

```

1  ORG 00H                ; Assembly Starts from 0000H.
2  ; Main Program
3  START: MOV P1, #0XFF    ; Move 11111111 to PORT1.
4  CALL WAIT              ; Call WAIT
5  MOV A, P1              ; Move P1 value to ACC
6  CPL A                  ; Complement ACC
7  MOV P1, A              ; Move ACC value to P1
8  CALL WAIT              ; Call WAIT
9  SJMP START             ; Jump to START
10 WAIT:  MOV R1, #10      ; Load Register R1 with 10 (0x0A)
11 WAIT1: MOV R3, #200     ; Load Register R3 with 10 (0xC8)
12 WAIT2: MOV R4, #100     ; Load Register R4 with 10 (0x64)
13        DJNZ R1, $        ; Decrement R1 till it is 0. Stay here if not 0.
14        DJNZ R3, WAIT2    ; Decrement R3 till it is 0. Jump to WAIT2 if not 0.
15        DJNZ R2, WAIT1    ; Decrement R2 till it is 0. Jump to WAIT1 if not 0.
16        RET              ; Return to Main Program
17 END                    ; End Assembly

```

8051 MICROCONTROLLER ASSEMBLY LANGUAGE PROGRAMMING

Motor Control Using Assembly Language Programing Examples

O García



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