

Introduction to Aircraft Flight Mechanics

Performance, Static and Dynamic
Stability, Classical Feedback Control, with
State-Space and Rotorcraft Foundations

Third Edition

Thomas R. Yechout

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Mechanics Of Flight

Ashish Tewari



Mechanics Of Flight:

Basic Flight Mechanics Ashish Tewari, 2016-04-22 This book presents flight mechanics of aircraft spacecraft and rockets to technical and non technical readers in simple terms and based purely on physical principles Adapting an accessible and lucid writing style the book retains the scientific authority and conceptual substance of an engineering textbook without requiring a background in physics or engineering mathematics Professor Tewari explains relevant physical principles of flight by straightforward examples and meticulous diagrams and figures Important aspects of both atmospheric and space flight mechanics are covered including performance stability and control aeroelasticity orbital mechanics and altitude control The book describes airplanes gliders rotary wing and flapping wing flight vehicles rockets and spacecraft and visualizes the essential principles using detailed illustration It is an ideal resource for managers and technicians in the aerospace industry without engineering degrees pilots and anyone interested in the mechanics of flight *Aerodynamics, Aeronautics and Flight Mechanics* Barnes W. McCormick, 1979-08 A single comprehensive in depth treatment of both basic and applied modern aerodynamics Covers the fluid mechanics and aerodynamics of incompressible and compressible flows with particular attention to the prediction of lift and drag characteristics of airfoils and wings and complete airplane configurations Following an introduction to propellers piston engines and turbojet engines methods are presented for analyzing the performance of an airplane throughout its operating regime Also covers static and dynamic longitudinal and lateral directional stability and control Includes lift drag propulsion and stability and control data numerical methods and working graphs **Introduction to Aircraft Flight Mechanics** Thomas R. Yechout, 2003 Based on a 15 year successful approach to teaching aircraft flight mechanics at the US Air Force Academy this text explains the concepts and derivations of equations for aircraft flight mechanics It covers aircraft performance static stability aircraft dynamics stability and feedback control *Flight Mechanics Modeling and Analysis* Jitendra R. Raol, Jatinder Singh, 2008-08-20 The design development analysis and evaluation of new aircraft technologies such as fly by wire unmanned aerial vehicles and micro air vehicles necessitate a better understanding of flight mechanics on the part of the aircraft systems analyst A text that provides unified coverage of aircraft flight mechanics and systems concept will go a long way **Fundamentals of Airplane Flight Mechanics** David G. Hull, 2007-01-20 Flight mechanics is the application of Newton's laws to the study of vehicle trajectories performance stability and aerodynamic control This text is concerned with the derivation of analytical solutions of airplane flight mechanics problems associated with flight in a vertical plane Algorithms are presented for calculating lift drag pitching moment and stability derivatives Flight mechanics is a discipline As such it has equations of motion acceptable approximations and solution techniques for the approximate equations of motion Once an analytical solution has been obtained numbers are calculated in order to compare the answer with the assumptions used to derive it and to acquaint students with the sizes of the numbers A subsonic business jet is used for these calculations Mechanics of Flight Alfred

Cotterill Kermode,1996 Beginning with a summary of the mechanics of flight this book goes on to cover various aspects such as air and airflow aerofoils thrust level flight gliding landing etc It will continue to be an excellent text for all student pilots

Introduction to Aircraft Flight Mechanics ,2003 Flight Mechanics of High-Performance Aircraft Nguyen X.

