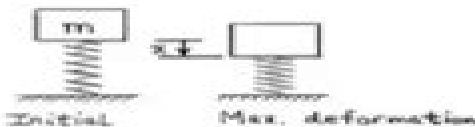


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The maximum force  $F = kx$  occurs when  $x$  is a maximum with  $\dot{x} = 0$ .

$$U_1 + \Delta T = mgs - \frac{1}{2}kx^2 = 0, \quad x = \frac{2mg}{k}$$

$$\text{So } F = kx = 2mg$$

$$3/129 \quad T_A + V_{A-0} = T_C : 0 + 2mgR = \frac{1}{2}mv_C^2, \quad v_C^2 = 4gR$$

$$(a) \quad \Sigma F_n = ma_n : N_B = m \frac{4gR}{R} = 4mg$$

$$(b) \quad T_A + V_{A-C} = T_C : 0 + 3mgR = \frac{1}{2}mv_C^2, \quad v_C^2 = 6gR$$

$$\Sigma F_n = ma_n : N_C - mg = m \frac{6gR}{R}$$

$$N_C = 7mg$$

(c) Coll. stopping point E:

$$T_A + V_{A-E} = T_E$$

$$0 + 2mgR - mg\left(\frac{1}{2}\right) - \mu_k \frac{15}{2}mg = 0$$

$$s = \frac{4R}{1 + \mu_k 15}$$

(Note: Normal force on incline is)

$$N = mg \cos 30^\circ = \frac{\sqrt{3}}{2}mg$$

3/130 Let  $s$  = distance down incline before reversal of direction.

$$U_1 + \Delta T = 100(2)(10 + s - s) - 200(10 + s - s)\frac{5}{13} = 1046 \text{ ft}\cdot\text{lb}$$

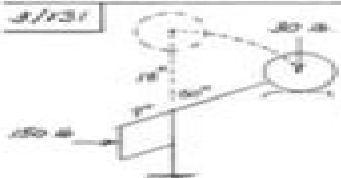
$$\Delta T = \frac{1}{2} \frac{350}{32.2} [v^2 - (17)^2] = 4.66v^2 - 377 \text{ ft}\cdot\text{lb}$$

$$U_1 + \Delta T : 1046 = 4.66v^2 - 377$$

$$v = 17.45 \text{ ft/sec}$$

The initial kinetic energy is positive regardless of the velocity direction.

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$$U_1 + \Delta T$$

$$150\left(\frac{1}{2} \sin 60^\circ\right) - 30 \frac{30}{16} = \frac{1}{2} \frac{30}{16} (v^2 - 0)$$

$$v^2 = 160.8, \quad v = 12.68 \text{ m/sec}$$

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$$U_1 + \Delta T : mg(0.8 - 1.8 \cos 60^\circ) = \frac{1}{2}m(15^2 - 0)$$

$$R/R(0.20) = \frac{1}{2}(15^2 - 0), \quad 15^2 = 12.80, \quad 15 = 3.57 \text{ m/s}$$

3/133



$$+\uparrow \Sigma F = 0 : 9810 - 4T = 0, \quad T = 2450 \text{ N}$$

Length of cable  $L = 4s_0 + \text{constants}$

$$L = 4v_0 = 4(3) = 12 \text{ m/s}$$

$$P_{\text{out}} = -T\dot{L} = -2450(12) = 29400 \text{ watts}$$

$$\text{or } P_{\text{out}} = 29.4 \text{ kW}$$

$$C = \frac{P_{\text{out}}}{P_{\text{in}}}, \quad P_{\text{in}} = \frac{P_{\text{out}}}{C} = \frac{29.4}{0.8}$$

$$P_{\text{in}} = 36.8 \text{ kW}$$

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$$U_1 + \Delta T (\text{system})$$

$$\text{First interval: } 30(9.81)(1.2) - [30(9.81)(0.5 + 1.224)] \frac{1}{2} = \frac{1}{2} 30 v^2 + \frac{1}{2} 30 (10)^2$$

$$v^2 = 6.076 \text{ m/s}^2, \quad v = 2.447 \text{ m/s}$$

$$\text{Second interval: } 15(9.81)(2) - [30(9.81)(0.5 + 1.224)] \frac{1}{2} = 0 - \frac{1}{2} 15 (2.447)^2$$

$$s = 2.18 \text{ m}, \quad S = \frac{1}{2}(1.2 + 2.18) = 1.69 \text{ m}$$

3/135

$$U_1 + \Delta T : -\int_0^0 (3x^2 + 60x) dx = \frac{1}{2} \frac{400}{32.2} (0 - v^2) 12$$

$$x^2 + 20x^2 \Big|_0^0 = \frac{500}{32.2} v^2, \quad v \text{ in ft/sec.}$$

$$v^2 = \frac{32.2}{500} (60 + 480) = 60.82 (100 \text{ m/s})^2, \quad v = 240 \text{ ft/sec}$$

