

Ana L.C. Bazzan · Franziska Klügl

Introduction to Intelligent Systems in Traffic and Transportation

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Kristen Jaskie, Andreas Spanias



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Introduction to Intelligent Systems in Traffic and Transportation Ana L.C. Bazzan, Franziska Klügl, 2014-05-01

Urban mobility is not only one of the pillars of modern economic systems but also a key issue in the quest for equality of opportunity once it can improve access to other services. Currently, however, there are a number of negative issues related to traffic, especially in mega cities, such as economical issues, cost of opportunity caused by delays, environmental externalities related to emissions of pollutants, and social traffic accidents. Solutions to these issues are more and more closely tied to information and communication technology. Indeed, a search in the technical literature using the keyword urban traffic to filter out articles on data network traffic retrieved the following number of articles as of December 3, 2013: 9,443 ACM Digital Library, 26,054 Scopus, and 1,730,000 Google Scholar. Moreover, articles listed in the ACM query relate to conferences as diverse as MobiCom, CHI, PADS, and AAMAS. This means that there is a big and diverse community of computer scientists and computer engineers who tackle research that is connected to the development of intelligent traffic and transportation systems. It is also possible to see that this community is growing and that research projects are getting more and more interdisciplinary. To foster the cooperation among the involved communities, this book aims at giving a broad introduction into the basic but relevant concepts related to transportation systems, targeting researchers and practitioners from computer science and information technology. In addition, the second part of the book gives a panorama of some of the most exciting and newest technologies originating in computer science and computer engineering that are now being employed in projects related to car-to-car communication, interconnected vehicles, car navigation, platooning, crowd sensing, and sensor networks, among others. This material will also be of interest to engineers and researchers from the traffic and transportation community.

Introduction to Intelligent Systems in Traffic and Transportation Ana L.C. Bazzan, Franziska Klügl, 2022-05-31

Urban mobility is not only one of the pillars of modern economic systems but also a key issue in the quest for equality of opportunity once it can improve access to other services. Currently, however, there are a number of negative issues related to traffic, especially in mega cities, such as economical issues, cost of opportunity caused by delays, environmental externalities related to emissions of pollutants, and social traffic accidents. Solutions to these issues are more and more closely tied to information and communication technology. Indeed, a search in the technical literature using the keyword urban traffic to filter out articles on data network traffic retrieved the following number of articles as of December 3, 2013: 9,443 ACM Digital Library, 26,054 Scopus, and 1,730,000 Google Scholar. Moreover, articles listed in the ACM query relate to conferences as diverse as MobiCom, CHI, PADS, and AAMAS. This means that there is a big and diverse community of computer scientists and computer engineers who tackle research that is connected to the development of intelligent traffic and transportation systems. It is also possible to see that this community is growing and that research projects are getting more and more interdisciplinary. To foster the cooperation among the involved communities, this book aims at giving a broad introduction into

the basic but relevant concepts related to transportation systems targeting researchers and practitioners from computer science and information technology In addition the second part of the book gives a panorama of some of the most exciting and newest technologies originating in computer science and computer engineering that are now being employed in projects related to car to car communication interconnected vehicles car navigation platooning crowd sensing and sensor networks among others This material will also be of interest to engineers and researchers from the traffic and transportation community

Statistical Relational Artificial Intelligence Luc De Raedt, Kristian Kersting, Sriraam Natarajan, David Poole, 2022-05-31 An intelligent agent interacting with the real world will encounter individual people courses test results drugs prescriptions chairs boxes etc and needs to reason about properties of these individuals and relations among them as well as cope with uncertainty Uncertainty has been studied in probability theory and graphical models and relations have been studied in logic in particular in the predicate calculus and its extensions This book examines the foundations of combining logic and probability into what are called relational probabilistic models It introduces representations inference and learning techniques for probability logic and their combinations The book focuses on two representations in detail Markov logic networks a relational extension of undirected graphical models and weighted first order predicate calculus formula and Problog a probabilistic extension of logic programs that can also be viewed as a Turing complete relational extension of Bayesian networks