Vinh,1995-05-04 Covers all aspects of flight performance of modern day high performance aircraft **Flight mechanics and flight control for a multibody aircraft** Köthe, Alexander,2019-06-26 Aircraft operating as so called High Altitude Platform Systems HAPS have been considered as a complementary technology to satellites since several years These aircraft can be used for similar communication and monitoring tasks while operating at a fraction of the cost Such concepts have been successfully tested Those include the AeroVironment Helios and the Airbus Zephyr with an endurance of nearly 624 hours 26 days All these HAPS aircraft have a high aspect ratio wing using lightweight construction In gusty atmosphere this results in high bending moments and high structural loads which can lead to overloads Aircraft crashes for example from Google s Solara 50 or Facebook s Aquila give proof of that fact Especially in the troposphere where the active weather takes place gust loads occur which can lead to the destruction of the structure The Airbus Zephyr the only HAPS aircraft without flight accidents provides only a very small payload Thus it does not fully comply with the requirements for future HAPS aircraft To overcome the shortcomings of such single wing aircraft so called multibody aircraft are considered to be an alternative The concept assumes multiple aircraft connected to each other at their wingtips It goes back to the German engineer Dr Vogt In the United States shortly after the end of World War II he experimented with the coupling of manned aircraft This resulted in a high aspect ratio wing for the aircraft formation The range of the formation could be increased correspondingly The engineer Geoffrey S Sommer took up Vogt s idea and patented an aircraft configuration consisting of several unmanned aerial vehicles coupled at their wingtips However the patent does not provide any insight into the flight performance the flight mechanical modeling or the control of such an aircraft Single publications exist that deal with the performance of coupled aircraft A profound complete analysis however is missing so far This is where the present work starts For the first time a flying vehicle based on the concept of the multibody aircraft will be analyzed in terms of flight mechanics and flight control In a performance analysis the aircraft concept is analyzed in detail and the benefits in terms of bending moments and flight performance are clearly highlighted Limits for operation in flight are shown considering aerodynamic optimal points The joints at the wingtips allow a roll and pitch motion of the individual aircraft This results in additional degrees of freedom for the design through the implementation of different relative pitch and bank angles For example using individual pitch angles for individual aircraft further decreases the induced drag and increases flight performance Because the lift is distributed symmetrically but not homogenously along the wingspan a lateral trim of the individual aircraft in formation flight becomes necessary The thesis presents a new method to implement this trim by moving the battery mass along half the wingspan which avoids additional parasite drag Further a complete flight dynamics model is provided and

analyzed for aircraft that are mechanically connected at their wingtips To study this model in detail a hypothetical torsional and bending spring between the aircraft is introduced If the spring constants are very high the flight dynamics model has properties similar to those of an elastic aircraft Rigid body and formation eigenmotions can be clearly distinguished If the spring constants are reduced towards zero which represents the case of the multibody aircraft classical flight mechanics eigenmotions and modes resulting from the additional degrees of freedom are coupled This affects the eigenstructure of the aircraft Hence normal motions with respect to the inertial space as known from a rigid aircraft cannot be observed anymore The plant also reveals unstable behavior Using the non linear flight dynamics model flight controllers are designed to stabilize the plant and provide the aircraft with an eigenstructure similar to conventional aircraft Different controller design methods are used The flight controller shall further maintain a determined shape of the flight formation it shall control flight bank and pitch angles and it shall suppress disturbances Flight control theories in the time domain Eigenstructure assignment and in the frequency domain H infinity loop shaping are considered The resulting inner control loops yield a multibody aircraft behavior that is similar to the one of a rigid aircraft For the outer control loops classical autopilot concepts are applied Overall the flight trajectory of the multibody aircraft above ground is controlled and thus an actual operation as HAPS is possible In the last step the flight controller is successfully validated in non linear simulations with complete flight dynamics

Flugzeuge in der Form von sogenannten H henplattformen engl High Altitude Platform Systems HAPS werden seit einigen Jahren als kosteng nstige Erg nzung zu teuren Satelliten betrachtet Diese Flugzeuge k nnen f r hnliche Kommunikations- und bewachungsaufgaben eingesetzt werden Zu den gegenw rtigen Konzepten solcher Flugger te die bereits erfolgreich im Flugversuch eingesetzt wurden z hlen der Helios von AeroVironment und der Airbus Zephyr der eine Flugdauer von fast 624 Stunden 26 Tagen erreicht hat Alle diese HAPS Flugzeuge besitzen einen Fl gel langer Streckung der in Leichtbauweise konstruiert ist Hieraus resultieren in b iger Atmosph re hohe Biegemomente und starke strukturelle Belastungen die zu berbelastungen f hren k nnen Flugunf lle beispielsweise von Googles Solara 50 oder Facebooks Aquila belegen dies Insbesondere in der Troposph re in der das aktive Wetter stattfindet treten B elasten auf die die Struktur zerst ren k nnen Der Airbus Zephyr der bisher als einziges HAPS Flugzeug frei von Flugunf llen ist besitzt nur eine sehr geringe Nutzlast Daher kann er die Anforderungen an zuk nftige HAPS Flugzeuge nicht vollst ndig erf llen Um die Schwachstellen solcher Ein Fl gel Konzepte zu berwinden wird in dieser Arbeit ein alternatives Flugzeugkonzept betrachtet das als Mehrkr perflugzeug bezeichnet wird Das Konzept geht von mehreren an den Fl gelspitzen miteinander verbundenen Flugzeugen aus und beruht auf Ideen des deutschen Ingenieurs Dr Vogt Dieser hatte in den USA kurz nach Ende des Zweiten Weltkrieges bemannte Flugzeuge aneinanderkoppeln lassen Hierdurch ergab sich ein Flugzeugverbund mit einem Fl gel langer Streckung Damit konnte die Reichweite des Verbundes gesteigert werden Geoffrey S Sommer griff die Idee von Vogt auf und lies sich eine Flugzeugkonfiguration patentieren die aus mehreren unbemannten Flugzeugen besteht die an den Enden der