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$$\Theta = \tan^{-1} \frac{6}{100} = 3.43^\circ$$

$$U_1 + \Delta T : U_1 + mgh = \frac{1}{2} m (v_1^2 + v_2^2)$$

$$U_1 = -1400(9.81)(200 \sin 3.43^\circ)$$

$$+ \frac{1}{2} 1400 \left[ \left(\frac{20}{5.28}\right)^2 - \left(\frac{100}{5.28}\right)^2 \right]$$

$$= -683,000 \text{ J} \quad \text{or} \quad -683 \text{ kJ}$$

$$\text{Energy lost } Q = 683 \text{ kJ}$$

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The power output of the drivetrain is

$$P_{\text{out}} = Fv = 540 \left( \frac{30}{3.6} \right) = 14,400 \text{ W}$$

The power input to the drivetrain:

$$P_{\text{in}} = \frac{P_{\text{out}}}{\epsilon} = \frac{14,400}{0.70} = 20,571 \text{ W}$$

$$\text{So the motor output } P = 20.6 \text{ kW}$$

# Meriam Kraige Engineering Mechanics Dynamics 7th Solutions

**JR Anderson**



## **Meriam Kraige Engineering Mechanics Dynamics 7th Solutions:**

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nonlinear waves before dealing with nonlinear waves in bounded media The examples used come mainly from gas dynamics water waves and viscoelastic waves      Next Generation Energetics Jacqueline Akhavan,2025-07-18 Held for the second time in the UK the international conference in explosives and other energetics took place in June 2024 These conferences host international academics and practitioners who share and showcase research undertaken in this area Particularly important is the part the UK plays as one of the world leaders in this area with the opportunity to provide unclassified and novel research This book contains the proceedings of this meeting and comprises unique peer reviewed papers which are highly desirable for researchers in this field Divided into two sections on synthesis characterisation and diagnostics and artificial intelligence simulation and modelling the book captures the fundamental science of explosives and energetic materials that underpins deeper understanding of explosives propellants pyrotechnics and gas generators All professionals from early careers through to subject matter experts will find topics of interest in this snapshot of research      **XVIII International Coal Preparation Congress** Vladimir Litvinenko,2016-10-21 This book gathers technical and scientific articles by leading experts from 15 countries and originally presented at the world s most prestigious forum on coal preparation the XVIII International Coal Preparation Congress Topics addressed include the mineral resources basis of the coal industry problems and prospects of development in the coal industry crushing grinding screening and classification processes used at sorting plants coal processing and briquette factories review of plant designs and operations used around the world new developments in dense medium separators water based separation processes froth flotation and dewatering technologies and equipment for the dry separation of coal coal deep processing technologies and equipment energy generation as an area of coal deep processing and simulation and optimization software for separation processes In general the future of coal around the world is defined by its competitiveness As the cheapest form of fuel comparatively speaking coal undoubtedly continues to be in high demand around the world      **Books in Print Supplement** ,1994      **Climbing and Walking Robots** Manuel Armada,Pablo González de Santos,2006-01-16 Interest in climbing and walking robots CLAWAR has increased remarkably over recent years Novel solutions for complex and very diverse application fields exploration intervention in severe environments personal services emergency rescue operations transportation entertainment medical etc have been anticipated by great progress in this area of robotics This book contains the proceedings of the 7th Climbing and Walking Robots 2004 CLAWAR 2004 Conference offering the international scientific community one of the most excellent forums for academics researchers and industrialists interested in this motivating area of climbing and walking robots It provides a wide forum of original state of the art contributions from various industrial and new emerging research fields presenting a full picture of climbing and walking robots The conference held in Madrid Spain September 22 24 2004 was organized by the Thematic Network CLAWAR 2 and funded by the European Commission under the GROWTH Program      **The British National Bibliography** Arthur James Wells,1998      *Einführung in die Mehrkörpersimulation* Ahmed A. Shabana,2017-07-10 Mehrkörperdynamik ist

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