Transfer Learning for Multiagent Reinforcement Learning Systems Felipe Leno da Silva, Anna Helena Reali Costa, 2022-06-01 Learning to solve sequential decision making tasks is difficult Humans take years exploring the environment essentially in a random way until they are able to reason solve difficult tasks and collaborate with other humans towards a common goal Artificial Intelligent agents are like humans in this aspect Reinforcement Learning RL is a well known technique to train autonomous agents through interactions with the environment Unfortunately the learning process has a high sample complexity to infer an effective actuation policy especially when multiple agents are simultaneously actuating in the environment However previous knowledge can be leveraged to accelerate learning and enable solving harder tasks In the same way humans build skills and reuse them by relating different tasks RL agents might reuse knowledge from previously solved tasks and from the exchange of knowledge with other agents in the environment In fact virtually all of the most challenging tasks currently solved by RL rely on embedded knowledge reuse techniques such as Imitation Learning Learning from Demonstration and Curriculum Learning This book surveys the literature on knowledge reuse in multiagent RL The authors define a unifying taxonomy of state of the art solutions for reusing knowledge providing a comprehensive discussion of recent progress in the area In this book readers will find a comprehensive discussion of the many ways in which knowledge can be reused in multiagent sequential decision making tasks as well as in which scenarios each of the approaches is more efficient The authors also provide their view of the current low hanging fruit developments of the area as well as the still open big questions that could result in breakthrough developments Finally the book provides

resources to researchers who intend to join this area or leverage those techniques including a list of conferences journals and implementation tools This book will be useful for a wide audience and will hopefully promote new dialogues across communities and novel developments in the area

Introduction to Logic Programming Michael Genesereth,Vinay K. Chaudhri,2022-06-01 Logic Programming is a style of programming in which programs take the form of sets of sentences in the language of Symbolic Logic Over the years there has been growing interest in Logic Programming due to applications in deductive databases automated worksheets Enterprise Management business rules Computational Law and General Game Playing This book introduces Logic Programming theory current technology and popular applications In this volume we take an innovative model theoretic approach to logic programming We begin with the fundamental notion of datasets i e sets of ground atoms Given this fundamental notion we introduce views i e virtual relations and we define classical logic programs as sets of view definitions written using traditional Prolog like notation but with semantics given in terms of datasets rather than implementation We then introduce actions i e additions and deletions of ground atoms and we define dynamic logic programs as sets of action definitions In addition to the printed book there is an online version of the text with an interpreter and a compiler for the language used in the text and an integrated development environment for use in developing and deploying practical logic programs

Introduction to Graph Neural Networks Zhiyuan Liu,Jie Zhou,2022-05-31 Graphs are useful data structures in complex real life applications such as modeling physical systems learning molecular fingerprints controlling traffic networks and recommending friends in social networks However these tasks require dealing with non Euclidean graph data that contains rich relational information between elements and cannot be well handled by traditional deep learning models e g convolutional neural networks CNNs or recurrent neural networks RNNs Nodes in graphs usually contain useful feature information that cannot be well addressed in most unsupervised representation learning methods e g network embedding methods Graph neural networks GNNs are proposed to combine the feature information and the graph structure to learn better representations on graphs via feature propagation and aggregation Due to its convincing performance and high interpretability GNN has recently become a widely applied graph analysis tool This book provides a comprehensive introduction to the basic concepts models and applications of graph neural networks It starts with the introduction of the vanilla GNN model Then several variants of the vanilla model are introduced such as graph convolutional networks graph recurrent networks graph attention networks graph residual networks and several general frameworks Variants for different graph types and advanced training methods are also included As for the applications of GNNs the book categorizes them into structural non structural and other scenarios and then it introduces several typical models on solving these tasks Finally the closing chapters provide GNN open resources and the outlook of several future directions

An Introduction to Constraint-Based Temporal Reasoning Roman Barták,Robert A. Morris,K. Brent Venable,2014-02-01 Solving challenging computational problems involving time has been a critical component in the development of artificial

intelligence systems almost since the inception of the field This book provides a concise introduction to the core computational elements of temporal reasoning for use in AI systems for planning and scheduling as well as systems that extract temporal information from data It presents a survey of temporal frameworks based on constraints both qualitative and quantitative as well as of major temporal consistency techniques The book also introduces the reader to more recent extensions to the core model that allow AI systems to explicitly represent temporal preferences and temporal uncertainty This book is intended for students and researchers interested in constraint based temporal reasoning It provides a self contained guide to the different representations of time as well as examples of recent applications of time in AI systems

