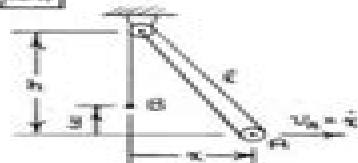


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Length of cable is

$$L = h - y + 2l + \text{constant} = h - y + 2\sqrt{x^2 + h^2} + \text{const.}$$

$$L = 0 = -\dot{y} + \frac{2x\dot{x}}{\sqrt{x^2 + h^2}}$$

Substitute v_A for \dot{x} and v_B for \dot{y} :
 $v_B = \frac{2x}{\sqrt{x^2 + h^2}} v_A$ (4 times as fast as)

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$$\text{Cable length } L = 3(s_B - s_A) + (s_C - s_A)$$

$$0 = 3v_B - 4v_A, \quad 0 = 3a_B - 4a_A$$

$$v_A = \frac{3}{4} v_B = \frac{3}{4} (2) = 1.5 \text{ m/s}$$

$$a_A = \frac{3}{4} a_B = \frac{3}{4} (3) = 2.25 \text{ m/s}^2$$

$$v_{E/A} = v_B - v_A = 2 - (1.5) = 0.5 \text{ m/s}$$

$$a_{E/A} = a_B - a_A = 3 - (2.25) = 0.75 \text{ m/s}^2$$

Length of cable between points E and C:

$$L' = (s_B - s_A) + (s_C - s_A) + \text{constants}$$

$$0 = v_B - 2v_A + v_C \Rightarrow v_C = 2v_A - v_B$$

$$\text{or } v_C = 2(1.5) - 2 = 1 \text{ m/s}$$

(All answers are quantities directed to right)

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$$\dot{x} = u \cos \theta = 200 \cos 60^\circ = 100 \text{ ft/sec}$$

$$\dot{y} = u \sin \theta - gt = 200 \sin 60^\circ - 32.2t = 173.2 - 32.2t$$

$$\text{At } t_1: \dot{x} = \dot{y}: 100 = 173.2 - 32.2t_1, \quad t_1 = 2.27 \text{ sec}$$

$$\text{At } t_2: \dot{x} = -\dot{y}: 100 = -173.2 + 32.2t_2, \quad t_2 = 5.48 \text{ sec}$$

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From A to B, $a = 0$ From B to C, $a = a_n = v^2/\rho$

$$a_n = \frac{(90 + 44/30)^2}{1000} = 12.42 \text{ ft/sec}^2$$

12.42 ft/sec²

Abrupt acceleration would cause abrupt forces which would be uncomfortable for passengers. A transition section to change curvature gradually over an interval of track would be required.

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$$r = r_0 + b \sin \frac{2\pi t}{\tau}, \quad \dot{r} = \frac{2\pi}{\tau} b \cos \frac{2\pi t}{\tau}$$

$$\ddot{r} = -\frac{4\pi^2}{\tau^2} b \sin \frac{2\pi t}{\tau}$$

$$a_r = \ddot{r} - r\dot{\theta}^2 = -\frac{4\pi^2}{\tau^2} b \sin \frac{2\pi t}{\tau} - r\dot{\theta}^2 = 0$$

$$\Rightarrow r = \frac{b}{1 + \left(\frac{2\pi}{\tau}\right)^2}$$

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$$\dot{x} = 20 \text{ mm/s}, \quad \ddot{x} = 0$$

$$y = x/80, \quad \dot{y} = \dot{x}/80, \quad \ddot{y} = (\ddot{x} + x\ddot{\theta})/80$$

$$v = \sqrt{\dot{x}^2 + \dot{y}^2} = \sqrt{2^2 + (0.25)^2} = 2.03 \text{ mm/s}$$

$$\text{For } x = 80 \text{ mm}$$

$$v = 20 \sqrt{1 + (60/80)^2} = 25 \text{ mm/s}$$

$$a = \ddot{y} = \ddot{x}/80 \text{ since } \ddot{x} = 0, \quad a = 100/80 = 1.25 \text{ mm/s}^2$$

