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Mechanical Engineering Mechatronics Lab Manual

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Mechanical Engineering Mechatronics Lab Manual:

Proceedings of the International Conference on Advanced Technology and Multidiscipline (ICATAM 2024)

Tahta Amrillah, Prihartini Widiyanti, Retno Sari, Purbandini Purbandini, Lilik Jamilatul Awal, Rizki Putra Prastio, Muhammad Noor Fakhruzzaman, Ananta Adhi Wardana, Prastika Krisma Jiwanti, 2024-11-01 This is an open access book Technology has revolutionized our world and daily lives shaping a future that must harmonize with nature Through innovations in green energy low emission transportation and energy efficient housing technology holds the potential to significantly aid resource recovery and environmental preservation However we must always consider the societal impacts of technological advancements It is crucial to strive for a balance ensuring that our technological progress supports both humanity and the environment sustainably The Faculty of Advanced Technology and Multidiscipline at Universitas Airlangga is dedicated to leading the way in the formulation of engineering and advanced technology solutions This year we are proud to host the 4th International Conference of Advanced Technology and Multidiscipline ICATAM This virtual scientific platform aims to unite academia researchers engineers government bodies non governmental organizations private sectors industries and consultants from around the world Our goal is to foster connections collaboration and discourse within a safe and physically distanced framework

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IEEE/ASME International Conference on Advanced Intelligent Mechatronics Proceedings, 2001

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reconstruction open and closed loop system characteristics steady state accuracy for different system types and input functions stability analysis in z domain Jury's test bilinear transformation from z to w domain stability analysis in w domain Routh Hurwitz criterion root locus techniques in z domain frequency domain analysis in w domain control system specifications in time and frequency domains design of controllers PI PD PID phase lag phase lead phase lag lead using time and frequency domain specifications state space methods controllability and observability pole placement controllers design of observers estimators full order prediction reduced order and current observers system identification optimal control linear quadratic regulator LQR linear quadratic Gaussian LQG estimator Kalman filter implementation of controllers and laboratory experiments for validation of analysis and design techniques on real laboratory scale hardware modules Both single input single output SISO and multi input multi output MIMO systems are covered Software platform of Matlab Simulink is used for analysis design and simulation and hardware software platforms of National Instruments NI LabVIEW are used for implementation and validation of analysis and design of digital control systems Demonstrating the use of an integrated approach to cover interdisciplinary topics of digital control emphasizing theoretical background validation through analysis simulation and implementation in physical laboratory experiments the book is ideal for students of engineering and applied science across in a range of concentrations

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