An Introduction to the Planning Domain Definition Language Patrik Haslum,Nir Lipovetzky,Daniele Magazzeni,Christian Muise,2022-05-31 Planning is the branch of Artificial Intelligence AI that seeks to automate reasoning about plans most importantly the reasoning that goes into formulating a plan to achieve a given goal in a given situation AI planning is model based a planning system takes as input a description or model of the initial situation the actions available to change it and the goal condition to output a plan composed of those actions that will accomplish the goal when executed from the initial situation The Planning Domain Definition Language PDDL is a formal knowledge representation language designed to express planning models Developed by the planning research community as a means of facilitating systems comparison it has become a de facto standard input language of many planning systems although it is not the only modelling language for planning Several variants of PDDL have emerged that capture planning problems of different natures and complexities with a focus on deterministic problems The purpose of this book is two fold First we present a unified and current account of PDDL covering the subsets of PDDL that express discrete numeric temporal and hybrid planning Second we want to introduce readers to the art of modelling planning problems in this language through educational examples that demonstrate how PDDL is used to model realistic planning problems The book is intended for advanced students and researchers in AI who want to dive into the mechanics of AI planning as well as those who want to be able to use AI planning systems without an in depth explanation of the algorithms and implementation techniques they use

Introduction to Symbolic Plan and Goal Recognition Reuth Mirsky,Sarah Keren,Christopher Geib,2022-05-31 Plan recognition activity recognition and goal recognition all involve making inferences about other actors based on observations of their interactions with the environment and other agents This synergistic area of research combines unites and makes use of techniques and research from a wide range of areas including user modeling machine vision automated planning intelligent user interfaces human computer interaction autonomous and multi agent systems natural language understanding and machine learning It plays a crucial role in a wide variety of applications including assistive technology software assistants computer and network security human robot collaboration natural language processing video games and many more This wide range of applications and disciplines has produced a wealth of ideas models tools and results in the recognition literature However it has also contributed to

fragmentation in the field with researchers publishing relevant results in a wide spectrum of journals and conferences This book seeks to address this fragmentation by providing a high level introduction and historical overview of the plan and goal recognition literature It provides a description of the core elements that comprise these recognition problems and practical advice for modeling them In particular we define and distinguish the different recognition tasks We formalize the major approaches to modeling these problems using a single motivating example Finally we describe a number of state of the art systems and their extensions future challenges and some potential applications

Lifelong Machine Learning Zhiyuan Chaudhri,Bing Liu,2022-11-10 Lifelong Machine Learning or Lifelong Learning is an advanced machine learning paradigm that learns continuously accumulates the knowledge learned in previous tasks and uses it to help future learning In the process the learner becomes more and more knowledgeable and effective at learning This learning ability is one of the hallmarks of human intelligence However the current dominant machine learning paradigm learns in isolation given a training dataset it runs a machine learning algorithm on the dataset to produce a model It makes no attempt to retain the learned knowledge and use it in future learning Although this isolated learning paradigm has been very successful it requires a large number of training examples and is only suitable for well defined and narrow tasks In comparison we humans can learn effectively with a few examples because we have accumulated so much knowledge in the past which enables us to learn with little data or effort Lifelong learning aims to achieve this capability As statistical machine learning matures it is time to make a major effort to break the isolated learning tradition and to study lifelong learning to bring machine learning to new heights Applications such as intelligent assistants chatbots and physical robots that interact with humans and systems in real life environments are also calling for such lifelong learning capabilities Without the ability to accumulate the learned knowledge and use it to learn more knowledge incrementally a system will probably never be truly intelligent This book serves as an introductory text and survey to lifelong learning