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$$y = 40 \sin \theta, \quad v^2 = v_x^2 + v_y^2; \quad 0 = v_x^2 - 2y/40 \quad \text{At } C$$

$$v_y = \sqrt{2(40 \sin \theta)/40} = 15.34 \text{ m/s}$$

$$s = v_y t + \frac{1}{2} a_y t^2; \quad -50 = 15.34t - \frac{32}{2} t^2$$

$$t^2 - 2.128t - 3.125 = 0$$

$$t = 4.00 \text{ s} \quad (t = -1.24 \text{ s})$$

$$x = 40 \cos \theta, \quad 40 = v_x (4.00), \quad v_x = 10 \text{ m/s}$$

$$a = \sqrt{v_x^2 + v_y^2} = \sqrt{10^2 + 15.34^2} = 17.74 \text{ m/s}^2$$

$$\theta = \tan^{-1} \left(\frac{v_y}{v_x} \right) = 57.1^\circ; \quad \theta_2 = \tan^{-1} \left(\frac{v_y}{v_x} \right) = 30.1^\circ$$

$$\theta = \theta_2 = 57.1^\circ + 30.1^\circ = 87.2^\circ$$

Meriam Dynamics Solution

Dean C. Karnopp, Donald L. Margolis



Meriam Dynamics Soulation:

Engineering Applications of Dynamics Dean C. Karnopp, Donald L. Margolis, 2007-12-14 A GROUNDBREAKING TEXT THAT BRIDGES THE GAP BETWEEN THEORETICAL DYNAMICS AND INDUSTRY APPLICATIONS Designed to address the perceived failure of introductory dynamics courses to produce students capable of applying dynamic principles successfully both in subsequent courses and in practice *Engineering Applications of Dynamics* adopts a much needed practical approach designed to make the subject not only more relevant but more interesting as well Written by a highly respected team of authors the book is the first of its kind to tie dynamics theory directly to real world situations By touching on complex concepts only to the extent of illustrating their value in real world applications the authors provide students with a deeper understanding of dynamics in the engineering of mechanical systems Topics of interest include The formulation of equations in forms suitable for computer simulation Simulation examples of real engineering systems Applications to vehicle dynamics Lagrange's equations as an alternative formulation procedure Vibrations of lumped and distributed systems Three dimensional motion of rigid bodies with emphasis on gyroscopic effects Transfer functions for linearized dynamic systems Active control of dynamic systems A Solutions Manual with detailed solutions for all problems in this book is available at the Web site www.wiley.com/college/karnopp

Engineering Mechanics James L. Meriam, L. G. Kraige, J. N. Bolton, 2020-07-28 *Engineering Mechanics* Dynamics provides a solid foundation of mechanics principles and helps students develop their problem solving skills with an extensive variety of engaging problems related to engineering design More than 50% of the homework problems are new and there are also a number of new sample problems To help students build necessary visualization and problem solving skills this product strongly emphasizes drawing free body diagrams the most important skill needed to solve mechanics problems

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illustrates both the cohesiveness of the relatively few fundamental ideas in this area and the great variety of problems these ideas solve All of the problems address principles and procedures inherent in the design and analysis of engineering structures and mechanical systems with many of the problems referring explicitly to design considerations

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Principles of Engineering Mechanics Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text A logical and systematic building of well known kinematic concepts theorems and formulas illustrated by examples and problems is presented offering insights into both fundamentals and applications Problems amplify the material and pave the way for advanced study of topics in mechanical design analysis advanced kinematics of mechanisms and analytical dynamics mechanical vibrations and controls and continuum mechanics of solids and fluids Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics engineering science engineering physics applied mathematics materials science and mechanical aerospace and civil engineering Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics

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Francis C. Moon, 2008-10-20 For almost a decade now this textbook had been at the forefront in using modern analytical and computational codes and in addressing novel developments Already used by numerous institutions for their courses this second edition has been substantially revised with new sections on biomechanics and micro and nanotechnology There is also more coverage of robotics multibody simulations and celestial mechanics Numerous examples have been added and problems partly using MATLAB have been included Free solutions manual available for lecturers at www.wiley-vch.de/supplements

VFLOW2D Walter P. Wolfe, James H. Strickland, Gregory F. Homicz, Albert A. Gossler, 2000 A numerical flow model is developed to simulate two dimensional fluid flow past immersed elastically supported tube arrays This work is motivated by the objective of predicting forces and motion associated with both deep water drilling and production risers in the oil industry This work has other engineering applications including simulation of flow past tubular heat exchangers or submarine towed sensor arrays and the flow about parachute ribbons In the present work a vortex method is used for solving the unsteady flow field This method demonstrates inherent advantages over more conventional grid based computational fluid dynamics The vortex method is non iterative does not require artificial viscosity for stability displays minimal numerical diffusion can easily treat moving boundaries and allows a greatly reduced computational domain since vorticity occupies only a small fraction of the fluid volume A gridless approach is used in the flow sufficiently distant from surfaces A Lagrangian remap scheme is used near surfaces to calculate diffusion and convection of vorticity A fast multipole technique is utilized for efficient calculation of velocity from the vorticity field The ability of the method to correctly predict lift and drag forces on simple stationary geometries over a broad range of Reynolds numbers is presented

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