


3/1 $v_2^2 - v_1^2 = 2a(x_2 - x_1)$
 $0^2 - \left(\frac{100}{3.2}\right)^2 = 2a_x(50)$, $a_x = -7.72 \text{ m/s}^2$


$\Sigma F_x = ma_x$: $-4F = 1500(-7.72)$
 $F = 2870 \text{ N}$

3/2 $50(9.81) \text{ N}$ $\Sigma F_y = 0$: $N - 50(9.81) \cos 15^\circ = 0$
 $N = 474 \text{ N}$ Throughout

(a) $P = 0$
 Equilibrium check:
 $\Sigma F_x = 0$: $F - 50(9.81) \sin 15^\circ = 0$
 $F = 127.9 \text{ N}$

$F_{\max} = \mu_s N = 0.2(474) = 94.8 \text{ N} < F$: motion \checkmark
 $\Sigma F_x = ma_x$: $0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$
 $a_x = -1.118 \text{ m/s}^2$

(b) $P = 150 \text{ N}$; Equilibrium check:
 $\Sigma F_y = 0$: $150 + F - 50(9.81) \sin 15^\circ = 0$


$F = -23.9 \text{ N}$, $|F| < F_{\max}$ so no motion: $a = 0$


(c) $P = 300 \text{ N}$; Equilibrium check yields $F = -173.0 \text{ N}$
 $|F| > F_{\max}$, so motion \checkmark , $F = F_k \checkmark$.
 $\Sigma F_x = ma_x$: $300 - 0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$
 $a_x = 2.04 \text{ m/s}^2$

3/3 80 lb $\Sigma F_y = 0$: $N - 80 \cos 20^\circ = 0$
 $N = 75.2 \text{ lb}$
 $\Sigma F_x = ma_x$:
 $-0.25(75.2) - 80 \sin 20^\circ = \frac{80}{32.2} a$
 $a = -18.58 \text{ ft/sec}^2$

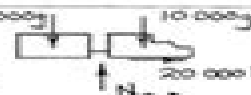
$v = v_0 + at$: $0 = 30 - 18.58t$, $t = 1.615 \text{ sec}$
 $v^2 = v_0^2 + 2a(s - s_0)$: $0^2 = 30^2 + 2(-18.58)d$
 $d = 24.2 \text{ ft}$

$v^2 = v_0^2 + 2a(s - s_0)$: $15^2 = 30^2 + 2(-18.58)d'$
 $d' = 18.17 \text{ ft}$


3/4 $300,000(9.81) \text{ N}$

 $\Sigma F_x = ma_x$:
 $3(240,000) - 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$
 $a_x = 2.31 \text{ m/s}^2$

$v^2 = 2a_x s$: $\left(\frac{220}{3.6}\right)^2 = 2(2.31)s$, $s_x = 807 \text{ m}$

 $\Sigma F_x = ma_x$:
 $3(240,000) + 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$
 $a_x = 2.49 \text{ m/s}^2$


$v^2 = 2a_x s$: $\left(\frac{220}{3.6}\right)^2 = 2(2.49)s$, $s_x = 751 \text{ m}$

3/5 For entire unit: $20,000 \text{ kg}$ $10,000 \text{ kg}$
 $\Sigma F = ma$: $20,000 = 30,000a$
 $a = 0.667 \text{ m/s}^2$


For trailer alone, $T = 20,000(0.667) = 13,330 \text{ N}$
 or $T = 13.33 \text{ kN}$


3/6 $\Sigma F_x = ma_x$: $mg \sin 40^\circ - \mu_k mg \cos 40^\circ = ma$
 $a = 9.81(\sin 40^\circ - \mu_k \cos 40^\circ)$
 $= 6.31 - 7.51 \mu_k$


For constant accel. $s = v_0 t + \frac{1}{2} a t^2$:
 $20 = 0 + \frac{1}{2}(6.31 - 7.51 \mu_k) 2.58^2$
 $\mu_k = 0.0595$

3/7 $\Sigma F = ma$: $T - 100 = \frac{100}{32.2} a$
 (a) $T \uparrow$ $150 - T = \frac{100}{32.2} a$
 $50 = \frac{200}{32.2} a$, $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$


(b) $150 - 100 = \frac{100}{32.2} a$, $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$


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Dynamics - Formulas and Problems Dietmar Gross, Wolfgang Ehlers, Peter Wriggers, Jörg Schröder, Ralf Müller, 2016-10-05 This book contains the most important formulas and more than 190 completely solved problems from Kinetics and Hydrodynamics It provides engineering students material to improve their skills and helps to gain experience in solving engineering problems Particular emphasis is placed on finding the solution path and formulating the basic equations Topics include Kinematics of a Point Kinetics of a Point Mass Dynamics of a System of Point Masses Kinematics of Rigid Bodies Kinetics of Rigid Bodies Impact Vibrations Non Inertial Reference Frames Hydrodynamics

Principles of Engineering Mechanics Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text A logical and systematic building of well known kinematic concepts theorems and formulas illustrated by examples and problems is presented offering insights into both fundamentals and applications Problems amplify the material and pave the way for advanced study of topics in mechanical design analysis advanced kinematics of mechanisms and analytical dynamics mechanical vibrations and controls and continuum mechanics of solids and fluids Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics engineering science engineering physics applied mathematics materials science and mechanical aerospace and civil engineering Professionals

working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics

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