Federated Learning Qiang Yang,Yang Liu,Yong Cheng,Yan Kang,Tianjian Chen,Han Yu,2022-06-01 How is it possible to allow multiple data owners to collaboratively train and use a shared prediction model while keeping all the local training data private Traditional machine learning approaches need to combine all data at one location typically a data center which may very well violate the laws on user privacy and data confidentiality Today many parts of the world demand that technology companies treat user data carefully according to user privacy laws The European Union s General Data Protection Regulation GDPR is a prime example In this book we describe how federated machine learning addresses this problem with novel solutions combining distributed machine learning cryptography and security and incentive mechanism design based on economic principles and game theory We explain different types of privacy preserving machine learning solutions and their technological backgrounds and highlight some representative practical use cases We show how federated learning can become the foundation of next generation machine learning that caters to technological and societal needs for responsible AI development and application

Judgment

Aggregation Davide Grossi, Gabriella Pigozzi, 2022-06-01 Judgment aggregation is a mathematical theory of collective decision making It concerns the methods whereby individual opinions about logically interconnected issues of interest can or cannot be aggregated into one collective stance Aggregation problems have traditionally been of interest for disciplines like economics and the political sciences as well as philosophy where judgment aggregation itself originates from but have recently captured the attention of disciplines like computer science artificial intelligence and multi agent systems Judgment aggregation has emerged in the last decade as a unifying paradigm for the formalization and understanding of aggregation problems Still no comprehensive presentation of the theory is available to date This Synthesis Lecture aims at filling this gap presenting the key motivations results abstractions and techniques underpinning it Table of Contents Preface Acknowledgments Logic Meets Social Choice Theory Basic Concepts Impossibility Coping with Impossibility Manipulability Aggregation Rules Deliberation Bibliography Authors Biographies Index **Positive Unlabeled Learning** Kristen

Jaskie, Andreas Spanias, 2022-04-20 Machine learning and artificial intelligence AI are powerful tools that create predictive models extract information and help make complex decisions They do this by examining an enormous quantity of labeled training data to find patterns too complex for human observation However in many real world applications well labeled data can be difficult expensive or even impossible to obtain In some cases such as when identifying rare objects like new archeological sites or secret enemy military facilities in satellite images acquiring labels could require months of trained human observers at incredible expense Other times as when attempting to predict disease infection during a pandemic such as COVID 19 reliable true labels may be nearly impossible to obtain early on due to lack of testing equipment or other factors In that scenario identifying even a small amount of truly negative data may be impossible due to the high false negative rate of available tests In such problems it is possible to label a small subset of data as belonging to the class of interest though it is impractical to manually label all data not of interest We are left with a small set of positive labeled data and a large set of unknown and unlabeled data Readers will explore this Positive and Unlabeled learning PU learning problem in depth The book rigorously defines the PU learning problem discusses several common assumptions that are frequently made about the problem and their implications and considers how to evaluate solutions for this problem before describing several of the most popular algorithms to solve this problem It explores several uses for PU learning including applications in biological medical business security and signal processing This book also provides high level summaries of several related learning problems such as one class classification anomaly detection and noisy learning and their relation to PU learning *Representing and Reasoning with Qualitative Preferences* Ganesh Ram Santhanam, Samik Basu, Vasant Honavar, 2022-05-31 This book provides a tutorial introduction to modern techniques for representing and reasoning about qualitative preferences with respect to a set of alternatives The syntax and semantics of several languages for representing preference languages including CP nets TCP nets CI nets and CP theories are reviewed Some key problems in reasoning about preferences are introduced including

determining whether one alternative is preferred to another or whether they are equivalent with respect to a given set of preferences These tasks can be reduced to model checking in temporal logic Specifically an induced preference graph that represents a given set of preferences can be efficiently encoded using a Kripke Structure for Computational Tree Logic CTL One can translate preference queries with respect to a set of preferences into an equivalent set of formulae in CTL such that the CTL formula is satisfied whenever the preference query holds This allows us to use a model checker to reason about preferences i e answer preference queries and to obtain a justification as to why a preference query is satisfied or not with respect to a set of preferences This book defines the notions of the equivalence of two sets of preferences including what it means for one set of preferences to subsume another and shows how to answer preferential equivalence and subsumption queries using model checking Furthermore this book demonstrates how to generate alternatives ordered by preference along with providing ways to deal with inconsistent preference specifications A description of CRISNER an open source software implementation of the model checking approach to qualitative preference reasoning in CP nets TCP nets and CP theories is included as well as examples illustrating its use

