact is to be maximum possible ? What is the length of arc of contact ?

(OR)

- b) In the planetary gear train shown in below figure, gear A is the driver and gears B and D are compounded. Gears E and C are internal gears with C as the fixed gear. Number of teeth on gears are : $T_A = 20$; $T_B = 60$; $T_C = 140$;

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Peter Smid



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Data-Driven Science and Engineering Steven L. Brunton, J. Nathan Kutz, 2019-02-28 Data driven discovery is revolutionizing the modeling prediction and control of complex systems This textbook brings together machine learning engineering mathematics and mathematical physics to integrate modeling and control of dynamical systems with modern methods in data science It highlights many of the recent advances in scientific computing that enable data driven methods to be applied to a diverse range of complex systems such as turbulence the brain climate epidemiology finance robotics and autonomy Aimed at advanced undergraduate and beginning graduate students in the engineering and physical sciences the text presents a range of topics and methods from introductory to state of the art

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The Enhanced Guide for Occupational Exploration ,1991 Provides information on 2 500 jobs organized within major career clusters and descriptions of each job *Advances in Neural Networks - ISNN 2005* Jun Wang,Xiaofeng Liao,Zhang Yi,2005-05-04 The three volume set LNCS 3496 3497 3498 constitutes the refereed proceedings of the Second International Symposium on Neural Networks ISNN 2005 held in Chongqing China in May June 2005 The 483 revised papers presented were carefully reviewed and selected from 1 425 submissions The papers are organized in topical sections on theoretical analysis model design learning methods optimization methods kernel methods component analysis pattern analysis systems modeling signal processing image processing financial analysis control systems robotic systems telecommunication networks incidence detection fault diagnosis power systems biomedical applications industrial applications and other applications

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