Tragflächen miteinander gekoppelt sind. Die Patentschrift gibt jedoch keinen Einblick in die Flugleistungen, die flugmechanische Modellierung oder die Regelung eines solchen Fluggerätes. Vereinzelt existieren Veröffentlichungen, die sich mit den Flugleistungen von gekoppelten Luftfahrzeugen beschäftigen. Eine tiefgreifende vollständige flugmechanische Analyse fehlt jedoch bisher. Hier setzt die vorliegende Arbeit an. Ein Fluggerät basierend auf dem Konzept des Mehrkörperflugzeugs wird erstmalig hinsichtlich der Flugmechanik und Flugregelung untersucht. In einer Flugleistungsbetrachtung wird das Flugzeugkonzept genau analysiert und die Vorteile hinsichtlich der Biegemomente und der Flugleistungen klar herausgestellt. Die Grenzen des Einsatzes im Flugbetrieb werden mithilfe aerodynamischer Optimalpunkte aufgezeigt. Bei der Lager an den Flügelspitzen, die eine relative Roll- und Nickbewegung der Flugzeuge untereinander ermöglichen, ergeben sich durch die Einstellung unterschiedlicher Längslage- und Höhenwinkel zur tztlichen Freiheitsgeraden im Entwurf. Die Verwendung unterschiedlicher Nicklagewinkel der einzelnen Flugzeuge reduziert beispielsweise den induzierten Widerstand weiter und steigert die Flugleistung. Durch die symmetrische entlang der Spannweite jedoch nicht homogene Auftriebsverteilung ist auch eine laterale Trimmung der einzelnen Flugzeuge in der Formation notwendig. Hier stellt die Arbeit eine neuartige Möglichkeit vor, um diese Trimmung ohne zusätzlichen parasitären Widerstand mittels Verschiebung der Batteriemasse entlang der Halbspannweite umzusetzen. Weiterhin wird ein vollständiges flugdynamisches Modell für mechanisch miteinander verbundene Luftfahrzeuge aufgestellt und analysiert. Für diese Analyse wird eine hypothetische Torsions- und Biegefeder zwischen den Flugzeugen modelliert. Sind die Federsteifigkeiten hinreichend hoch, besitzt das flugdynamische Modell Eigenschaften, die einem elastischen Flugzeug entsprechen. Starrkörper- und elastische Eigenbewegungsformen sind in diesem Fall klar separiert. Bei immer weiterer Reduzierung bis auf eine Federsteifigkeit von Null kommt es zu Kopplungen zwischen den klassischen flugmechanischen Eigenbewegungsformen und den Moden aus den zusätzlichen Freiheitsgraden. Dies stellt den Auslegungsfall für das Mehrkörperflugzeug dar. Hierbei verändert sich die Eigenstruktur (engl. eigenstructure) des Flugzeugs und normale bei einem starren Flugzeug beobachtbare Bewegungen gegenüber dem inertialen Raum sind nicht mehr erkennbar. Zusätzlich zeigt die Strecke instabiles Verhalten. Basierend auf dem nichtlinearen flugdynamischen Modell werden mit verschiedenen Methoden Regler entworfen, die die Regelstrecke stabilisieren und dem Flugzeug eine Streckenstruktur zuweisen, die derjenigen klassischer Flugzeuge ähnelt. Zudem soll durch die Regler eine vorgegebene Form des Flugzeugverbundes beibehalten werden. Die Fahrt der Längs- und Rolllagewinkel sollen geregelt und Störungen unterdrückt werden. Als Auslegungsverfahren werden Theorien der Zustandsregelungen im Zeitbereich, Eigenstrukturvorgabe und Frequenzbereich, H_∞ loop shaping verwendet. Hierdurch wird durch die inneren Regelschleifen ein Verhalten des Mehrkörperflugzeugs erzielt, das dem eines starren Flugzeugs entspricht. Für die äußeren Regelschleifen werden anschließend klassische Konzepte von Autopiloten verwendet. Im Ergebnis ist eine Regelung des Flugweges über Grund des Mehrkörperflugzeugs und somit ein tatsächlicher Betrieb als HAPS möglich. Die Funktionalität des Reglers wird abschließend in

nichtlinearen Simulationen mit vollständiger Flugdynamik verifiziert
Philpott, 2018-07-19 An introduction to the principles of flight

Mechanics of Flight R. H. Barnard, D. R.

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