Metric Learning Aurélien Muise, Amaury Yang, 2022-05-31 Similarity between objects plays an important role in both human cognitive processes and artificial systems for recognition and categorization How to appropriately measure such similarities for a given task is crucial to the performance of many machine learning pattern recognition and data mining methods This book is devoted to metric learning a set of techniques to automatically learn similarity and distance functions from data that has attracted a lot of interest in machine learning and related fields in the past ten years In this book we provide a thorough review of the metric learning literature that covers algorithms theory and applications for both numerical and structured data We first introduce relevant definitions and classic metric functions as well as examples of their use in machine learning and data mining We then review a wide range of metric learning algorithms starting with the simple setting of linear distance and similarity learning We show how one may scale up these methods to very large amounts of training data To go beyond the linear case we discuss methods that learn nonlinear metrics or multiple linear metrics throughout the feature space and review methods for more complex settings such as multi task and semi supervised learning Although most of the existing work has focused on numerical data we cover the literature on metric learning for structured data like strings trees graphs and time series In the more technical part of the book we present some recent statistical frameworks for analyzing the generalization performance in metric learning and derive results for some of the algorithms presented earlier Finally we illustrate the relevance of metric learning in real world problems through a series of successful applications to computer vision bioinformatics and information retrieval

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[Applying Reinforcement Learning on Real-World](#)

Data with Practical Examples in Python Philip Osborne, Kajal Singh, Matthew E. Taylor, 2022-05-20 Reinforcement learning is a powerful tool in artificial intelligence in which virtual or physical agents learn to optimize their decision making to achieve long term goals. In some cases this machine learning approach can save programmers time, outperform existing controllers, reach super human performance and continually adapt to changing conditions. It has shown human level performance on a number of tasks. REF and the methodology for automation in robotics and self driving cars. REF This book argues that these successes show reinforcement learning can be adopted successfully in many different situations including robot control, stock trading, supply chain optimization and plant control. However reinforcement learning has traditionally been limited to applications in virtual environments or simulations in which the setup is already provided. Furthermore experimentation may be completed for an almost limitless number of attempts risk free. In many real life tasks applying reinforcement learning is not as simple as 1 data is not in the correct form for reinforcement learning 2 data is scarce and 3 automation has limitations in the real world. Therefore this book is written to help academics, domain specialists and data enthusiasts alike to understand the basic principles of applying reinforcement learning to real world problems. This is achieved by focusing on the process of taking practical examples and modeling standard data into the correct form required to then apply basic agents. To further assist readers gain a deep and grounded understanding of the approaches the book shows hand calculated examples in full and then how this can be achieved in a more automated manner with code. For decision makers who are interested in reinforcement learning as a solution but are not proficient the book includes simple non technical examples in the introduction and case studies section. These provide context of what reinforcement learning offer but also the challenges and risks associated with applying it in practice. Specifically these sections illustrate the differences between reinforcement learning and other machine learning approaches as well as how well known companies have found success using the approach to their problems.

Learning and Decision-Making from Rank Data Lirong Xia, 2022-06-01 The ubiquitous challenge of learning and decision making from rank data arises in situations where intelligent systems collect preference and behavior data from humans, learn from the data and then use the data to help humans make efficient, effective and timely decisions. Often such data are represented by rankings. This book surveys some recent progress toward addressing the challenge from the considerations of statistics, computation and socio economics. We will cover classical statistical models for rank data including random utility models, distance based models and mixture models. We will discuss and compare classical and state of the art algorithms such as algorithms based on Minorize Majorization MM, Expectation Maximization EM, Generalized Method of Moments GMM, rank breaking and tensor decomposition. We will also introduce principled Bayesian preference elicitation frameworks for collecting rank data. Finally we will examine socio economic aspects of statistically desirable decision making mechanisms such as Bayesian estimators. This book can be useful in three ways 1 for theoreticians in statistics and machine learning to better understand the considerations and caveats of learning from rank data compared

to learning from other types of data especially cardinal data 2 for practitioners to apply algorithms covered by the book for sampling learning and aggregation and 3 as a textbook for graduate students or advanced undergraduate students to learn about the field This book requires that the reader has basic knowledge in probability statistics and algorithms Knowledge in social choice would also help but is not required

Reasoning with Probabilistic and Deterministic Graphical Models Rina Dechter, 2019-02-14 Graphical models e g Bayesian and constraint networks influence diagrams and Markov decision processes have become a central paradigm for knowledge representation and reasoning in both artificial intelligence and computer science in general These models are used to perform many reasoning tasks such as scheduling planning and learning diagnosis and prediction design hardware and software verification and bioinformatics These problems can be stated as the formal tasks of constraint satisfaction and satisfiability combinatorial optimization and probabilistic inference It is well known that the tasks are computationally hard but research during the past three decades has yielded a variety of principles and techniques that significantly advanced the state of the art This book provides comprehensive coverage of the primary exact algorithms for reasoning with such models The main feature exploited by the algorithms is the model's graph We present inference based message passing schemes e g variable elimination and search based conditioning schemes e g cycle cutset conditioning and AND OR search Each class possesses distinguished characteristics and in particular has different time vs space behavior We emphasize the dependence of both schemes on few graph parameters such as the treewidth cycle cutset and the pseudo tree height The new edition includes the notion of influence diagrams which focus on sequential decision making under uncertainty We believe the principles outlined in the book would serve well in moving forward to approximation and anytime based schemes The target audience of this book is researchers and students in the artificial intelligence and machine learning area and beyond

Graph-Based Semi-Supervised Learning Amarnag Subramanya, Partha Pratim Talukdar, 2022-05-31 While labeled data is expensive to prepare ever increasing amounts of unlabeled data is becoming widely available In order to adapt to this phenomenon several semi supervised learning SSL algorithms which learn from labeled as well as unlabeled data have been developed In a separate line of work researchers have started to realize that graphs provide a natural way to represent data in a variety of domains Graph based SSL algorithms which bring together these two lines of work have been shown to outperform the state of the art in many applications in speech processing computer vision natural language processing and other areas of Artificial Intelligence Recognizing this promising and emerging area of research this synthesis lecture focuses on graph based SSL algorithms e g label propagation methods Our hope is that after reading this book the reader will walk away with the following 1 an in depth knowledge of the current state of the art in graph based SSL algorithms and the ability to implement them 2 the ability to decide on the suitability of graph based SSL methods for a problem and 3 familiarity with different applications where graph based SSL methods have been successfully applied Table of Contents Introduction Graph Construction Learning and

Inference Scalability Applications Future Work Bibliography Authors Biographies Index **Robot Learning from Human Teachers** Sonia Chernova, Andrea L. Thomaz, 2022-06-01 Learning from Demonstration LfD explores techniques for learning a task policy from examples provided by a human teacher The field of LfD has grown into an extensive body of literature over the past 30 years with a wide variety of approaches for encoding human demonstrations and modeling skills and tasks Additionally we have recently seen a focus on gathering data from non expert human teachers i e domain experts but not robotics experts In this book we provide an introduction to the field with a focus on the unique technical challenges associated with designing robots that learn from naive human teachers We begin in the introduction with a unification of the various terminology seen in the literature as well as an outline of the design choices one has in designing an LfD system Chapter 2 gives a brief survey of the psychology literature that provides insights from human social learning that are relevant to designing robotic social learners Chapter 3 walks through an LfD interaction surveying the design choices one makes and state of the art approaches in prior work First is the choice of input how the human teacher interacts with the robot to provide demonstrations Next is the choice of modeling technique Currently there is a dichotomy in the field between approaches that model low level motor skills and those that model high level tasks composed of primitive actions We devote a chapter to each of these Chapter 7 is devoted to interactive and active learning approaches that allow the robot to refine an existing task model And finally Chapter 8 provides best practices for evaluation of LfD systems with a focus on how to approach experiments with human subjects in this domain

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Introduction To Intelligent Systems In Traffic And Transportation Franziska Klugl Introduction

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